



LB11884 — Monolithic Digital IC Three-in-One Motor Driver for Portable VCR

Overview

LB11884 is a three-in-one motor driver for portable VCR.

Features

- Capstan motor drive unit
 - 3-phase, 120 degrees full conducting, direct PWM drive
 - Built in PWM oscillator
 - Current limiter (It is fixed internally and setup externally.)
 - Forward/reverse rotation
 - 2 levels FG amplifier (Built-in gain resistor)
 - Control amplifier output pin
 - Built-in over-voltage protection function
- Drum motor drive unit
 - 3-phase, 120 degrees full conducting soft switching sensorless drive
 - FG sensorless function
 - 2 levels PG amplifier
 - FG and PG mixing output (Separated output is also possible.)
 - Over-voltage protection function
- Loading motor drive unit
 - H-bridge forward/reverse rotation
 - Motor voltage switch
 - Short brake
 - Input control for 3 values
 - Over-voltage protection function
- Common unit
 - Over-heat protection function (Thermal Shut Down)

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Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
IC source voltage	VREG max		6.5	V
Motor power source 1	C_VCC max		18.0	V
Motor power source 2	DL_VCC max		18.0	V
Applied input voltage	V11 max		-0.3 to VCC+0.3	V
Motor output current 1	ICOUT max		1.2	A
Motor output current 2	IDOUT max		0.8	A
Motor output current 3	ILOUT max		0.8	A
Allowable internal power dissipation	Pd max1	IC alone	0.6	W
	Pd max2	* Mounted on a specified board	1.8	W
Pin voltage range 1	VPIN max1	C_RSS, C_RSP, C_UOUT, C_VOUT, C_WOUT IVF = 1.2A	C_MGND-VF to C_VCC+VF	V
Pin voltage range 2	VPIN max2	D_RF, D_COM, D_UOUT, D_VOUT, D_WOUT IVF = 0.8A	DL_GND-VF to D_VCC+VF	V
Pin voltage range 3	VPIN max3	L_OUT1, L_OUT2 IVF = 0.8A	DL_GND-VF to L_VCC+VF	V
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

Note 1: If the current of maximum IC_VCC rate or more flows while the regenerative diode for capstan motor is recovering, the IC will not be damaged.

*: Mounted on a specified board (114.3mm×76.1mm×1.6mm, glass epoxy)

Allowable Operating Range at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Power source voltage 1	VREG		4 to 6	V
Power source voltage 2	C_VCC		8 to 16	V
Power source voltage e 3	DL_VCC		8 to 16	V
Electric potential difference between MGND and SGND	ΔGND	(MGND)-(SGND)	-0.3 to +0.4	V

Note: Turning ON/OFF for C_VCC and DL_VCC must be performed while the VREG is OFF.

Electrical Characteristics

Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Common Unit at Ta = 25°C, VCC = 5V, CVCO = DLVCO = 12V						
Power source current 1	I _{REG}	D_PGIN = C_FGIN = C_CNT = D_CNT = 0V		17	25	mA
Power source current 2	I _{C_VCC}	Same as above.		1	2	mA
Power source current 3	I _{DL_VCC}	Same as above.		2.6	4	mA
Power source current 4	I _{VCCQ}	VREG = 0V, I _{C_VCC} +I _{DL_VCC}			100	μA
Thermal shutdown temperature	TSD	*Design Target	140	160	180	°C
Thermal shutdown hysteresis	ΔTSD	*Design Target		15		°C
Capstan Motor Unit at Ta = 25°C, VREG = 5V, C_VCC = 12V						
Output saturation voltage	CVSAT	I _O = 1.0A, Source+Sink		2.4	3.5	V
Hall signal input level	VHALL		100			mVp-p
Hall in-phase input voltage	VCM		1.0		V _{CC} -1.7	V
C_ILM pin input voltage	VCILM		0		V _{CC}	V
C_ILM pin input current	ICILM	C_ILM = 3V, sink current		0.5	2.0	μA
C_ILM offset voltage	OCILM	VCRSP≥10mV	2.440	2.515	2.590	V
C_ILM gain	GCILM	C_CNT = 5V Calculation of OC_ILM+0.2V and OC_ILM +0.4V.	0.49	0.53	0.57	V/V
C_ILM pin short brake release voltage	BROFF1		1.1		1.4	V
Pin current at C_ILM pin short brake released	IBROFF1	Source current, C_ILM = 0V		0.1	0.3	μA

* It is a design target value and measurement is not carried out.

