











Instruments

LMH6574 SNCS103E - NOVEMBER 2004 - REVISED AUGUST 2018

LMH6574 4:1 High Speed Video Multiplexer

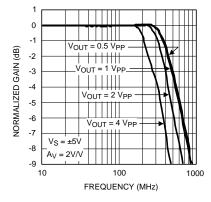
Features

- 500 MHz, 500 mV -3 dB Bandwidth, $A_V = 2$
- 400 MHz, 2 V_{PP} -3 dB Bandwidth, $A_V = 2$
- 8 ns Channel Switching Time
- 70 dB Channel to Channel Isolation at 10 MHz
- 0.02%, 0.05° Diff. Gain, Phase
- 0.1 dB Gain Flatness to 150 MHz
- 2200 V/µs Slew Rate
- Wide Supply Voltage Range: 6 V (±3 V) to 12 V (±6 V)
- -68 dB HD2 at 5 MHz
- -84 dB HD3 at 5 MHz

Applications

- Video Router
- Multi Input Video Monitor
- Instrumentation / Test Equipment
- Receiver IF Diversity Switch
- Multi Channel A/D Driver
- Picture in Picture Video Switch

Frequency Response vs Vout



3 Description

LMH6574 is a high-performance multiplexer optimized for professional grade video and other high fidelity high bandwidth analog applications. The output amplifier selects any one of four buffered input signals based on the state of the two address bits. The LMH6574 provides a 400-MHz bandwidth at 2 V_{PP} output signal levels. Multimedia and high definition television (HDTV) applications can benefit from the LMH6574 0.1 dB bandwidth of 150 MHz and its 2200 V/µs slew rate.

The LMH6574 supports composite video applications with its 0.02% and 0.05° differential gain and phase errors for NTSC and PAL video signals while driving a single, back terminated 75-Ω load. An 80-mA linear output current is available for driving multiple video load applications.

The LMH6574 gain is set by external feedback and gain set resistors for maximum flexibility.

The LMH6574 is available in the 14-pin SOIC package.

Device Information⁽¹⁾

PART NUMBER	PACKAGE	BODY SIZE (NOM)
LMH6574	SOIC (14)	8.65 mm × 3.91 mm

(1) For all available packages, see the orderable addendum at the end of the data sheet.

Frequency Response vs Gain

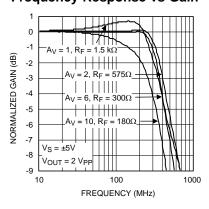




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	7.2 Feature Description			

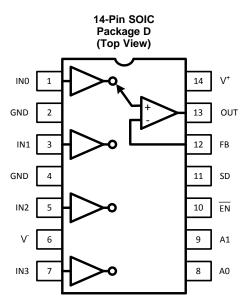
4 Revision History

NOTE: Page numbers for previous revisions may differ from page numbers in the current version.

С	changes from Revision D (December 2014) to Revision E	Page
•	Changed IBN parameter maximum specifications from ±5 μA to ±5.2 μA and from ±5.6 μA to ±5.8 μA	5
•	Changed PSRR parameter minimum specifications from 47 dB to 43 dB and from 45 dB to 41 dB	<mark>5</mark>
•	Changed Supply Current Disabled parameter maximum specifications from 5.8 mA to 6.2 mA and from 5.9 mA to 6.3 mA	6
•	Changed IiL parameter minimum specifications from –2.9 μA to –3.3 μA and from –8.5 μA to –9 μA	6
•	Added Feature Description and Device Functional Modes sections	13
С		
_	changes from Revision C (November 2012) to Revision D	Page
•	Added, updated, or revised the following sections: Pin Configuration and Functions, Specifications, Application and Implementation, Power Supply Recommendations, Layout, Device and Documentation Support, and Mechanical, Packaging, and Orderable Information	
_	Added, updated, or revised the following sections: Pin Configuration and Functions, Specifications, Application and Implementation, Power Supply Recommendations, Layout, Device and Documentation Support, and Mechanical,	1



