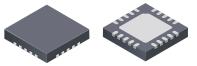


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# **Features and Benefits**

- •2-wire serial I<sup>2</sup>C<sup>TM</sup> -compatible interface: control (write) and status (read)
- •LNB voltages (6 programmable levels) compatible with all common standards
- Tracking switch-mode power converter for lowest dissipation
- Integrated converter switches and current sensing
- Provides up to 700 mA continuous load current
- •Output current limit of 800 mA minimum, with 48 ms timer
- •Static current limit circuit allows full current at startup and  $13 \rightarrow 18$  V output transition; reliably starts wide load range
- •Push-pull output stage minimizes  $13 \rightarrow 18$  V and  $18 \rightarrow 13$  V output transition times for highly capacitive loads
- •Adjustable rise/fall time via external timing capacitor
- ■Built-in tone oscillator, factory-trimmed to 22 kHz facilitates DiSEqC<sup>TM</sup> tone encoding, even at no-load
- Two methods of 22 kHz tone generation, including outgoing tone verification (TDET)
- •Auxiliary modulation input
- LNB overcurrent with timer
- •Diagnostics for output voltage level, input supply UVLO, and DiSEqC<sup>TM</sup> tone output
- **Package:** 20-contact 4 × 4 mm MLP/QFN (suffix ES)



# Description

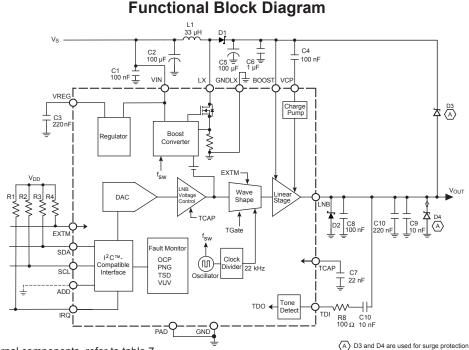
Intended for analog and digital satellite receivers, this single low noise block converter regulator (LNBR) is a monolithic linear and switching voltage regulator, specifically designed to provide the power and the interface signals to an LNB down converter via coaxial cable. The A8294 requires few external components, with the boost switch and compensation circuitry integrated inside of the device. A high switching frequency is chosen to minimize the size of the passive filtering components, further assisting in cost reduction. The high levels of component integration ensure extremely low noise and ripple figures.

The A8294 has been designed for high efficiency, utilizing the Allegro<sup>TM</sup> advanced BCD process. The integrated boost switch has been optimized to minimize both switching and static losses. To further enhance efficiency, the voltage drop across the tracking regulator has been minimized.

For DiSEqC<sup>TM</sup> communications, several schemes are available for generating tone signals, all the way down to no-load, and using either the internal clock or an external time source.

A comprehensive set of fault registers are provided, which comply with all the common standards, including: overcurrent, thermal shutdown, undervoltage, and power not good.

Continued on the next page ...



#### 8294-DS, Rev. 6

## **Description (continued)**

The device uses a 2-wire bidirectional serial interface, compatible with the  $I^2C^{TM}$  standard, that operates up to 400 kHz.

The A8294 is supplied in a lead (Pb) free MLP/QFN package, ES, 20-contact, 4 mm  $\times$  4 mm, 0.75 nominal overall height.

## **Selection Guide**

Part Number	Description	
A8294SESTR-T <sup>b</sup>	7 in. reel, 1500 pieces/reel 12 mm carrier tape	ES package, MLP/QFN surface mount 4 mm × 4 mm × 0.75 mm nominal height

<sup>a</sup> Contact Allegro for additional packing options.

<sup>b</sup> Leadframe plating 100% matte tin.

#### **Absolute Maximum Ratings**

Characteristic	Symbol	Conditions	Rating	Units
Load Supply Voltage, VIN pin	V <sub>IN</sub>		30	V
Output Current <sup>1</sup>	I <sub>OUT</sub>		Internally Limited	A
Output Voltage, BOOST pin			-0.3 to 33	V
Output Voltage, LNB pin		Surge <sup>2</sup>	-1 to 33	V
Output Voltage, LX pin			-0.3 to 30	V
Output Voltage, VCP pin	V <sub>CP</sub>		-0.3 to 41	V
Logic Input Voltage, EXTM pin			–0.3 to 5	V
Logic Input Voltage, other pins			–0.3 to 7	V
Logic Output Voltage			–0.3 to 7	V
Operating Ambient Temperature	T <sub>A</sub>		-20 to 85	°C
Junction Temperature	T <sub>J</sub> (max)		150	°C
Storage Temperature	T <sub>stg</sub>		–55 to 150	°C

<sup>1</sup>Output current rating may be limited by duty cycle, ambient temperature, and heat sinking. Under any set of conditions, do not exceed the specified current ratings, or a junction temperature, T<sub>J</sub>, of 150°C.

<sup>2</sup>Use Allegro recommended Application circuit.