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Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
C_CNT input voltage	VCCNT		0		V _{CC}	V
C_CNT input current	ICCNT	C_CNT = 3V, sink current		0.5	2.0	μA
C_CNT offset voltage	OCCTL	VC_RFP ≥ 10mV	2.440	2.515	2.590	V
C_CNT gain	GCCNT	C_ILM = 5V Calculation of "OCCNT+0.2V" and "OCCNT+0.4V".	0.49	0.53	0.57	V/V
C_CNT pin short brake release voltage	BROFF2		1.1		1.4	V
Pin current at C_CNT pin short brake released	IBROFF2	Source current, C_CNT = 0V		0.1	0.3	μA
F/R forward voltage	VFW		1.5		V _{CC}	V
F/R reverse voltage	VRW		0		1	V
F/R input current	IFR	C_FR = 3V, sink current		100	200	μA
FG amplifier reference voltage	VFGR		2.40	2.50	2.60	V
Linear amplifier gain DC 36kHz	GDC		29.5	31.1	32.7	fold
	G36		20.0	25.0	30.0	fold
Hysteresis amplifier output low level voltage	VHO	I _{HO} = 4mA		0.2	0.4	V
Hysteresis of hysteresis amplifier	VHS	Both hysteresis	60	72	80	mV
Hysteresis amplifier output duty ratio	FGDT	360Hz F _{gin} = 40mVp-p	49	50	51	%
PWM carrier frequency	FOSC	CPWM = 680pF	18.5	21.7	25.0	kHz
Internal current limiter setup voltage	CILM	C_RF = 100Ω	0.70	0.75	0.80	V
Drum Motor Unit at Ta = 25°C, VREG = 5V, DL_VCC = 12V						
Output saturation voltage	DVSAT	I _O = 0.6A, Source+Sink		1.8	2.6	V
D_CNT input voltage	VDCNT		0		V _{CC}	V
D_CNT input current	IDCNT	D_CNT = 3V, sink current			0.5	μA
D_CNT offset voltage	ODCNT	VD_RF ≥ 10mV	2.40	2.50	2.60	V
D_CNT gain	GDCTL	D_RF = 0.5Ω, Calculation of ODCTL+0.2V and ODCTL+0.4V	0.40	0.50	0.60	V/V
PCOUT output current 1	IPCOU	Source current *Design target	20	45		μA
PCOUT output current 2	IPCOD	Sink current *Design target	20	45		μA
D_VCOIN input current	IVCOIN	D_VCOIN = 3V, sink current			1	μA
Minimum VCO frequency	FVCO min	D_CX = 0.022μF, D_VCOIN = Open	330	410	500	Hz
Maximum VCO frequency	FVCO max	D_CX = 0.022μF, D_VCOIN = 5V	15.0	18.0	21.0	kHz
D_C1, D_C2 source current ratio	RSOURCE	1-(IC1SOURCE/IC2SOURCE)	-12	0	12	%
D_C1, D_C2 sink current ratio	RSINK	1-(IC1SINK/IC2SINK)	-12	0	12	%
D_C1 source/sink current ratio	RC1	IC1SOURCE/IC1SINK	40	50	60	%
D_C2 source/sink current ratio	RC2	IC2SOURCE/IC2SINK	40	50	60	%
D_FG output high level voltage	VFH		4.7			V
D_FG output low level voltage	VFL	-0.5mA load			0.4	V
D_PG amplifier reference voltage	VPGR		2.8	3.0	3.2	V
D_PG amplifier input offset	OPG		-4		+4	mV
D_PG amplifier input bias	IPG	D_PG- = 2.5V, source current			0.25	μA
Linear amplifier gain	G1	Freq = 1kHz	50			dB
Hysteresis amplifier threshold level 1	VHYS1		70	100	130	mV
Hysteresis amplifier threshold level 2	VHYS2		140	200	260	mV
D_PG output high level voltage	VPH	0.5mA load	4.7			V
D_PG output low level voltage	VPL				0.2	V
FG/PG mix MID voltage	Vmid	D_PGO2 D_FGO short circuit	2.4	2.5	2.6	V
Internal current limiter setup voltage	DILM	D_RF = 100Ω	0.38	0.41	0.44	V

* It is a design target value and measurement is not carried out.

