

### General Description

The MAX1480A/MAX1480B/MAX1490A/MAX1490B are complete, electrically isolated, RS-485/RS-422 data-communications interface solutions. Transceivers, opto-couplers, and a transformer provide a complete interface in a standard DIP package. A single +5V supply on the logic side powers both sides of the interface.

The MAX1480B/MAX1490B feature reduced-slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free data transmission at data rates up to 250kbps. The MAX1480A/MAX1490A driver slew rate is not limited, allowing transmission rates up to 2.5Mbps. The MAX1480A/B are designed for half-duplex communication, while the MAX1490A/B feature full-duplex communication.

Drivers are short-circuit current limited and protected against excessive power dissipation by thermal shutdown circuitry that places the driver outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a known output (RO low for the MAX1480A/B, RO high for the MAX1490A/B) if the input is open circuit.

The MAX1480A/MAX1480B/MAX1490A/MAX1490B typically withstand  $1600V_{RMS}$  (1 minute) or  $2000V_{RMS}$  (1 second). Their isolated outputs meet all RS-485/RS-422 specifications. The MAX1480A/B are available in a 28-pin DIP package, and the MAX1490A/B are available in a 24-pin DIP package.

### Selection Table

PART	HALF/FULL DUPLEX	DATA RATE (Mbps)	SLEW- RATE LIMITED	DRIVER ENABLE
MAX1480A	Half	2.5	No	Yes
MAX1480B	Half	0.25	Yes	Yes
MAX1490A	Full	2.5	No	No
MAX1490B	Full	0.25	Yes	No

### **Applications**

Isolated RS-485/RS-422 Data Interface Transceivers for EMI-Sensitive Applications Industrial-Control Local Area Networks Automatic Test Equipment HVAC/Building Control Networks

### **Features**

- Isolated Data Interface, Typically to 1600V<sub>RMS</sub> (1 minute)
- ♦ Slew-Rate Limited for Errorless Data Transmission (MAX1480B/MAX1490B)
- High-Speed, Isolated, 2.5Mbps RS-485/RS-422 Interface (MAX1480A/MAX1490A)
- ♦ Full-Duplex Data Communication (MAX1490A/B)
- → -7V to +12V Common-Mode Input Voltage Range with Respect to Isolated Ground
- ♦ Single +5V Supply
- Current Limiting and Thermal Shutdown for Driver Overload Protection
- Standard 0.6" DIP Package: 28-Pin DIP (MAX1480A/B) 24-Pin DIP (MAX1490A/B)

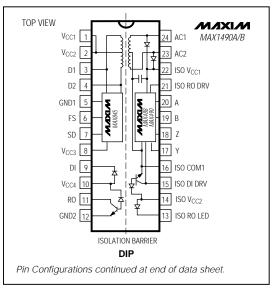
### Ordering Information

PART <sup>†</sup>	TEMP. RANGE	PIN-PACKAGE
MAX1480ACPI	0°C to +70°C	28 Wide Plastic DIP
MAX1480AEPI	-40°C to +85°C	28 Wide Plastic DIP

#### Ordering Information continued at end of data sheet.

 $^\dagger$  Data rate for "A" parts is up to 2500kbps. Data rate for "B" parts is up to 250kbps.

### Pin Configurations



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### **ABSOLUTE MAXIMUM RATINGS**

With Respect to GND_
Supply Voltage (V <sub>CC</sub> )0.3V to +6V
Control Input Voltage (SD, FS)0.3V to (VCC_ + 0.3V)
Receiver Output Voltage (RO, RO)0.3V to (V <sub>CC</sub> + 0.3V)
Output Switch Voltage (D1, D2)+12V
With Respect to ISO COM_
Control Input Voltage (ISO DE_)0.3V to (ISO V <sub>CC</sub> + 0.3V)
Driver Input Voltage (ISO DI_)0.3V to (ISO V <sub>CC</sub> _ + 0.3V)
Receiver Output Voltage (ISO RO_)0.3V to (ISO VCC_ + 0.3V)
Driver Output Voltage (A, B, Y, Z)8V to +12.5V
Receiver Input Voltage (A, B)8V to +12.5V

LED Forward Current (DI, DE, ISO RO LED)50mA
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )
24-Pin Plastic DIP (derate 8.7mW°C above +70°C)696mW
28-Pin Plastic DIP (derate 9.09mW/°C above +70°C)727mW
Operating Temperature Ranges
MAX1480_CPI/MAX1490_CPI0°C to +70°C
MAX1480_EPI/MAX1490_EPI40°C to +85°C
Storage Temperature Range65°C to +160°C
Lead Temperature (soldering, 10sec)+300°C
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Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

### **ELECTRICAL CHARACTERISTICS**

 $(V_{CC_{-}} = 5V \pm 10\%, FS = 0V, T_{A} = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } V_{CC_{-}} = 5V \text{ and } T_{A} = +25^{\circ}C.)$  (Notes 1, 2)