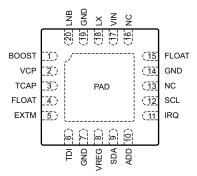
#### Thermal Characteristics may require derating at maximum conditions, see application information

Characteristic Symbol		Test Conditions*	Value	Unit
Package Thermal Resistance	$R_{\theta JA}$	On 4-layer PCB based on JEDEC standard	37	°C/W

\*Additional thermal information available on the Allegro website



### **Device Pin-out Diagram**



(Top View)

#### **Terminal List Table**

News	Number	Europhics
Name	ES	Function
ADD	10	Address select
FLOAT	4, 15	These pins must not be connected to anything; do not ground these pins
BOOST	1	Tracking supply voltage to linear regulator
EXTM	5	External modulation input
GND	7, 14	Signal ground
GNDLX	19	Boost switch ground
IRQ	11	Interrupt request
LNB	20	Output voltage to LNB
LX	18	Inductor drive point
NC	13, 16	No connection
PAD	Pad	Exposed pad; connect to the ground plane, for thermal dissipation
SCL	12	I <sup>2</sup> C <sup>™</sup> -compatible clock input
SDA	9	I <sup>2</sup> C <sup>™</sup> -compatible data input/output
TCAP	3	Capacitor for setting the rise and fall time of the LNB output
TDI	6	Outgoing Tone Detect Feedback (for verification)
VCP	2	Gate supply voltage
VIN	17	Supply input voltage
VREG	8	Analog supply



# ELECTRICAL CHARACTERISTICS at $T_A = 25^{\circ}$ C, $V_{IN} = 10$ to 16 V, unless noted otherwise<sup>1</sup>

LEED INIOAL ONANAOTENISTIOS at 1	- 20 0, VIN -	to to to v, unless noted otherwise				
Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Units
General						
Set-Point Accuracy, Load and Line Regulation <sup>2</sup>	Err	Relative to selected $V_{LNB}$ target level, I <sub>LOAD</sub> = 0 to 450 mA	-3.0	_	3.0	%
	I <sub>IN(Off)</sub>	ENB bit = 0, LNB output disabled, $V_{IN}$ = 12 V	-	-	10.0	mA
Supply Current	I <sub>IN(On)</sub>	ENB bit = 1, LNB output enabled, $I_{LOAD} = 0 \text{ mA}, V_{IN} = 12 \text{ V}$	-	-	19.0	mA
Boost Switch On Resistance	R <sub>DS(on)BOOST</sub>	I <sub>LOAD</sub> = 450 mA	-	300	-	mΩ
Switching Frequency	f <sub>SW</sub>		320	352	384	kHz
Switch Current Limit	ILIMSW	V <sub>OUT</sub> = 19.0 V	-	2.7	-	А
Linear Regulator Voltage Drop	$\Delta V_{REG}$	V <sub>BOOST</sub> – V <sub>LNB</sub> , no tone signal, I <sub>LOAD</sub> = 450 mA	_	800	-	mV
	I <sub>CHG</sub>	TCAP capacitor (C7) charging	-12.5	-10	-7.5	μA
TCAP Pin Current	I <sub>DISCHG</sub>	TCAP capacitor (C7) discharging	7.5	10	12.5	μA
Output Voltage Rise Time <sup>3</sup>	t <sub>r(VLNB)</sub>	For V <sub>LNB</sub> 13 $\rightarrow$ 18 V; C <sub>TCAP</sub> = 5.6 nF, I <sub>LOAD</sub> = 450 mA	_	500	-	μs
Output Voltage Pull-Down Time <sup>3</sup>	t <sub>f(VLNB)</sub>	For V <sub>LNB</sub> 18 $\rightarrow$ 13 V; C <sub>LOAD</sub> = 100 µF, I <sub>LOAD</sub> = 0 mA	-	12.5	_	ms
Output Reverse Current	I <sub>RLNB</sub>	ENB bit = 0, V <sub>LNB</sub> = 33 V , BOOST capacitor (C5) fully charged	_	1	5	mA
Ripple and Noise on LNB Output <sup>4</sup>	V <sub>rip,n(pp)</sub>	20 MHz BWL; reference circuit shown in Functional Block diagram; contact Allegro for additional information on application circuit board design	Η	30	-	mV <sub>PP</sub>
Protection Circuitry				-		
Output Overcurrent Limit <sup>5</sup>	I <sub>LIMLNB</sub>	$V_{BOOST} - V_{LNB} = 800 \text{ mV}$	800	850	950	mA
Overcurrent Disable Time	t <sub>DIS</sub>		-	48	-	ms
VIN Undervoltage Lockout Threshold	V <sub>UVLO</sub>	V <sub>IN</sub> falling	7.05	7.35	7.65	V
VIN Turn On Threshold	V <sub>IN(th)</sub>	V <sub>IN</sub> rising	7.40	7.70	8.00	V
Undervoltage Hysteresis	V <sub>UVLOHYS</sub>		_	350	-	mV
Thermal Shutdown Threshold <sup>3</sup>	TJ		_	165	-	°C
Thermal Shutdown Hysteresis <sup>3</sup>	$\Delta T_{J}$		_	20	-	°C
Power Not Good Flag Set	PNG <sub>SET</sub>	With respect to V <sub>LNB</sub>	77	85	93	%
Power Not Good Flag Reset	PNG <sub>RESET</sub>	With respect to V <sub>LNB</sub>	82	90	98	%
Power Not Good Hysteresis	PNG <sub>HYS</sub>	With respect to V <sub>LNB</sub>	-	5	-	%
Tone						
Tone Frequency	f <sub>TONE</sub>		20	22	24	kHz
Tone Amplitude, Peak-to-Peak	V <sub>TONE(pp)</sub>	$I_{LOAD}$ = 0 to 450 mA, $C_{LOAD}$ = 750 nF	400	620	900	mV
Tone Duty Cycle	DC <sub>TONE</sub>	I <sub>LOAD</sub> = 0 to 450 mA, C <sub>LOAD</sub> = 750 nF	40	50	60	%
Tone Rise Time	t <sub>rTONE</sub>	I <sub>LOAD</sub> = 0 to 450 mA, C <sub>LOAD</sub> = 750 nF	5	10	15	μs
Tone Fall Time	t <sub>fTONE</sub>	I <sub>LOAD</sub> = 0 to 450 mA, C <sub>LOAD</sub> = 750 nF	5	10	15	μs
Outgoing Tone Detection		· · · · · · · · · · · · · · · · · · ·				
Outgoing Tone Amplitude, Peak to Peak <sup>3</sup>	V <sub>TDT(pp)init</sub>	f <sub>TONE</sub> = 22 kHz sine wave, using internal tone	400	_	_	mV
Outgoing Tone Frequency Capture <sup>3</sup>	f <sub>TDI</sub>	600 mVpp sine wave	20	_	24	kHz