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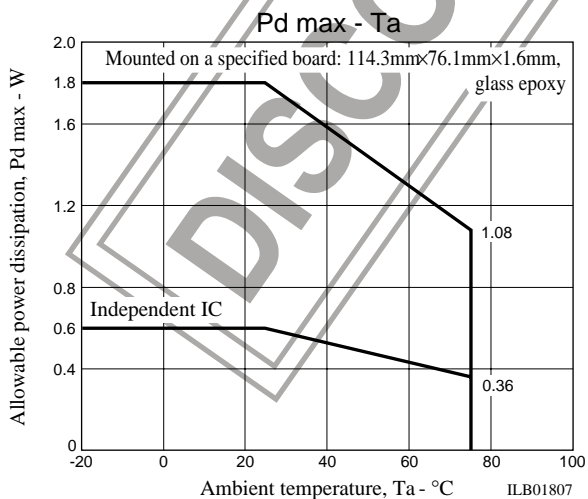
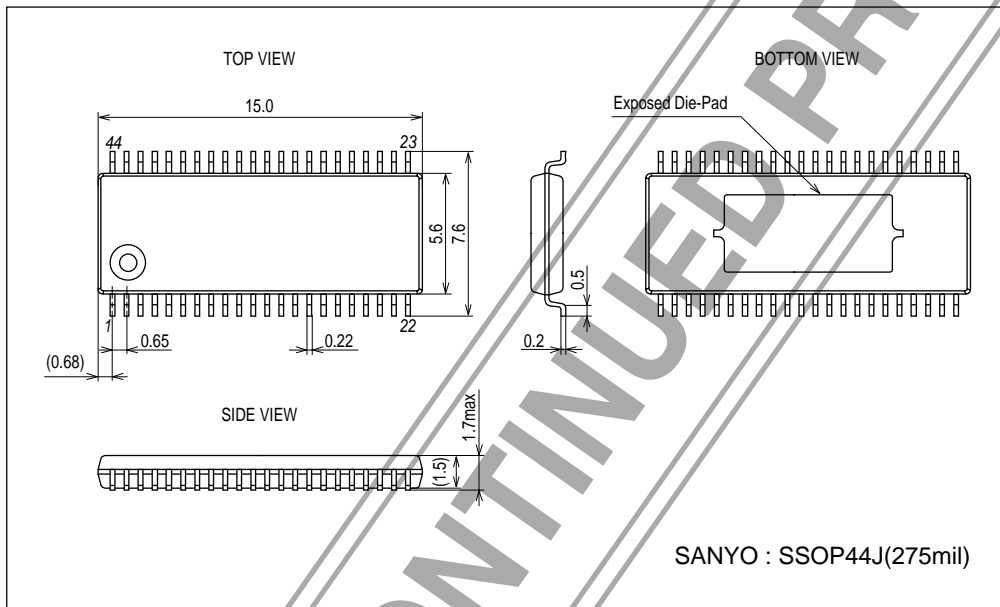
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Parameter	Symbol	Conditions	Ratings			Unit
			min	typ	max	
Loading Unit at Ta = 25°C, VREG = 5V, DL_VCC = 12V						
Input voltage	1 (HIGH)	V _{INH}	4		5	V
	2 (Middle)	V _{INM}	2		3	V
	3 (LOW)	V _{INL}	0		1	V
Input current	ILIN0	L_IN = 0V, source side		130	200	μA
	ILIN5	L_IN = 5V, sink side		130	200	μA
Saturation voltage	VSAT U-1	Between output and DL_VCC I _O = 0.6A, CW/CCW mode		1.9	2.4	V
	VSAT L-1	Between output and DL_GND I _O = 0.6A, CW/CCW mode		1.2	1.7	V
	VSAT UL	SINK+SOURCE I _O = 0.4A, CW/CCW mode		2.8	3.4	V
Output transistor leak current	Upper	ILU	VREG = 0V		50	μA
	Lower	ILL	VREG = 0V		50	μA