PARAMETER	SYMBOL	CON	DITIONS		MIN	TYP	MAX	UNITS
Cupply Valtage	1/0	FS = 0V			4.5	5.0	5.5	V
Supply Voltage	Vs	FS = V <sub>CC</sub> or open			4.75	5.0	5.25	V
	Гоин	FS = 0V	MAX14	80A/B		200		- kHz
Switch Frequency	FSWL	F3 = UV	MAX14	90A/B		535		
Switch Frequency	Fswh	FS = Vcc or open	MAX14	80A/B		350		KHZ
	I SWH	13 = VCC_ or open	MAX14	90A/B		725		
		MAX1480A,		RL = ∞		55	90	
		DE' = Vcc_ or open		$R_L = 54\Omega$		120		
		MAX1480B,		RL = ∞		28	45	
Operating Supply Current	Icc	DE' = V <sub>CC</sub> or open		$R_L = 54\Omega$		86		mA
operating Supply Current	100	MAX1490A	R <sub>L</sub> = ∞		100	150	IIIA	
	IVIAX 1470A		$R_L = 54\Omega$		170			
		MAX1490B		RL = ∞		65	125	
		IVII/ (XT470B		$R_L = 54\Omega$		135		
Shutdown Supply Current (Note 3)	I <sub>SHDN</sub>	SD = V <sub>CC</sub> _				0.2		μΑ
Chutdown Input Throobold	Vsdh	High			2.4			V
Shutdown Input Threshold	Vsdl	Low					0.8	V
Shutdown Input Leakage Current						10		рА
50.1 . T	V <sub>FSH</sub>	High			2.4			.,
FS Input Threshold	VFSL	Low				0.8	V	
FS Input Pull-Up Current		FS low					50	μA
FS Input Leakage Current		FS high				10		pА
Input High Voltage	VIH	DE', DI'			Vcc -	0.4		V
Input Low Voltage	VIL	DE', DI'					0.4	V
Isolation Resistance	Riso	T <sub>A</sub> = +25°C, V <sub>ISO</sub> = 50	VDC		100	10,000		ΜΩ
Isolation Capacitance	CISO	$T_A = +25^{\circ}C$ , $V_{ISO} = 50$				10		pF

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### **ELECTRICAL CHARACTERISTICS (continued)**

 $(V_{CC} = 5V \pm 10\%, FS = 0V, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$  Typical values are at  $V_{CC} = 5V$  and  $T_A = +25^{\circ}C.$ ) (Notes 1, 2)

PARAMETER	SYMBOL	CONDITION	S	MIN	TYP	MAX	UNITS
Differential Driver Output (no load)	V <sub>OD1</sub>					8	V
Differential Driver Output	V <sub>OD2</sub>	$R = 50\Omega (RS-422)$		2			V
(with load)	VOD2	R = 27Ω (RS-485), Figure 4		1.5		5	V
Change in Magnitude of Driver Output Voltage for	ΔVορ	$R = 27\Omega$ or $50\Omega$ , Figure 4	Differential			0.3	V
Complementary Output States	7.00	1 - 2732 01 3032, 1 iguie 4	Common Mode			0.3	v
Driver Common-Mode Output	V <sub>OC</sub>	$R = 27\Omega$ or $50\Omega$ , Figure 4				4	V
Input Current (A, B)	ISO I <sub>IN</sub>	DE' = 0V, V <sub>CC</sub> = 0V or 5.5V	V <sub>IN</sub> = 12V			1.0	mA
input current (A, B)	130 1111	DL = 00, 000_ = 00 01 5.50	VIN = -7V			0.8	IIIA
Receiver Input Resistance	RIN	-7V ≤ V <sub>CM</sub> ≤ 12V		12			kΩ
Receiver Differential Threshold	VTH	-7V ≤ V <sub>CM</sub> ≤ 12V		-0.2		0.2	V
Receiver Input Hysteresis	$\Delta V_{TH}$	V <sub>CM</sub> = 0V			70		mV
Receiver Output/Receiver Output Low Voltage	VoL	Using resistor values listed in 1	ables 1 and 2			0.4	V
Receiver Output/Receiver Output High Current	ГОН	V <sub>OUT</sub> = 5.5V				250	μΑ
Driver Short-Circuit Current	ISO Iosd	-7V ≤ V <sub>O</sub> ≤ 12V (Note 4)			100		mA

### SWITCHING CHARACTERISTICS—MAX1480A/MAX1490A

 $(V_{CC\_} = 5V \pm 10\%, FS = 0V, T_A = T_{MIN} \ to \ T_{MAX}, \ unless \ otherwise \ noted. \ Typical \ values \ are \ at \ V_{CC\_} = 5V \ and \ T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Input to Output	tplH	Figures 5 and 7, $R_{DIFF} = 54\Omega$ ,		100	275	ns
Propagation Delay	t <sub>PHL</sub>	$C_{L1} = C_{L2} = 100pF$		100	275	115
Driver Output Skew	tskew	Figures 5 and 7, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		25	90	ns
Driver Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	Figures 5 and 7, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		15	40	ns
Driver Enable to Output High (MAX1480A only)	tzн	Figures 6 and 8, C <sub>L</sub> = 100pF, S2 closed		0.5	1.5	μs
Driver Enable to Output Low (MAX1480A only)	t <sub>ZL</sub>	Figures 6 and 8, C <sub>L</sub> = 100pF, S1 closed		0.5	1.5	μs
Driver Disable Time from Low (MAX1480A only)	tLZ	Figures 6 and 8, C <sub>L</sub> = 15pF, S1 closed		0.5	1.5	μs
Driver Disable Time from High (MAX1480A only)	tHZ	Figures 6 and 8, C <sub>L</sub> = 15pF, S2 closed		0.5	1.5	μs
Receiver Input to Output	tplh	Figures 5 and 10, R <sub>DIFF</sub> = 54Ω, C <sub>L1</sub> = C <sub>L2</sub> = 100pF		100	225	ns
Propagation Delay	tphl	1 rigures 3 and 10, RDJFF = 3452, CET = CE2 = 100pt		100	225	115
tplh - tphl  Differential Receiver Skew	t <sub>SKD</sub>	Figures 5 and 10, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		20		ns
Maximum Data Rate	fMAX	tplh, tphl < 50% of data period	2.5			Mbps
Time to Shutdown	tshdn			100		μs
Shutdown to Driver Output High	tzh(shdn)	Figures 6 and 9, C <sub>L</sub> = 100pF, S2 closed		3	10	μs
Shutdown to Driver Output Low	tzl(SHDN)	Figures 6 and 9, C <sub>L</sub> = 100pF, S1 closed		3	10	μs