Continued on the next page ...



### ELECTRICAL CHARACTERISTICS (continued) at T<sub>A</sub> = 25°C, V<sub>IN</sub> = 10 to 16 V, unless noted otherwise<sup>1</sup>

Characteristics	Symbol	Test Conditions	Min.	Тур.	Max.	Units
I²C™-Compatible Interface	·			·	··	
Logic Input (SDA,SCL) Low Level	V <sub>SCL(L)</sub>		_	-	0.8	V
Logic Input (SDA,SCL) High Level	V <sub>SCL(H)</sub>		2.0	-	-	V
Logic Input Hysteresis	V <sub>I2CIHYS</sub>		_	150	-	mV
Logic Input Current	I <sub>I2CI</sub>	V <sub>12C1</sub> = 0 to 7 V	-10	<±1.0	10	μA
Logic Output Voltage SDA and IRQ	V <sub>t2COut(L)</sub>	I <sub>LOAD</sub> = 3 mA	_	-	0.4	V
Logic Output Leakage SDA and IRQ	V <sub>t2CLKG</sub>	$V_{t2COut} = 0 \text{ to } 7 \text{ V}$	_	-	10	μA
SCL Clock Frequency	f <sub>CLK</sub>		_	-	400	kHz
Output Fall Time	t <sub>fl2COut</sub>	V <sub>t2COut(H)</sub> to V <sub>t2COut(L)</sub>	_	-	250	ns
Bus Free Time Between Stop/Start	t <sub>BUF</sub>		1.3	-	-	μs
Hold Time Start Condition	t <sub>HD:STA</sub>		0.6	-	-	μs
Setup Time for Start Condition	t <sub>SU:STA</sub>		0.6	-	-	μs
SCL Low Time	t <sub>LOW</sub>		1.3	-	-	μs
SCL High Time	t <sub>HIGH</sub>		0.6	-	-	μs
Data Setup Time	t <sub>SU:DAT</sub>		100	-	-	ns
Data Hold Time	t <sub>HD:DAT</sub>	For $t_{HD:DAT}$ (min), the master device must provide a hold time of at least 300 ns for the SDA signal in order to bridge the undefined region of the SCL signal falling edge	0	_	900	ns
Setup Time for Stop Condition	t <sub>su:sto</sub>		0.6	-	-	μs
I²C™ Address Setting						
ADD Voltage for Address 0001,000	Address1		0	-	0.7	V
ADD Voltage for Address 0001,001	Address2		1.3	-	1.7	V
ADD Voltage for Address 0001,010	Address3		2.3	-	2.7	V
ADD Voltage for Address 0001,011	Address4		3.3	-	5.0	V

<sup>1</sup>Operation at 16 V may be limited by power loss in the linear regulator.