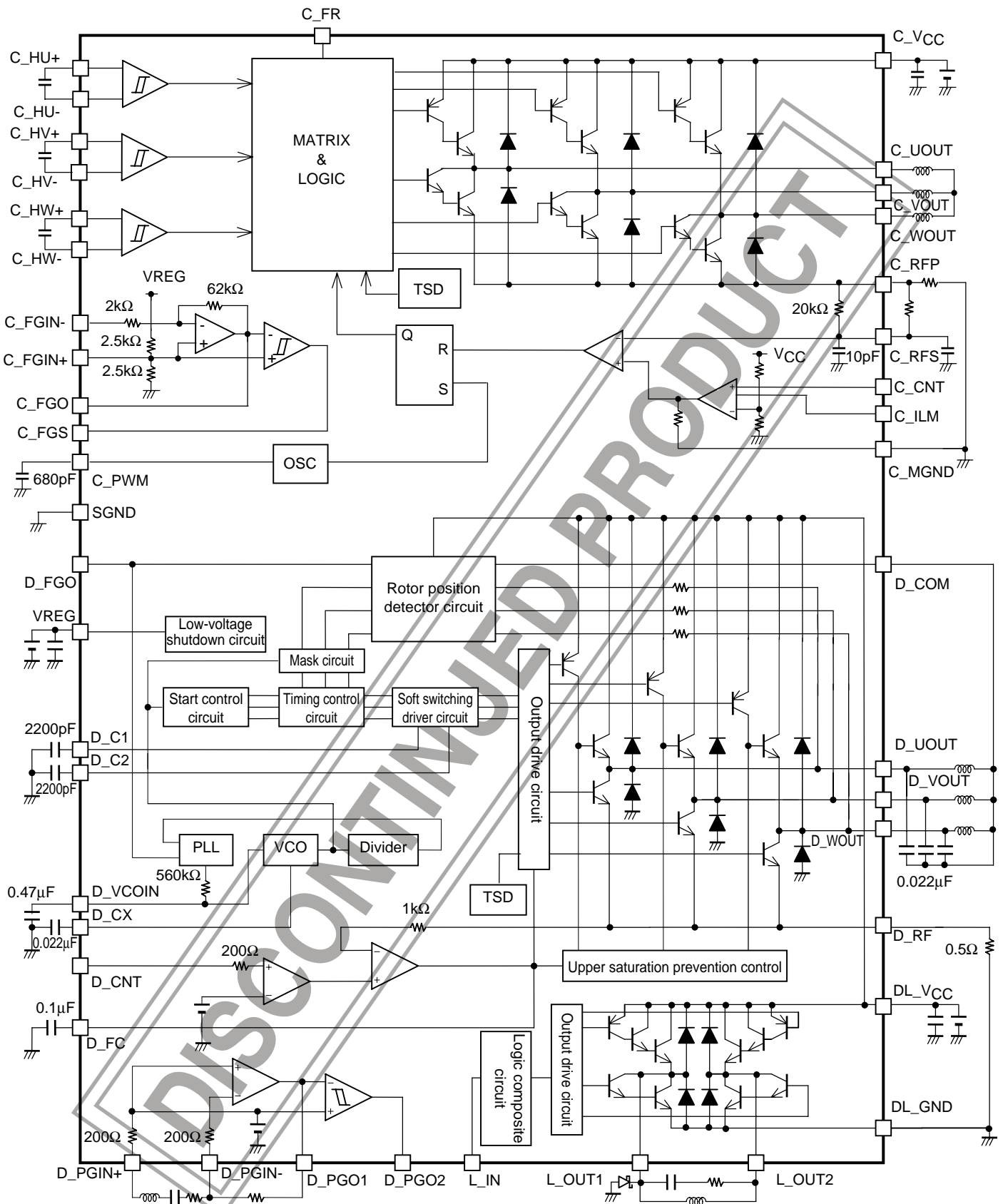
Package Dimensions

unit : mm (typ)

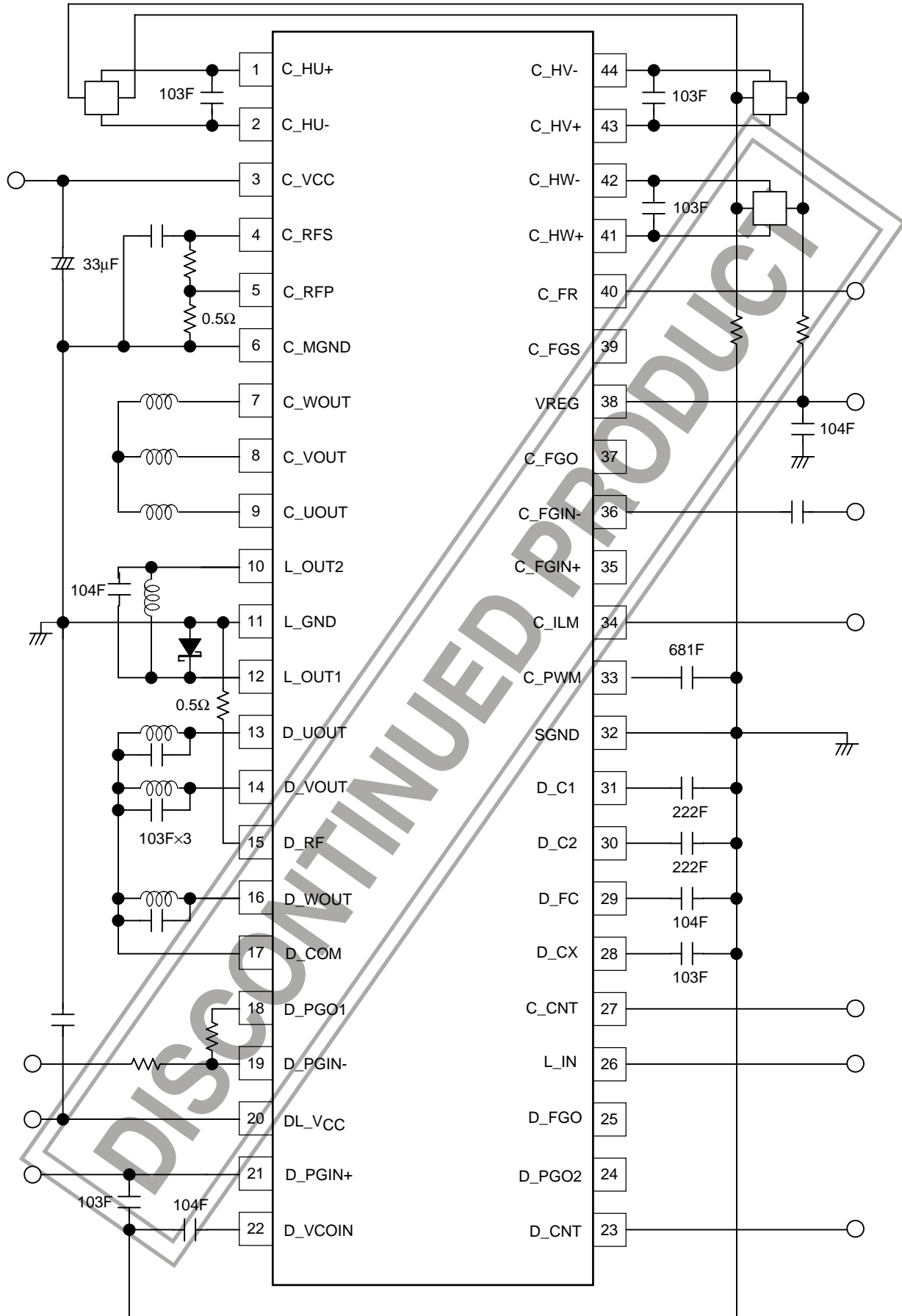
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Block Diagram