### SWITCHING CHARACTERISTICS—MAX1480B/MAX1490B

 $(V_{CC\_} = 5V \pm 10\%, FS = 0V, T_A = T_{MIN} \ to \ T_{MAX}, \ unless \ otherwise \ noted. \ Typical \ values \ are \ at \ V_{CC\_} = 5V \ and \ T_A = +25^{\circ}C.)$ 

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Driver Input to Output	tplH	Figures 5 and 7, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		1.0	2.0	He
Propagation Delay	t <sub>PHL</sub>	Figures 5 and 7, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		1.0	2.0	μs
Driver Output Skew	tskew	Figures 5 and 7, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		100	800	ns
Driver Rise or Fall Time	t <sub>R</sub> , t <sub>F</sub>	Figures 5 and 7, $R_{DIFF} = 54\Omega$ , $C_{L1} = C_{L2} = 100pF$		1.0	2.0	μs
Driver Enable to Output High (MAX1480B only)	t <sub>ZH</sub>	Figures 6 and 8, C <sub>L</sub> = 100pF, S2 closed		35	100	μs
Driver Enable to Output Low (MAX1480B only)	tzL	Figures 6 and 8, C <sub>L</sub> = 100pF, S1 closed		35	100	μs
Driver Disable Time from Low (MAX1480B only)	tLZ	Figures 6 and 8, C <sub>L</sub> = 15pF, S1 closed		13	50	μs
Driver Disable Time from High (MAX1480B only)	tHZ	Figures 6 and 8, C <sub>L</sub> = 15pF, S2 closed		13	50	μs
Receiver Input to Output	tpLH	Figures 5 and 10, $R_{DIFF} = 54\Omega$ , $C_{1.1} = C_{1.2} = 100pF$		0.8	2.0	μs
Propagation Delay	tphL	1 igures 3 and 10, NDJFF = 3422, OE1 = OE2 = 100pi		0.8	2.0	μЗ
tplh - tphl  Differential Receiver Skew	tskD	Figures 5 and 10, $R_{DIFF}$ = $54\Omega$ , $C_{L1}$ = $C_{L2}$ = $100pF$		200		ns
Maximum Data Rate	f <sub>MAX</sub>	t <sub>PLH</sub> , t <sub>PHL</sub> < 50% of data period	0.25			Mbps
Time to Shutdown	tshdn			100		μs
Shutdown to Driver Output High	tzh(shdn)	Figures 6 and 9, C <sub>L</sub> = 100pF, S2 closed		35	100	μs
Shutdown to Driver Output Low	tzl(SHDN)	Figures 6 and 9, C <sub>L</sub> = 100pF, S1 closed		35	100	μs

- Note 1: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to logicside ground (GND\_), unless otherwise specified.
- Note 2: For DE and DI pin descriptions, see Detailed Block Diagram and Typical Application Circuit (Figure 1 for MAX1480A) MAX1480B, Figure 2 for MAX1490A/MAX1490B).
- Note 3: Shutdown supply current is the current at V<sub>CC1</sub> and V<sub>CC2</sub> when shutdown is enabled.

  Note 4: Applies to peak current (see *Typical Operating Characteristics*). Although the MAX1480A/B and MAX1490A/B provide electrical isolation between logic ground and signal paths, they do not provide isolation between external shields and the signal paths (see Isolated Common Connection section).

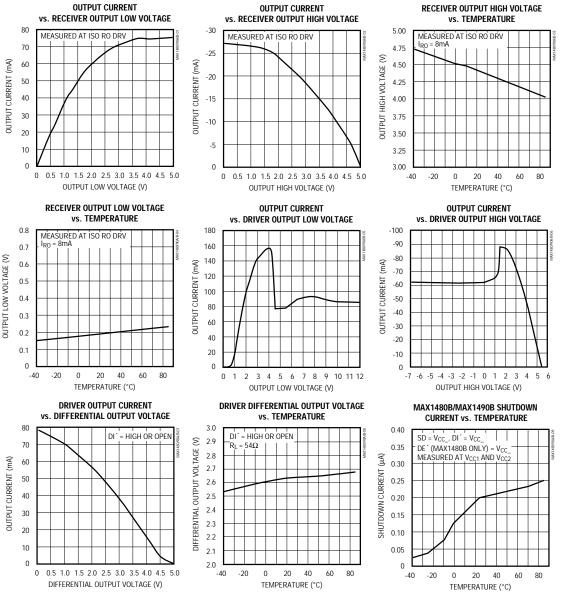
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## Complete, Isolated, RS-485/RS-422 Data Interface

### \_Typical Operating Characteristics

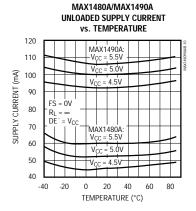
( $V_{CC}$  = 5V,  $T_A$  = +25°C, unless otherwise noted.)