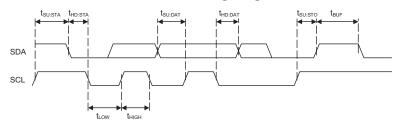
<sup>2</sup>For the selected V<sub>LNB</sub> target level 13.375 V, Err(min) = -3.7%.

<sup>3</sup>Guaranteed by worst case process simulations and system characterization.

<sup>4</sup>LNB output ripple and noise are dependent on component selection and PCB layout. Refer to the Application Schematic and PCB layout recommendations. Not production tested.

<sup>5</sup>Current from the LNB output may be limited by the choice of Boost components.

#### I<sup>2</sup>C<sup>™</sup> Interface Timing Diagram





# **Functional Description**

# Protection

The A8294 has a wide range of protection features and fault diagnostics which are detailed in the Status Register section.

# **Boost Converter/Linear Regulator**

The A8294 solution contains a tracking current-mode boost converter and linear regulator. The boost converter tracks the requested LNB voltage to within 800 mV, to minimize power dissipation. Under conditions where the input voltage,  $V_{BOOST}$ , is greater than the output voltage,  $V_{LNB}$ , the linear regulator must drop the differential voltage. When operating in these conditions, care must be taken to ensure that the safe operating temperature range of the A8294 is not exceeded.

The boost converter operates at 352 kHz typical: 16 times the internal 22 kHz tone frequency. All the loop compensation, current sensing, and slope compensation functions are provided internally.

The A8294 has internal pulse-by-pulse current limiting on the boost converter and DC current limiting on the LNB output to protect the IC against short circuits. When the LNB output is shorted, the LNB output current is limited to 700 mA typical, and the IC will be shut down if the overcurrent condition lasts for more than 48 ms. If this occurs, the A8294 must be reenabled for normal operation. The system should provide sufficient time between successive restarts to limit internal power dissipation; a minimum of 2 s is recommended.

At extremely light loads, the boost converter operates in a pulse-skipping mode. Pulse skipping occurs when the BOOST voltage rises to approximately 450 mV above the BOOST target output voltage. Pulse skipping stops when the BOOST voltage drops 200 mV below the pulse skipping level.

In the case that two or more set top box LNB outputs are connected together by the customer (e.g., with a splitter), it is possible that one output could be programmed at a higher voltage than the other. This would cause a voltage on one output that is higher than its programmed voltage (e.g., 19 V on the output of a 13 V programmed voltage). The output with the highest voltage will effectively turn off the other outputs. As soon as this voltage is reduced below the value of the other outputs, the A8294 output will auto-recover to their programmed levels.

**Charge Pump.** Generates a supply voltage above the internal tracking regulator output to drive the linear regulator control.

**Slew Rate Control.** During either start-up, or when the output voltage at the LNB pin is transitioning, the output voltage rise

and fall times can be set by the value of the capacitor connected from the TCAP pin to GND ( $C_{TCAP}$  or C7 in the Applications Schematic). Note that during start-up, the BOOST pin is pre-charged to the input voltage minus a voltage drop. As a result, the slew rate control for the BOOST pin occurs from this voltage.

The value of  $C_{\mbox{\scriptsize TCAP}}$  can be calculated using the following formula:

$$C_{\text{TCAP}} = (I_{\text{TCAP}} \times 6) / SR$$

where SR is the required slew rate of the LNB output voltage, in V/s, and  $I_{TCAP}$  is the TCAP pin current specified in the data sheet. The recommended value for  $C_{TCAP}$ , 10 nF, should provide satisfactory operation for most applications. However, in some cases, it may be necessary to increase the value of  $C_{TCAP}$  to avoid activating the current limit of the LNB output. One such situation is when two set-top boxes are connected in parallel. If this is the case, the following formula can be used to calculate  $C_{TCAP}$ :

$$\begin{split} C_{TCAP} &\geq (I_{TCAP} \times 6)(2 \times C_{BOOST}) \ / \ I_{LIMLNB} \ , \\ C_{TCAP} &\geq (10 \ \mu A \times 6)(2 \times 100 \ \mu F) \ / \ 500 \ mA = 24 \ nF \end{split}$$

The minimum value of  $C_{TCAP}$  is 2.2 nF. There is no theoretical maximum value of  $C_{TCAP}$  however too large a value will probably cause the voltage transition specification to be exceeded. Tone generation is unaffected by the value of  $C_{TCAP}$ .

**Pull-Down Rate Control.** In applications that have to operate at very light loads and that require large load capacitances (in the order of tens to hundreds of microfarads), the output linear stage provides approximately 40 mA of pull-down capability. This ensures that the output volts are ramped from 18 V to 13 V in a reasonable amount of time.

# **ODT (Overcurrent Disable Time)**

If the LNB output current exceeds 850 mA, typical, for more than 48 ms, then the LNB output will be disabled and the OCP bit will be set.

# **Short Circuit Handling**

If the LNB output is shorted to ground, the LNB output current will be clamped to 850 mA, typical. If the short circuit condition lasts for more than 48 ms, the A8294 will be disabled and the OCP bit will be set.