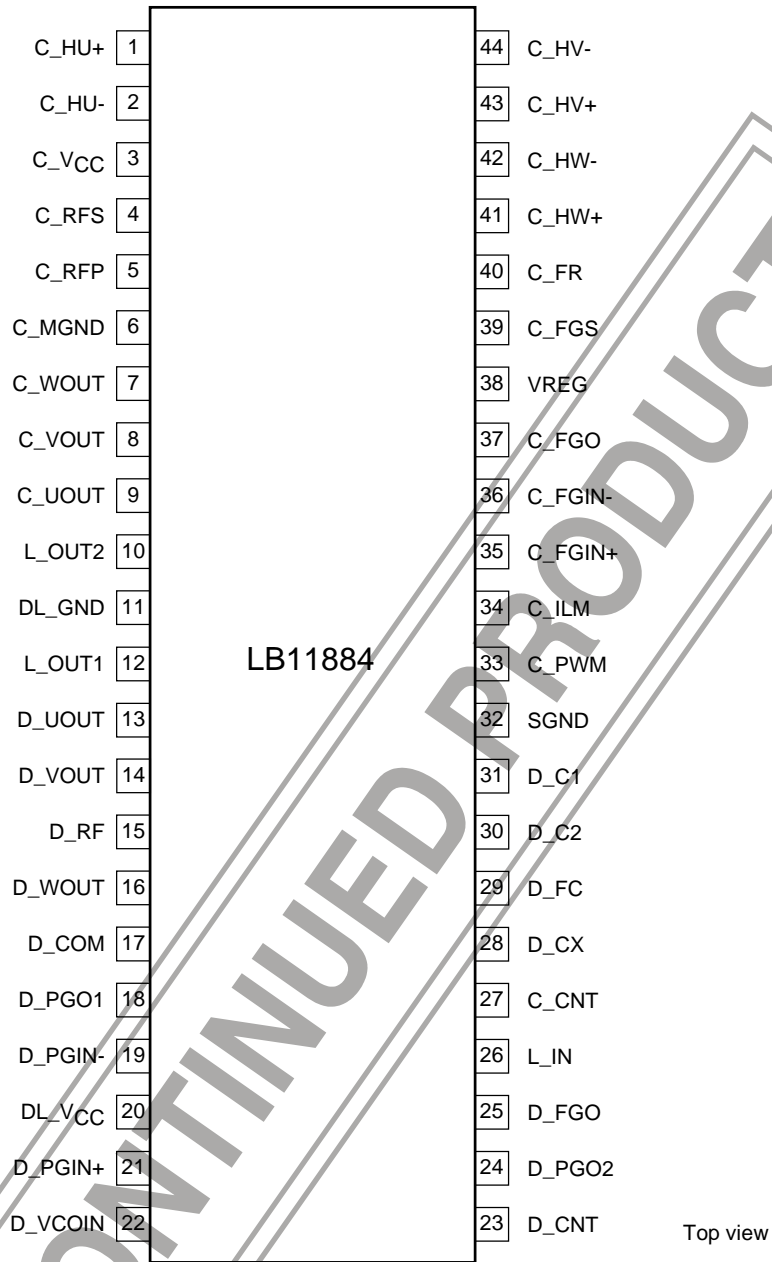


Sample Application Circuit



Note) The sample application circuit is for reference only and the optimum constant may differ depending on motor characteristics.

Pin Assignment



Pin Description

Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
3	C_VCC	8V to 16V	Power pin of capstan motor driver	
20	DL_VCC	8V to 16V	Power pin of drum and loading motor driver	
38	VREG	4V to 6V	Power pin to provide all voltages other than the output transistor and pre-drive.	
6	C_MGND		Capstan motor GND	
32	SGND		GND for all other than output	
1	C_HU+	1.0V to VCC-1.7	U-phase Hall element input pin. C_HU+>C_HU- state for logic H	
2	C_HU-			
43	C_HV+		V-phase Hall element input pin. C_HV+>C_HV- state for logic H	
44	C_HV-			
41	C_HW+		W-phase Hall element input pin. C_HW+>C_HW- state for logic H	
42	C_HW-			
36	C_FGIN-		Capstan FGAMP reverse input pin	
35	C_FGIN+	Capstan FGAMP non-inverted pin		
37	C_FGO	Capstan FGMP linear output pin Return resistor is incorporated with the amplification degree of about 31-fold.		
39	C_FGS		FG Schmidt amp output pin of capstan block	
40	C_FR	0V to VCC	Capstan forward/reverse control pin	

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
4	C_RFS		Capstan current detection filter pin. Connect the current detected at C_RFP to this pin after passing through the CR filter.	
33	C_PWM		Capacitor connection pin for PWM oscillation at capstan	
34	C_ILM	0V to V _{CC}	Capstan current limit setting pin	
27	C_CNT	0V to V _{CC}	Capstan speed control voltage application pin	
7	C_WOUT		Capstan W-phase output pin	
8	C_VOUT		Capstan V-phase output pin	
9	C_UOUT		Capstan U-phase output pin	
5	C_RFP		PWRTR GND and current return resistor connection pin	

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
29	D_FC		Drum frequency characteristics compensation pin. Insertion of a capacitor to GND stops oscillation of the closed loop of current control system.	
23	D_CNT	0V to V _{CC}	Drum speed control pin. Control is the constant current control to which current return is applied from D_RF.	
21	D_PGIN+	0.5V to V _{CC}	Drum PG amplifier non-inverted input pin. Biased internally to (3/5)×V _{REG} .	
19	D_PGIN-		Drum PG amplifier inverted input pin	

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
18	D_PGO1		Drum PG amplifier linear output pin	
24	D_PGO2		Drum PG Schmitt amplifier output pin	
25	D_FGO		Drum motor reverse counter-electromotive voltage detection output pin (three-phase synthesizing)	
22	D_VCOIN		VCO circuit voltage input pin of drum block. The PLL pin voltage is input via CR filter.	