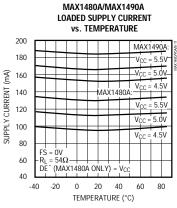
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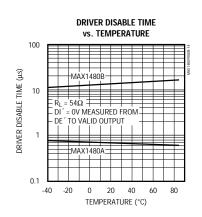


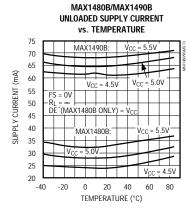
### \_Typical Operating Characteristics (continued)

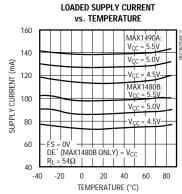
 $(V_{CC} = 5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 



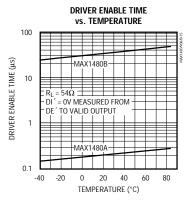








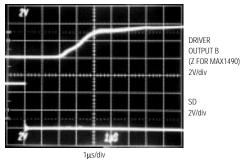
MAX1480B/MAX1490B



### Typical Operating Characteristics (continued)

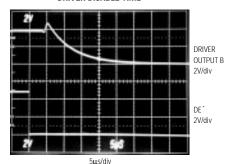
 $(V_{CC} = 5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 

### MAX1480A/MAX1490A POWER-UP DELAY TO DRIVER OUTPUTS VALID



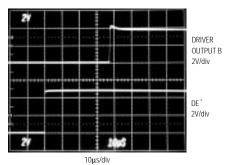
V<sub>CC</sub>\_ = 5.0V, DI '= 0V SD = 5V TO 0V AT 1kHz

### MAX1480B DRIVER DISABLE TIME



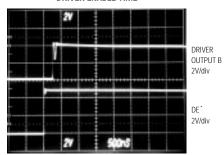
V<sub>CC</sub> = 5.0V, DI = 0V
DE TOGGLED 0V TO 5V AT 5kHz

#### MAX1480B Driver enable time



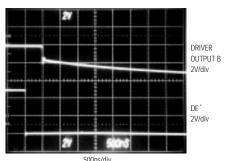
V<sub>CC</sub> = 5.0V, DI = 0V DE TOGGLED 0V TO 5V AT 5kHz

#### MAX1480A Driver enable time



V<sub>CC</sub> = 5.0V, DI´= 0V DE´TOGGLED 0V TO 5V AT 5kHz

#### MAX1480A DRIVER DISABLE TIME



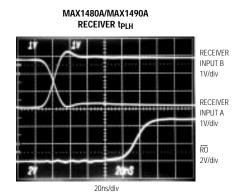
V<sub>CC</sub> = 5.0V, DI = 0V DE TOGGLED 0V TO 5V AT 5kHz

### \_Typical Operating Characteristics (continued)

 $(V_{CC} = 5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 

# MAX1480A/MAX1490A RECEIVER tpHL RECEIVER INPUT A 1V/div RECEIVER INPUT B 1V/div RO 2V/div

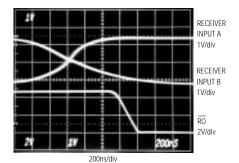
V<sub>CC</sub>\_ = 5.0V, DE´= V<sub>CC</sub>\_ DI´= 0V TO 5V AT 1.25MHz



V<sub>CC</sub>\_ = 5.0V, DE´= V<sub>CC</sub>\_ DI´ = 0V TO 5V AT 1.25MHz

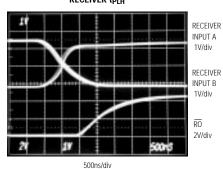
### MAX1480B/MAX1490B RECEIVER t<sub>PHL</sub>

20ns/div



V<sub>CC</sub>\_ = 5.0V, DE '= V<sub>CC</sub>\_ DI '= 0V TO 5V AT 125kHz

### MAX1480B/MAX1490B RECEIVER t<sub>PLH</sub>



V<sub>CC</sub>\_ = 5.0V, DE´= V<sub>CC</sub>\_ DI´= 0V TO 5V AT 125kHz

### Pin Descriptions

PIN					
MAX1480A/B	MAX1490A/B	NAME	FUNCTION		
PINS ON THE	NON-ISOLATED	SIDE			
1, 2, 8, 10	1, 2, 8, 10	VCC1-VCC4	Logic-Side (non-isolated side) +5V Supply Voltages		
3, 4	3, 4	D1, D2	Internal Connections. Leave these pins unconnected.		
5	5	GND1	Logic-Side Ground. Connect to GND2 (pin 12).		
6	6	FS	Frequency Switch Input. If $FS = V_{CC}$ or is open, switch frequency is high; if $FS = 0V$ , switch frequency is low.		
7	7	SD	Shutdown Input. Ground for normal operation. When high, the power oscillator is disabled.		
9	9	DI	Driver Input. With DE' high (MAX1480A/B only), a low on DI' forces output A low and output B high. Similarly, a high on DI' forces output A high and output B low. Drives internal LED cathode through a resistor (Table 1 of Figure 1 for MAX1480, Table 2 of Figure 2 for MAX1490).		
11	_	Driver-Enable Input. The driver outputs, A and B, are enabled by bringing E high. The driver outputs are high impedance when DE' is low. If the driver outputs are enabled, the device functions as a line driver. While the driver outputs are high impedance, the device functions as a line receiver. Drives internal LED cathode through a resistor (Table 1 of Figure 1).			
_	11	RO Receiver Output. If A > B by 200mV, RO will be high; if A < B by 200mV, and will be high; if A < B by 200mV, and will be high; if A < B by 200mV, and will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A < B by 200mV, RO will be high; if A <			
12	12	GND2	Logic-Side Ground. Connect to GND1 (pin 5).		
13	_	RO	Receiver Output. If $A > B$ by 200mV, $\overline{RO}$ will be low; if $A < B$ by 200mV, $\overline{RO}$ will be high. Open collector; must have pull-up to $V_{CC}$ (Table 1 of Figure 1).		
14	_	V <sub>CC5</sub>	Logic-Side (non-isolated side) +5V Supply Voltage		
PINS ON THE	ISOLATED RS-4	85/RS-422 SIDE			
15	13	ISO RO LED	Isolated Receiver Output LED. Internal LED anode in MAX1480 and LED cathode in MAX1490. Connect to ISO RO DRV through a resistor (Table 1 of Figure 1 for MAX1480; Table 2 of Figure 2 for MAX1490).		
16	_	ISO COM2	Isolated Common. Connect to ISO COM1 (pin 20).		
17	_	ISO DE DRV	Isolated Driver-Enable Drive. The driver outputs, A and B, are enabled by bringing DE high. The driver outputs are high impedance when DE is low. If the driver outputs are enabled, the device functions as a line driver. While the driver outputs are high impedance, the device functions as a line receiver. Open-collector output; must have pull-up to ISO VCC_ and be tied to ISO DE IN for normal operation (Table 1 of Figure 1).		
18	14	ISO V <sub>CC2</sub>	Isolated Supply Voltage. Connect to ISO V <sub>CC1</sub> (pin 26 for MAX1480, or pin 22 for MAX1490).		
19	15	ISO DI DRV	Isolated Driver-Input Drive. With DE' high (MAX1480 only), a low on DI' forces output A low and output B high. Similarly, a high on DI' forces output A high and output B low. Connect to ISO DI IN (on the MAX1480 only) for normal operation. Open-collector output; connect a pull-up resistor to ISO VCC_ (Table 1 of Figure 1 for MAX1480; Table 2 of Figure 2 for MAX1490).		
20	16	ISO COM1	Isolated Common. For MAX1480, connect to ISO COM2 (pin 16) (Figures 1 and 2).		