# Auto-Restart

After a short circuit condition occurs, the host controller should periodically reenable the A8294 to check if the short circuit has



been removed. Consecutive startup attempts should allow at least 2 s of delay between restarts.

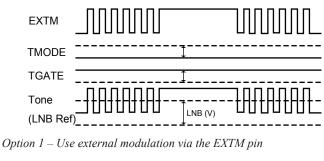
# In-Rush Current

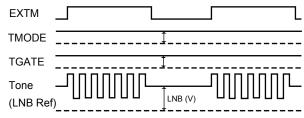
At start-up or during an LNB reconfiguration event, a transient surge current above the normal DC operating level can be provided by the A8294. This current increase can be as high as 850 mA, typical, for as long as required, up to a maximum of 48 ms.

## **Tone Generation**

The A8294 solution offers two options for tone generation. The EXTM pin (external modulation), in conjunction with the  $I^2C^{TM}$  control bit, TMODE (tone mode), provides the necessary control. Both the EXTM pin and TMODE bit determine the 22 kHz control, whether external or internal. With either of the two options, when a tone signal is generated TDET is set in the status register, with the minimum tone detect amplitude of 400 mV.

The two options for tone generation are shown in figure 1.





Option 2 – Use internal modulation by 22-kHz internal clock

Figure 1. Options for tone generation



# I<sup>2</sup>C<sup>™</sup>-Compatible Interface

This is a serial interface that uses two bus lines, SCL and SDA, to access the internal Control and Status registers of the A8294. Data is exchanged between a microcontroller (master) and the A8294 (slave). The clock input to SCL is generated by the master, while SDA functions as either an input or an open drain output, depending on the direction of the data.

## **Timing Considerations**

The control sequence of the communication through the  $I^2C^{TM}$ compatible interface is composed of several steps in sequence:

- 1. Start Condition. Defined by a negative edge on the SDA line, while SCL is high.
- 2. Address Cycle. 7 bits of address, plus 1 bit to indicate read (1) or write (0), and an acknowledge bit. The first five bits of the address are fixed as: 00010. The four optional addresses, defined by the remaining two bits, are selected by the ADD input.

The address is transmitted MSB first.

3. Data Cycles.

Write -6 bits of data and 2 bits for addressing four internal control registers, followed by an acknowledge bit. See Control Register section for more information.

Read – Two status registers, where register 1 is read first, followed by register 2, then register 1, and so on. At the start of any read sequence, register 1 is always read first. Data is transmitted MSB first.

4. Stop Condition. Defined by a positive edge on the SDA line, while SCL is high. Except to indicate a Start or Stop condition, SDA must be stable while the clock is high. SDA can only be changed while SCL is low. It is possible for the Start or Stop condition to occur at any time during a data transfer. The A8294 always responds by resetting the data transfer sequence.

The Read/Write bit is used to determine the data transfer direction. If the Read/Write bit is high, the master reads the contents of register 1, followed by register 2 if a further read is performed. If

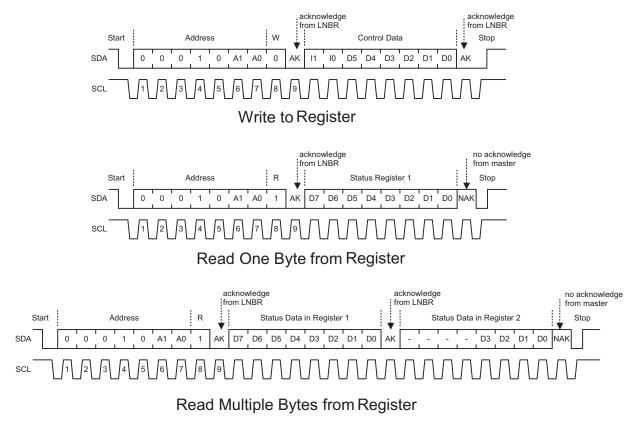


Figure 2. I<sup>2</sup>C<sup>™</sup> Interface. Read and write sequences.



the Read/Write bit is low, the master writes data to one of the two Control registers. Note that multiple writes are not permitted. All write operations must be preceded with the address.

The Acknowledge bit has two functions. It is used by the master to determine if the slave device is responding to its address and data, and it is used by the slave when the master is reading data back from the slave. When the A8294 decodes the 7-bit address field as a valid address, it responds by pulling SDA low during the ninth clock cycle.

During a data write from the master, the A8294 also pulls SDA low during the clock cycle that follows the data byte, in order to indicate that the data has been successfully received. In both cases, the master device must release the SDA line before the ninth clock cycle, in order to allow this handshaking to occur.