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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
13	D_UOUT		Drum motor driver output pin	
14	D_VOUT			
16	D_WOUT			
15	D_RF		Minimum potential of drum motor driver output transistor. Constant-current control is made through detection of this voltage. The current limiter also functions by detecting this potential.	
17	D_COM		Motor coil neutral point input pin. The coil voltage waveform is detected with reference to this voltage.	
31	D_C1		Triangular wave generating capacitor connection pin of drum block. This triangular wave performs soft-switching of the coil output waveform.	
30	D_C2			
28	D_CX		In the VCO circuit, the operation frequency range and minimum operation frequency are determined by means of the capacitor value connected to this pin and GND.	

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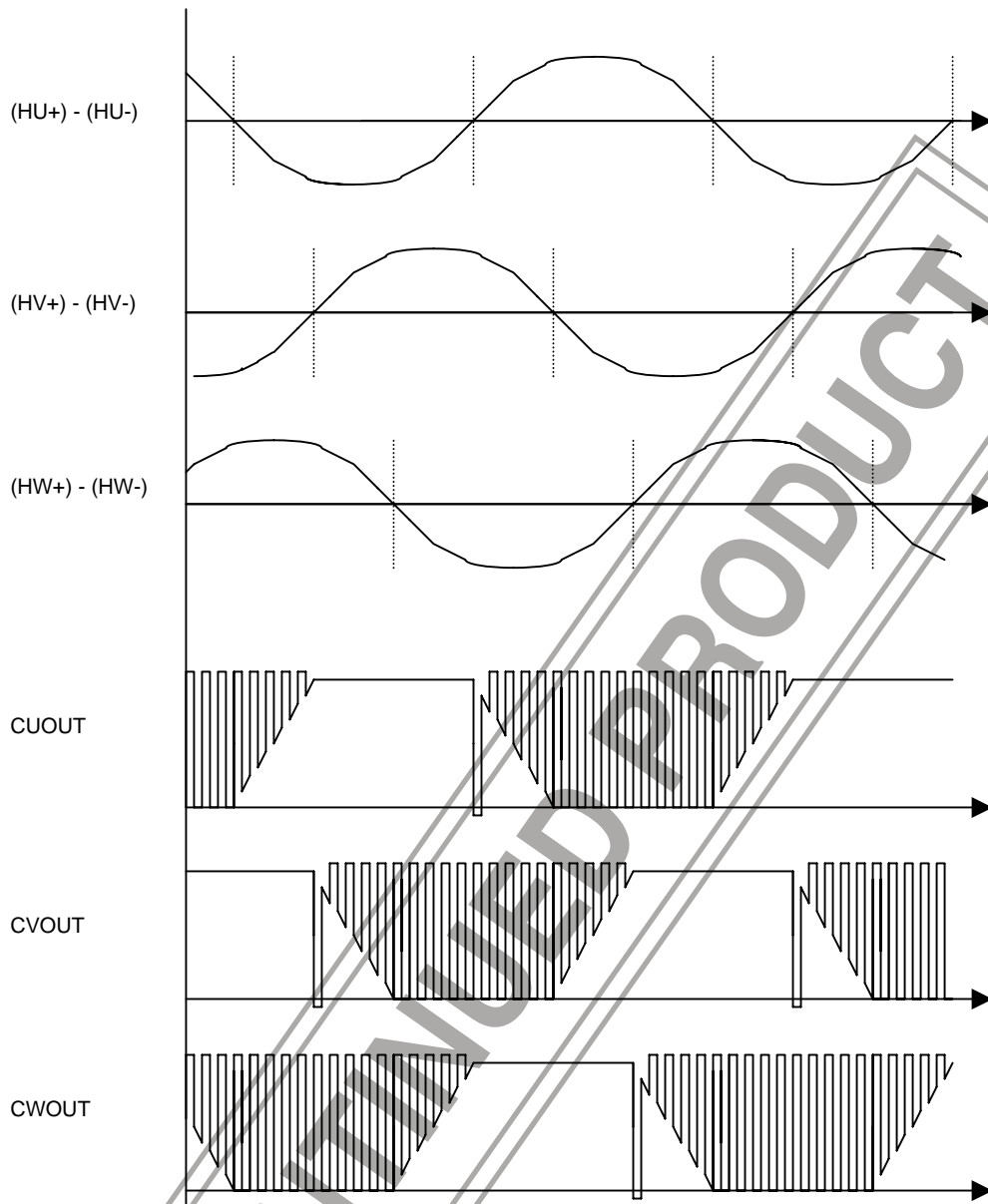
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Pin No	Symbol	Pin voltage	Pin Description	Equivalent Circuit
26	L_IN	0V to V _{CC}	Loading logic input pin	
12	L_OUT1		Loading motor driver output pin	
10	L_OUT2			
11	DL_GND			