### Pin Descriptions (continued)

Р	PIN NAME NAME						
MAX1480A/B			FUNCTION				
PINS ON THE ISOLATED RS-485/RS-422 SIDE (continued)							
_	17	Υ	Noninverting Driver Output				
_	18	Z	Inverting Driver Output				
_	19	В	Inverting Receiver Input				
_	20	А	Noninverting Receiver Input				
21	_	ISO DE IN	Isolated Driver-Enable Input. Connect to ISO DI DRV for normal operation.				
22	_	ISO DI IN	Isolated Driver Input. Connect to ISO DI DRV for normal operation.				
23	_	А	Noninverting Driver Output and Noninverting Receiver Input				
24	21	ISO RO DRV	Isolated Receiver-Output Drive. Connect to ISO RO LED through a resistor (Table 1 of Figure 1 for MAX1480, Table 2 of Figure 2 for MAX1490).				
25	_	В	Inverting Driver Output and Inverting Receiver Input				
26	22	ISO V <sub>CC1</sub>	Isolated Supply Voltage Source				
27, 28	23, 24	AC2, AC1	Internal Connections. Leave these pins unconnected.				

Note: For DE' and DI' pin descriptions, see *Detailed Block Diagram and Typical Application Circuit* (Figure 1 for MAX1480A/B, Figure 2 for MAX1490A/B).

### Detailed Description

The MAX1480A/MAX1480B/MAX1490A/MAX1490B are complete, electrically isolated, RS-485/RS-422 datacommunications interface solutions. Transceivers, optocouplers, a power driver, and a transformer in one standard 28-pin DIP package (24-pin for the MAX1490A/B) provide a complete interface. Signals and power are internally transported across the isolation barrier (Figures 1, 2). Power is transferred from the logic side (non-isolated side) to the isolated side of the barrier through a center-tapped transformer. Signals cross the barrier through high-speed optocouplers. A single +5V supply on the logic side powers both sides of the interface. The MAX1480A/B offer half-duplex communications while the MAX1490A/B feature fullduplex communication. The functional input/output relationships are shown in Tables 3-6.

The MAX1480B/MAX1490B feature reduced-slew-rate drivers that minimize EMI and reduce reflections caused by improperly terminated cables, allowing error-free transmission at data rates up to 250kbps. The MAX1480A/MAX1490A driver slew rate is not limited, allowing transmission rates up to 2.5Mbps.

The MAX1480B/MAX1490B shutdown feature reduces supply current to as low as 0.2µA by using the SD pin (see *Low-Power Shutdown Mode* section).

Use the FS pin to select between high and low switching frequencies for the isolated power driver. The driver switches at the lower frequency (200kHz for the MAX1480A/B, 535kHz for the MAX1490A/B) when FS is low, and at the higher frequency (350kHz for the MAX1480A/B, 725kHz for the MAX1490A/B) when FS is high. At the lower switching frequency, the devices' operating voltage ranges increase from 5V  $\pm 5\%$  to 5V  $\pm 10\%$ .

The FS pin has a weak internal pull-up that switches the device to the high-frequency mode when FS is left unconnected. With FS high or open, no-load supply current is reduced by approximately 4mA, and by up to 8mA when fully loaded.

Drivers are short-circuit current limited and are protected against excessive power dissipation by thermal shutdown circuitry that puts the driver outputs into a high-impedance state. The receiver input has a fail-safe feature that guarantees a logic-high RO (logic-low  $\overline{\text{RO}}$ ) output if the input is open circuit.

On the MAX1480A/B, the driver outputs are enabled by bringing DE high. Driver-enable times are typically 0.5µs for the MAX1480A and 35µs for the MAX1480B. Allow time for the devices to be enabled before sending data (see the Driver Enable Time vs. Temperature graph in the *Typical Operating Characteristics*). When enabled, driver outputs function as line drivers. Driver outputs are high impedance when DE is low. While outputs are high impedance, they function as line receivers.

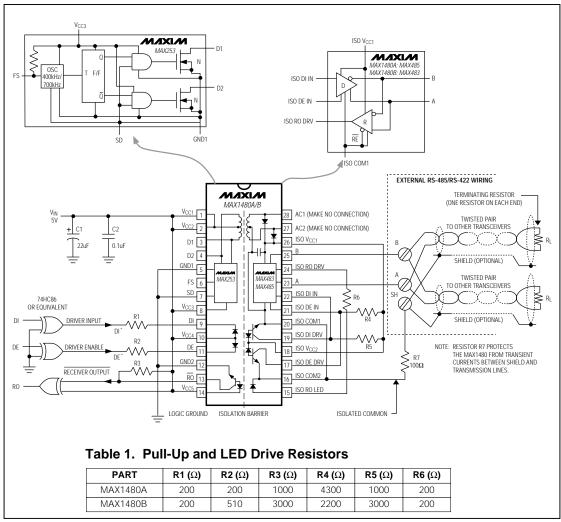


Figure 1. MAX1480A/MAX1480B Detailed Block Diagram and Typical Application Circuit

The MAX1480A/MAX1480B/MAX1490A/MAX1490B typically withstand 1600V<sub>RMS</sub> (1 minute) or 2000V<sub>RMS</sub> (1 second). The logic inputs can be driven from TTL/CMOS-logic with a series resistor, and the received data output can directly drive TTL or CMOS-logic families with only resistive pull-up.