During a data read, the A8294 acknowledges the address in the same way as in the data write sequence, and then retains control of the SDA line and send the data from register 1 to the master. On completion of the eight data bits, the A8294 releases the SDA line before the ninth clock cycle, in order to allow the master to acknowledge the data. If the master holds the SDA line low during this Acknowledge bit, the A8294 responds by sending the data from register 2 to the master. Data bytes continue to be sent to the master until the master releases the SDA line during the Acknowledge bit. When this is detected, the A8294 stops sending data and waits for a stop signal.

#### **Interrupt Request**

The A8294 also provides an interrupt request pin, IRQ, which is an open-drain, active-low output. This output may be connected to a common IRQ line with a suitable external pull-up and can be used with other  $I^2C^{TM}$ -compatible devices to request attention

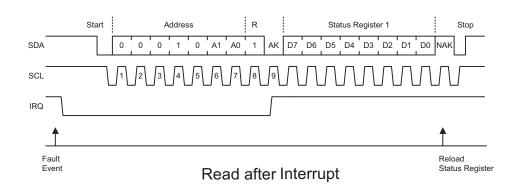
from the master controller.

The IRQ output becomes active when either the A8294 first recognizes a fault condition, or at power-on, when the main supply,  $V_{IN}$ , and the internal logic supply,  $V_{REG}$ , reach the correct operating conditions. It is only reset to inactive when the I<sup>2</sup>C<sup>TM</sup> master addresses the A8294 with the Read/Write bit set (causing a read). Fault conditions are indicated by the TSD, VUV, and OCP bits, and are latched in the Status register. See the Status register section for full description.

The DIS and PNG status bits do not cause an interrupt. The PNG bit is continually updated, apart from the DIS bit, which changes when the LNB is either disabled, faulted, or is enabled.

When the master recognizes an interrupt, it addresses all slaves connected to the interrupt line in sequence, and then reads the status register to determine which device is requesting attention. The A8294 latches all conditions in the Status register until the completion of the data read. The action at the resampling point is further defined in the Status Register section. The bits in the Status register are defined such that the all-zero condition indicates that the A8294 is fully active with no fault conditions.

When  $V_{IN}$  is initially applied, the I<sup>2</sup>C<sup>TM</sup>-compatible interface does not respond to any requests until the internal logic supply  $V_{REG}$  has reached its operating level. Once  $V_{REG}$  has reached this point, the IRQ output goes active, and the VUV bit is set. After the A8294 acknowledges the address, the IRQ flag is reset. After the master reads the status registers, the registers are updated with the VUV reset.







# Control Registers (I<sup>2</sup>C<sup>™</sup>-Compatible Write Register)

All main functions of the A8294 are controlled through the I<sup>2</sup>C<sup>TM</sup>compatible interface via the 8-bit Control registers. As the A8294 contains numerous control options, it is necessary to have two control registers. Each register contains up to 6 bits of data (bit 0 to bit 5), followed by 2 bits for the register address (bit 6 and bit 7). The power-up states for the control functions are all 0s.

The following tables define the control bits for each address and the settings for output voltage:

Bit	Name	Function
0	VSEL0	
1	VSEL1	See table 3, Output Voltage Amplitude Selection
2	VSEL2	
3	VSEL3	0: LNB = Low range
	VOLLO	1: LNB = High range
4	ODT	1 (recommended): The ODT functions are always enabled, but setting 1 recommended at all times.
_		0: Disable LNB Output
5	ENB	1: Enable LNB Output
6	10	Address Bit: 0
7	11	Address Bit: 0

Table 1. Control Register Address (I1, I0) = 00

Bit 0	VSEL0	These three bits pro	vide incremental contro	l over the voltage	on the LNB output
-------	-------	----------------------	-------------------------	--------------------	-------------------

Bit 1 VSEL1 The available voltages provide the necessary levels for all the common standards

Bit 2	VSEL2	plus the ability to add line compensation in increments of 333 mV. The voltage
		levels are defined in table 3, Output Voltage Amplitude Selection.

- Bit 3 VSEL3 Switches between the low level and high level output voltages on the LNB output. 0 selects the low level voltage and 1 selects the high level. The low-level center voltage is 12.709 V nominal and the high level is 18.042 V nominal. These may be increased in steps of 333 mV using the VSEL2, VSEL1 and VSEL0 control register bits.
  Bit 4 ODT The overcurrent disable timer is always enabled. Enables the LNB output. When set to 1 the LNB output is switched on. When set to 0, the LNB output is disabled.
- Bit 6 I0 Address
- Bit 7 I1 Address



Bit	Name	Function
0	TMODE	<ul><li>0: Enable external tone modulation via EXTM pin</li><li>1: Enable internal clock modulation of tone, with gating via EXTM pin</li></ul>
1	TGATE	Must be set to 1: Tone Ready
2	-	Not Used (0 recommended)
3	-	Not Used
4	-	Not Used
5	-	Not Used
6	10	Address Bit: 0
7	11	Address Bit: 1

Table 2.	Control	Register	Address	(11.	10	) = 10

- Bit 0 TMODE Tone Mode. Selects source of tone frequency generation. When set to 0, a digital pulse signal on the EXTM pin is used. When set to 1, a 22-kHz internal clock signal is used. In the case where the the internal clock is used, set the EXTM pin high to enable modulation, and set it low to disable modulation. See Tone Generation Section for more information.
- Bit 1 TGATE Tone Ready. Must be set to 1.
- Bit 2 Not Used.
- Bit 3 Not Used.
- Bit 4 Not Used.
- Bit 5 Not Used.
- Bit 6 I0 Address.
- Bit 7 I1 Address.