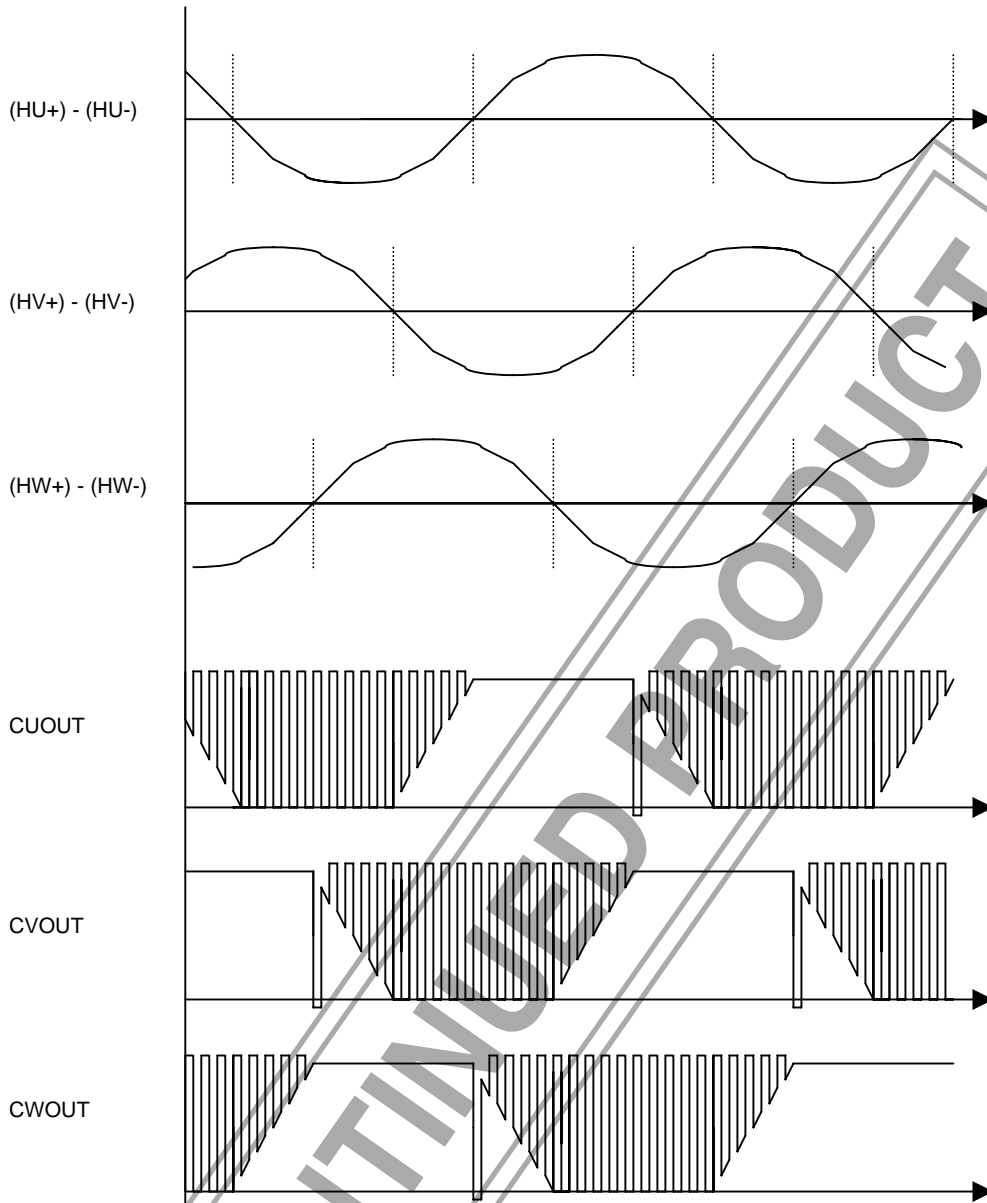
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Timing Chart and Truth Table