### Low-Power Shutdown Mode

The SD pin shuts down the oscillator on the internal power driver. With the primary side in shutdown, no power is transferred across the isolation barrier. The DI and DE optocouplers, however, still consume current if the drive signals on the non-isolated side are low. Therefore, leave DI´ and DE´ high or floating when in shutdown mode.

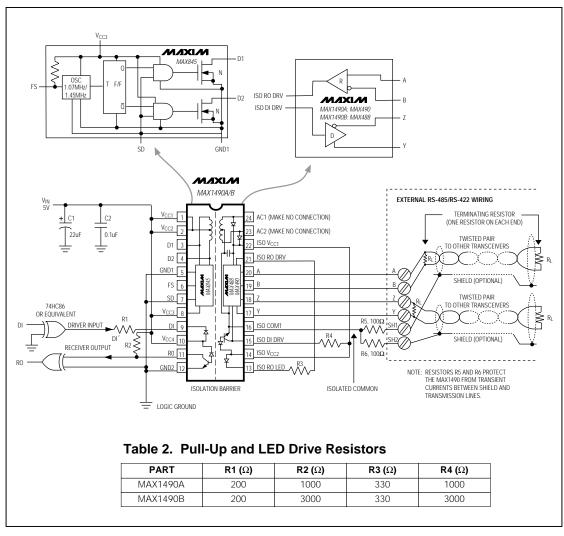


Figure 2. MAX1490A/MAX1490B Detailed Block Diagram and Typical Application Circuit

Under these conditions, the MAX1480B/MAX1490B supply current is reduced to as low as 0.2µA.

The high-speed optocouplers on the MAX1480A/ MAX1490A consume an additional 10mA through V<sub>CC5</sub> (V<sub>CC4</sub> for the MAX1490A). Therefore, to completely shut down these devices, use an external P-channel MOSFET as shown in Figure 3. In normal operation, SD is low, turning

the MOSFET on and thereby providing power to all the  $V_{CC}$  pins. When SD is pulled high, the power oscillator is disabled and the switch is turned off, disconnecting power from the DI and DE optocouplers. In normal operating mode, the switch carries only the optocoupler currents, so an on-resistance of several ohms will not significantly degrade efficiency.

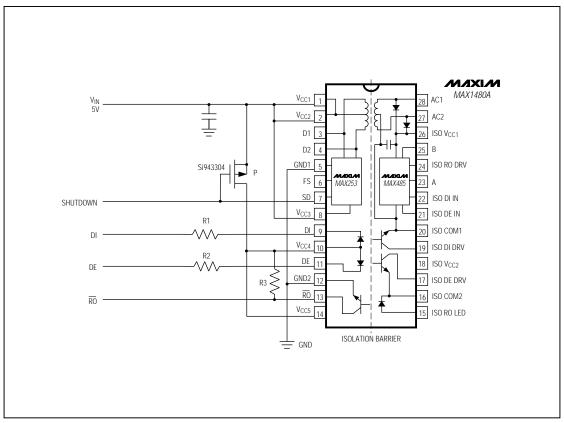


Figure 3. MAX1480A Low-Power Shutdown Mode

### Test Circuits

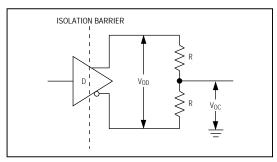


Figure 4. Driver DC Test Load

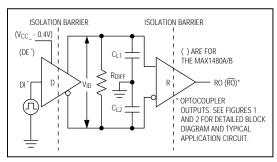


Figure 5. Driver/Receiver Timing Test Circuit

### Test Circuits (continued)

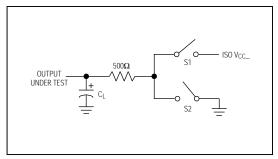


Figure 6. Driver Timing Test Load

### Switching Waveforms

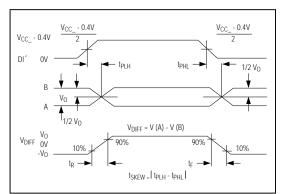


Figure 7. Driver Propagation Delays and Transition Times

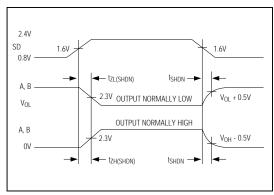


Figure 9. Times to/from Shutdown

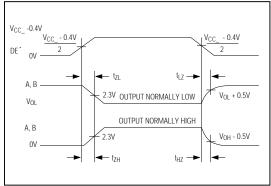


Figure 8. Driver Enable and Disable Times

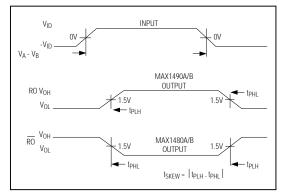


Figure 10. Receiver Propagation Delays

### MAX1480B/MAX1490B: Reduced EMI and Reflections

The MAX1480B/MAX1490B are slew-rate-limited, minimizing EMI and reducing reflections caused by improperly terminated cables. Figure 11 shows both the driver output waveform of a MAX1480A/MAX1490A transmitting a 150kHz signal and the Fourier analysis of that waveform. High-frequency harmonics with large amplitudes are evident. Figure 12 shows the same information for the slew-rate-limited MAX1480B/MAX1490B transmitting the same signal. The high-frequency harmonics have much lower amplitudes, and therefore the potential for EMI is significantly reduced.