	•			
VSEL <sub>3</sub> x	VSEL <sub>2</sub> x	VSEL <sub>1</sub> x	VSEL <sub>0</sub> x	LNB (V)
0	0	0	1	13.042
0	0	1	0	13.375
0	0	1	1	13.709
1	0	0	1	18.375
1	0	1	0	18.709
1	0	1	1	19.042

### Table 3. Output Voltage Amplitude Selection



# Status Registers (I<sup>2</sup>C<sup>™</sup>-Compatible Read Register)

The main fault conditions: overcurrent (OCP), under voltage (VUV) and overtemperature (TSD), are all indicated by setting the relevant bits in the Status registers. In all fault cases, once the bit is set, it remains latched until the A8294 is read by the  $I^2C^{TM}$  master, assuming the fault has been resolved.

The current status of the LNB output is indicated by the disable bit, DIS. The DIS bit is set when either a fault occurs or if the LNB is disabled intentionally. This bit is latched, and is reset when the LNB is commanded on again. The power not good (PNG) and outgoing tone detect (TDET) are the only bits which may be reset without an  $I^2C^{TM}$  read sequence. Table 4 summarizes the condition of each bit when set and how it is reset. As the A8294 has a comprehensive set of status reporting bits, it is necessary to have two Status registers. When performing a multiple read function, register 1 is read followed by register 2, then register 1 again and so on. Whenever a new read function is performed, register 1 is always read first.

The normal sequence of the master in a fault condition will be to detect the fault by reading the Status registers, then rereading the Status registers until the status bit is reset indicating the fault condition is reset. The fault may be detected either by continuously polling, by responding to an interrupt request (IRQ), or by detecting a fault condition externally and performing a diagnostic poll of all slave devices. Note that the fully-operational condition of the Status registers is all 0s, to simplify checking of the Status bit.

Status Bit	Function	Set	Reset Condition
-	Not used	_	Not used
DIS	LNB disabled, either intentionally or due to fault	Latched	LNB enabled and no fault
OCP	Overcurrent	Latched	I <sup>2</sup> C <sup>™</sup> read and fault removed
PNG	Power not good	Non-latched	LNB volts in range
TDET	Outgoing tone detect	Non-latched	Tone stopped
TSD	Thermal shutdown	Latched	I <sup>2</sup> C <sup>™</sup> read and fault removed
VUV	Undervoltage	Latched	I <sup>2</sup> C <sup>™</sup> read and fault removed

## Table 4. Status Register Bit Setting



### Table 5. Status Register 1

Bit	Name	Function	
0	DIS	LNB output disabled	
1	-	Not Used	
2	OCP	Overcurrent	
3	-	Not Used	
4	PNG	Power Not Good	
5	-	Not Used	
6	TSD	Thermal Shutdown	
7	VUV	V <sub>IN</sub> Undervoltage	

Bit 0	DIS	LNB Output Disabled. DIS is used to indicate the current condition of the LNB output. At power-on, or if a fault condition occurs, DIS will be set. This bit changing to 1 does not cause the IRQ to activate because the LNB output may be disabled intentionally by the $I^2C^{TM}$ master. This bit will be reset at the end of a write sequence if the LNB output is enabled.
Bit 1	_	Not used.
Bit 2	OCP	Overcurrent. If the LNB output detects an overcurrent condition, for greater than 48 ms, the LNB output will be disabled. The OCP bit will be set to indicate that an overcurrent has occurred and the disable bit, DIS, will be set. The Status register is updated on the rising edge of the 9 <sup>th</sup> clock pulse in the data read sequence, where the OCP bit is reset in all cases, allowing the master to reenable the LNB output. If the overcurrent timer is not enabled, the device operate in current limit indefinitely and the OCP bit will be set. If the overcurrent condition is removed, the OCP bit will automatically be reset. Note that if the overcurrent operates long enough, and a thermal shutdown occurs, the LNB output will be disabled and the TSD bit will be set.
Bit 3	_	Not used.
Bit 4	PNG	Power Not Good. Set to 1 when the LNB output is enabled and the LNB voltage is below 85% of the programmed voltage. The PNG is reset when the LNB volts are within 90% of the programmed LNB voltage.
Bit 5	_	Not used.
Bit 6	TSD	Thermal shutdown. 1 indicates that the A8294 has detected an overtemperature condition and has disabled the LNB output. The disable bit, DIS, will also be set. The status of the overtemperature condition is sampled on the rising edge of the 9 <sup>th</sup> clock pulse in the data read sequence. If the condition is no longer present, then the TSD bit will be reset, allowing the master to reenable the LNB output if required. If the condition is still present, then the TSD bit will remain at 1.
Bit 7	VUV	Undervoltage Lockout. 1 indicates that the A8294 has detected that the input supply, $V_{IN}$ is, or has been, below the minimum level and an undervoltage lockout has occurred disabling the LNB outputs. The disable bit, DIS, will also be set and the A8294 will not reenable the output until so instructed by writing the relevant bit into the control registers. The status of the undervoltage condition is sampled on the rising edge of the 9 <sup>th</sup> clock pulse in the data read sequence. If the condition is no longer present, then the VUV bit will be reset allowing the master to reenable the LNB output if required. If the condition is still present, then the VUV bit will remain at 1.