1. Capstan Motor Drive waveform (C_FR = L)



2. Capstan Motor Driver Drive waveform (C_FR = H)



3. Capstan Motor Driver Truth Table & Control Functions

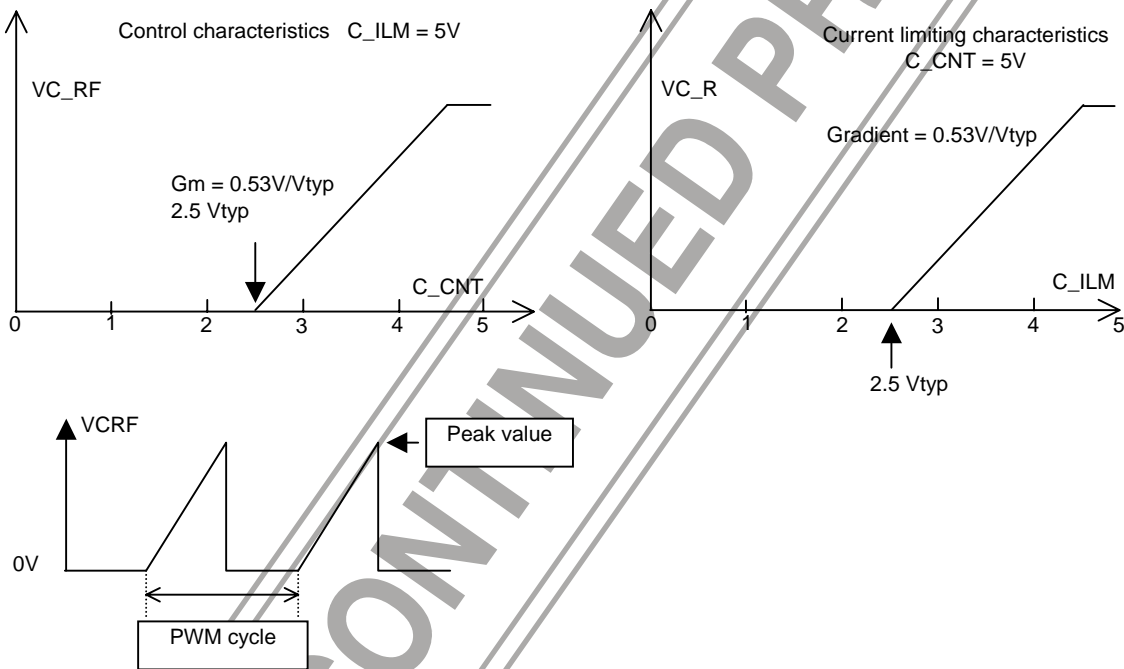
	Source→Sink	Hall input			C_FR
		U	V	W	
1	V → W	H	H	L	H
	W → V				L
2	U → W	H	L	L	H
	W → U				L
3	U → V	H	L	H	H
	V → U				L
4	W → V	L	L	H	H
	V → W				L
5	W → U	L	H	H	H
	U → W				L
6	V → U	L	H	L	H
	U → V				L

Note) H of FRC means the voltage of 1.5V or more while L means the voltage of 1.0V or less. (At V_{CC} = 5V)

Note) For the Hall input, the input H means the condition in which (+) relative to each phase input (-) is higher by 0.1V.

The input L means the condition in which (+) relative to (-) is lower by 0.1V or more.

Control function & control limiting function



Caution: For the V_{CRF} voltage of control characteristics, the peak value is to be measured.

Cautions for use)

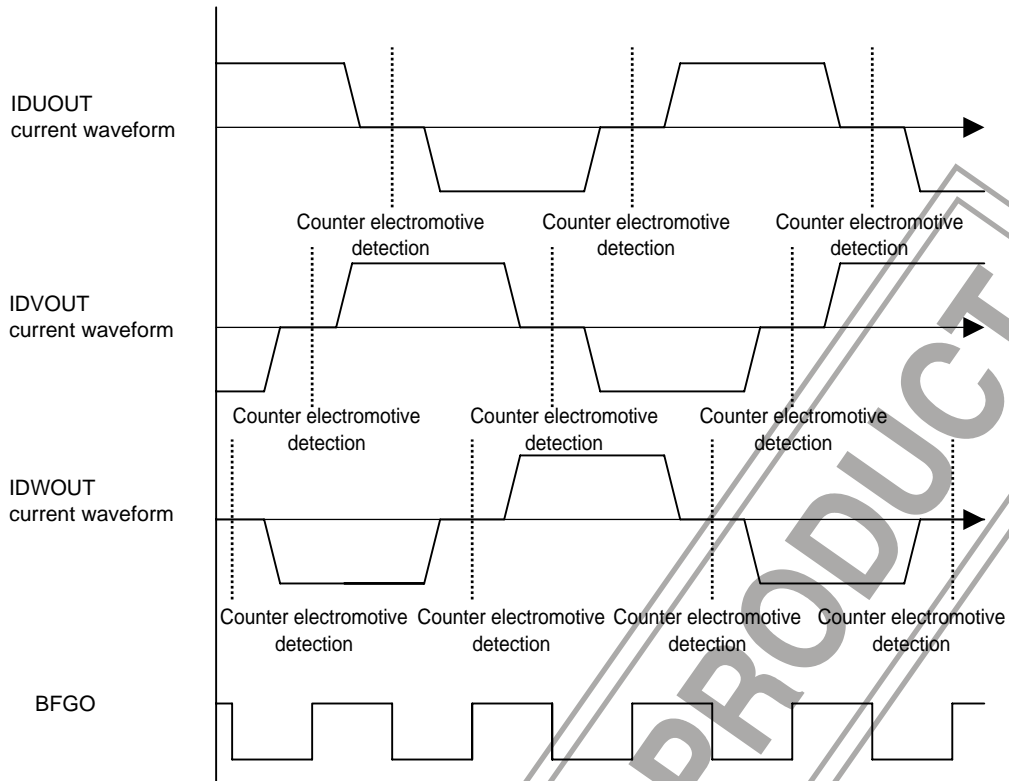
1. Capstan short-brake safety conditions

- C_{VCC} = 14V or less • 1500 rpm or less. Limiter 1.1 to 2.6V. 33μF or more between C_{VCC}-C_{MGND}

2. Capstan direct F/R safety conditions

- C_{VCC} = 16V or less • 2500 rpm or less. Limiter 2.6 to 3.0V. 33μF or more between C_{VCC}-C_{MGND}

4. Drum Motor Driver Drive current waveform



5. Loading Motor Truth table

Input	Output		Mode
	L_OUT1	L_OUT2	
L	L	H	Reverse
M (or OPEN)	L	L	Brake
H	H	L	Forward

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