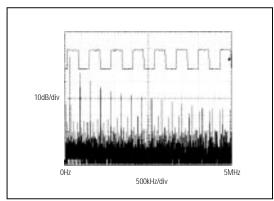


Figure 11. Driver Output Waveform and FFT Plot of MAX1480A/MAX1490A Transmitting a 150kHz Signal

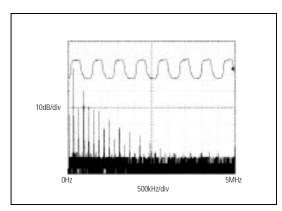


Figure 12. Driver Output Waveform and FFT Plot of MAX1480B/MAX1490B Transmitting a 150kHz Signal

### \_Function Tables

Half-Duplex Devices (MAX1480A/MAX1480B)

Table 3. Transmitting

INPL	JTS*	OUTPUTS			
DE ´	DI´	В	Α		
1	1	0	1		
1	0	1	0		
0	X	High-Z	High-Z		

X = Don't care

High-Z = High impedance

Table 4. Receiving

INPU	OUTPUT	
DE	V <sub>A</sub> - V <sub>B</sub>	(RO)
0	≥ +0.2V	0
0	≤ -0.2V	1
0	Open	0

### Full-Duplex Devices (MAX1490A/MAX1490B)

Table 5. Transmitting

INPUT	OUTI	PUTS
(DI´)*	Z	Y
1	0	1
0	1	0

### Table 6. Receiving

INPUT* (Va - VB)	OUTPUT (RO)
≥ +0.2V	1
≤ -0.2V	0
Open	1

<sup>\*</sup> For DE´ and DI´ pin descriptions, see *Detailed Block Diagram* and *Typical Application Circuit* (Figure 1 for MAX1480A/B, Figure 2 for MAX1490A/B).

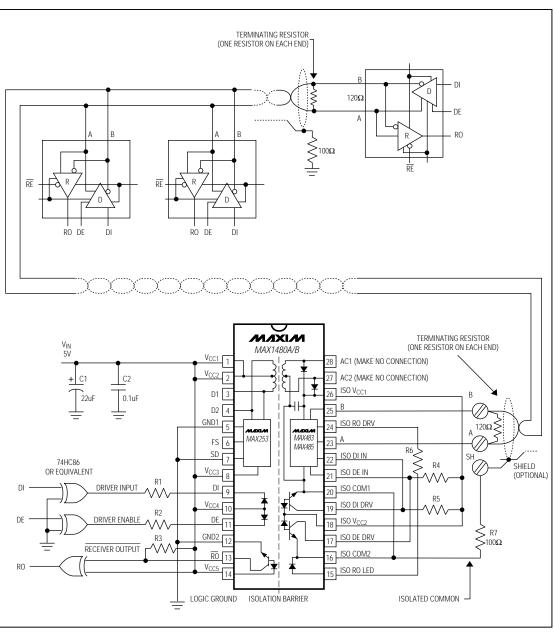


Figure 13. Typical Half-Duplex RS-485/RS-422 Network

### **Driver Output Protection**

There are two mechanisms to prevent excessive output current and power dissipation caused by faults or by bus contention. A foldback current limit on the output stage provides immediate protection against short circuits over the entire common-mode range (see *Typical Operating Characteristics*). In addition, a thermal shutdown circuit forces the driver outputs into a high-impedance state if the die temperature rises excessively.

### **Propagation Delay Skew**

Typical propagation delays are shown in the *Typical Operating Characteristics* using the test circuit of Figure 5. Propagation delay skew is simply the difference between the low-to-high and high-to-low propagation delay. Small driver/receiver skew times help reduce EMI and reflections by maintaining balanced differential signals.

The receiver skew time,  $|t_{PLH} - t_{PHL}|$ , is typically under 100ns for the MAX1480A/MAX1490A and under 1 $\mu$ s for the MAX1480B/MAX1490B.

The driver skew time is typically 25ns for the MAX1480A/MAX1490A and 100ns for the MAX1480B/MAX1490B.

### \_Applications Information

DI and DE are intended to be driven through a series current-limiting resistor. Directly grounding these pins destroys the device.

The MAX1480A/MAX1480B are designed for bidirectional data communications on multipoint bus-transmission lines. The MAX1490A/MAX1490B are designed for full-duplex bidirectional communications that are primarily point-to-point. Figures 13 and 14 show half-duplex and full-duplex typical network application circuits, respectively. To minimize reflections, terminate the line at both ends with its characteristic impedance, and keep stub lengths off the main line as short as possible. The slew-rate-limited MAX1480B/MAX1490B are more tolerant of imperfect termination and stubs off the main line.

### **Layout Considerations**

The MAX1480A/MAX1480B/MAX1490A/MAX1490B pinouts enable optimal PC board layout by minimizing interconnect lengths and crossovers.

 For maximum isolation, the "isolation barrier" should not be breached except by the MAX1480A/ MAX1480B/MAX1490A/MAX1490B. Connections

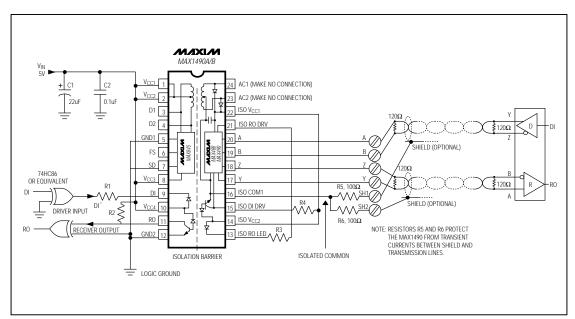


Figure 14. Typical Full-Duplex RS-485/RS-422 Network

and components from one side should not be located near those of the other side.