## Table 6. Status Register 2

Bit	Name	Function	
0	_	Not Used	
1	_	Not Used	
2	TDET	Outgoing Tone Detect	
3	_	Not Used	
4	-	Not Used	
5	_	Not Used	
6	-	Not Used	
7	_	Not Used	

Bit 0 – Not used.

Bit 1 – Not used.

Bit 2 TDET Outgoing Tone Detect. When tone is enabled, TDET will be set to 1 if the tone appears at the LNB output. When the tone is disabled, TDET is reset.

Bits 3 to 7 Not used.



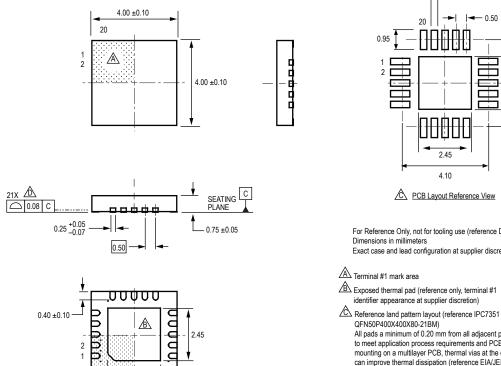
## Table 7. Component Selection Table

Component	Characteristics	Manufacturer Device
C1, C4, C8	100 nF, 50 V, X5R or X7R, 0603	
C2, C5	100 µF, 35 $V_{MIN}$ , ESR<75 m $\Omega$ , I <sub>RIPPLE</sub> > 800 mA	Panasonic: EEU-FM1H101B ChemiCon: EKZE500ELL101MHB5D Nichicon: UHC1V101MPT Panasonic: EEU-FM1H101B
C3	220 nF, 10 V <sub>MIN</sub> , X5R or X7R, 0402 or 0603	
C6	1.0 μF, 25 V <sub>MIN</sub> , X5R or X7R, 1206	TDK: C3216X7R1E105K Murata: GRM31MR71E105KA01 Taiyo Yuden: TMK316BJ105KL-T Kemet: C1206C105K3RACTU
C7	22 nF, 10 V <sub>MIN</sub> , X5R or X7R, 0402 or 0603	
C9	10 nF, 50 V, X5R or X7R, 0402 or 0603	
C10	220 nF, 50 V, X5R or X7R, 0805	
D1, D2	Schottky diode, 40 V, 1 A, SOD-123	Diodes, Inc: B140HW-7 Central Semi: CMMSH1-40
D3	Schottky diode, 40 V, 3 A, SMA	Sanken: SFPB-74 Vishay: B340A-E3/5AT Diodes, Inc.: B340A-13-F Central Senmi: CMSH3-40MA
D4	TVS, 20 $V_{RM}^{},$ 32 $V_{CL}^{}$ at 500 A (8/20 $\mu s$ ), 3000 W	ST:LNBTVS6-221S Littelfuse: SMDJ20A
L1	33 μH, I <sub>SAT</sub> > 2.6 A, DCR < 90 mΩ	TDK: TSL1112RA-330K2R3-PF Taiyo Yuden: LHLC10TB330K Coilcraft: DR0810-333L
R1 to R4	Determined by $V_{DD}$ , bus capacitance, etc.	



16

# Package ES 20-Pin MLP/QFN



0.00000

20 2.45

0.30 - 0.50 2 4 5 4.10 2.45 4.10 A PCB Layout Reference View

For Reference Only, not for tooling use (reference DWG-2864, JEDEC MO-220 WGGD) Dimensions in millimeters Exact case and lead configuration at supplier discretion within limits shown

- Exposed thermal pad (reference only, terminal #1

All pads a minimum of 0.20 mm from all adjacent pads; adjust as necessary to meet application process requirements and PCB layout tolerances; when mounting on a multilayer PCB, thermal vias at the exposed thermal pad land can improve thermal dissipation (reference EIA/JEDEC Standard JESD51-5)

Coplanarity includes exposed thermal pad and terminals



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