- A shield trace connected to the ground on each side
  of the barrier can help intercept capacitive currents
  that might otherwise couple into the signal path. In a
  double-sided or multilayer board, these shield traces
  should be present on all conductor layers.
- Try to maximize the width of the isolation barrier wherever possible; a clear space of at least 0.25 inches between ground and isolated common is suggested.

**Pull-Up and LED Drive Resistors** 

The MAX1480A/MAX1480B/MAX1490A/MAX1490B are specified and characterized using the resistor values shown in Table 1 of Figure 1 and Table 2 of Figure 2. Altering the recommended values can degrade performance.

The DI and DE (MAX1480A/B only) inputs are the cathodes of LEDs whose anodes are connected to the

supply. These points are best driven by a CMOS-logic gate with a series resistor to limit the current. The resistor values shown in Tables 1 and 2 are recommended when the 74HC86 gate or equivalent is used. These values may need to be adjusted if a driving gate with dissimilar series resistance is used.

All pull-up resistors are based on optocoupler specifications in order to optimize the devices' data-transfer rates.

### **Isolated Common Connection**

The isolated common may be completely floating with respect to the logic ground and the effective network ground. The receiver input resistors will cause the isolated common voltage to go to the mean voltage of the receiver inputs. If using shielded cable, tie the isolated common to the shield through a  $100\Omega$  resistor. In the case of the MAX1490, each shield should have its own  $100\Omega$  resistor (Figures 1, 2, 13, and 14).

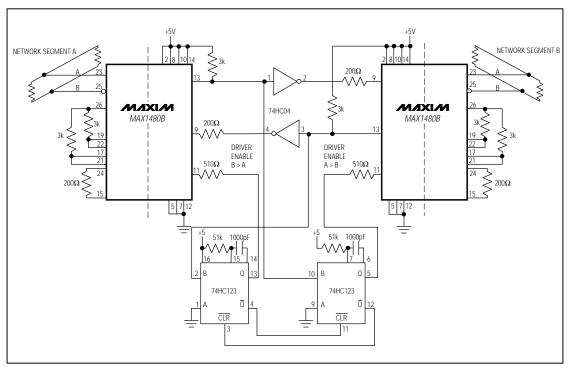


Figure 15. Doubly Isolated RS-485 Repeater

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### **Doubly Isolated RS-485 Repeater**

The RS-422/RS-485 standard is specified for cable lengths up to 4000 feet. When approaching or exceeding the specified maximum cable length, a ground-potential difference of several tens of volts can easily develop. This difference can be either DC, AC, at power-line frequency, or any imaginable noise or impulse waveform. It is typically very low impedance so that if a connection between the two grounds is attempted, very large currents may flow. These currents are by their nature unstable and unpredictable. In addition, they may cause noise to be injected into sensitive instrumentation and, in severe cases, might actually cause physical damage to such equipment.

Figure 15 shows a half-duplex (two-wire), bidirectional, party-line repeater system that prevents interference and/or damage from ground-potential differences. Two MAX1480A/MAX1480B isolated RS-485 transceivers are used to isolate each of the network segments from the electrical environment of the repeater. The MAX1480A/MAX1480B also regenerate bus signals that may have been degraded by line attenuation or dispersion

In the idle state, both transmitters are disabled, while all receivers in the system are enabled. If any device on the system has information for any other device, it starts sending its data onto the bus. Each data transmission on the bus retriggers the one-shot, keeping the sending transmitter enabled until there are no more transmissions. All receivers receive all data; if this is undesirable, the protocol must allow for an address field so receivers can ignore data not directed to them.

Each node must refrain from transmitting when data already exists on the bus, and must resend data that is corrupted by the collisions that inevitably occur with a party-line system. With the repeater of Figure 15, there might be transmitters up to 8000 feet apart. That represents more than 8µs (assuming 1ns/foot of delay) in which two nodes could be transmitting simultaneously.

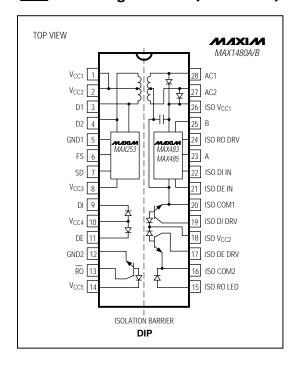
The circuit in Figure 15 can be used either directly as shown, with the slew-rate-limited MAX1480B, for data transfer rates up to 250kbps, or with the MAX1480A for data rates up to 2.5Mbps (see Table 1 for pull-up and LED resistor values when using the MAX1480A). If dual-port isolation is not needed, one of the MAX1480 devices can be replaced by a MAX485 for 2.5Mbps applications, or by a MAX483 for 250kbps applications.

### \_Ordering Information (continued)

PART <sup>†</sup>	TEMP. RANGE	PIN-PACKAGE
MAX1480BCPI	0°C to +70°C	28 Wide Plastic DIP
MAX1480BEPI	-40°C to +85°C	28 Wide Plastic DIP
MAX1490ACPG	0°C to +70°C	24 Wide Plastic DIP
MAX1490AEPG	-40°C to +85°C	24 Wide Plastic DIP
MAX1490BCPG	0°C to +70°C	24 Wide Plastic DIP
MAX1490BEPG	-40°C to +85°C	24 Wide Plastic DIP

<sup>†</sup> Data rate for "A" parts is up to 2500kbps. Data rate for "B" parts is up to 250kbps.

### \_\_\_Pin Configurations (continued)



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