5 Pin Configuration and Functions



Pin Functions

P	IN	1/0	DESCRIPTION
NO.	NAME	I/O	DESCRIPTION
1	IN0	I	Input Channel 0
2	GND	_	Ground
3	IN1	1	Input Channel 1
4	GND	_	Ground
5	IN2	1	Input Channel 2
6	V-	I	V ⁻ Supply
7	IN3	I	Input Channel 3
8	A0	1	Select Pin A0
9	A1	1	Select Pin A1
10	EN	1	Enable
11	SD	I	Shutdown
12	FB	I	Feedback
13	OUT	0	Output
14	V ⁺	I	V ⁺ Supply

Truth Table

A1	Α0	EN	SD	OUT
1	1	0	0	CH 3
1	0	0	0	CH2
0	1	0	0	CH1
0	0	0	0	CH 0
X	X	1	0	Disable
X	X	X	1	Shutdown



6 Specifications

6.1 Absolute Maximum Ratings⁽¹⁾⁽²⁾

	MIN	MAX	UNIT
Supply Voltage (V ⁺ – V ⁻)		13.2	٧
l _{оит} ⁽³⁾		130	mA
Signal & Logic Input Pin Voltage		±(V _S +0.6)	٧
Signal & Logic Input Pin Current		±20	mA
Maximum Junction Temperature		+150	°C
Storage Temperature	-65	+150	°C

- (1) Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications, see the Electrical Characteristics ±5 V tables
- (2) If Military/Aerospace specified devices are required, please contact the Texas Instruments Sales Office/ Distributors for availability and specifications.
- (3) The maximum output current (I_{OUT}) is determined by the device power dissipation limitations (The junction temperature cannot be allowed to exceed 150°C). See the *Power Dissipation* for more details. A short circuit condition should be limited to 5 seconds or less.

6.2 ESD Ratings

			VALUE	UNIT
V	Floring (1)	Human-body model (HBM), per ANSI/ESDA/JEDEC JS-001 (2)	±2000	V
V _(ESD)	Electrostatic discharge ⁽¹⁾	Machine model (MM)	±200	V

- (1) Human Body model, 1.5 k Ω in series with 100 pF. Machine model, 0 Ω In series with 200 pF.
- (2) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process. Manufacturing with less than 2000-V HBM is possible with the necessary precautions. Pins listed as ±200 V may actually have higher performance.

6.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)(1)

	MIN	NOM MAX	UNIT
Operating Temperature	-40	85	°C
Supply Voltage	6	12	V

⁽¹⁾ Absolute Maximum Ratings indicate limits beyond which damage to the device may occur. Operating Ratings indicate conditions for which the device is intended to be functional, but specific performance is not ensured. For ensured specifications, see the Electrical Characteristics ±5 V tables

6.4 Thermal Information

	THERMAL METRIC ⁽¹⁾		UNIT
	I THERMAL METRIC	14 PINS	UNII
$R_{\theta JA}$	Junction-to-ambient thermal resistance	130	°C/W
$R_{\theta JC(top)}$	Junction-to-case (top) thermal resistance	40	°C/W

 For more information about traditional and new thermal metrics, see the Semiconductor and IC Package Thermal Metrics application report.



6.5 Electrical Characteristics ±5 V

 $V_S = \pm 5 \text{ V}$, $R_L = 100 \Omega$, $A_V = 2 \text{ V/V}$, $R_F = 575 \Omega$, $T_J = 25 ^{\circ}\text{C}$, unless otherwise specified.

	PARAMETER	TEST CO	NDITIONS ⁽¹⁾	MIN	TYP	MAX	UNIT
FREQUE	NCY DOMAIN PERFORMA	ANCE					
SSBW	-3 dB Bandwidth	$V_{OUT} = 0.5 V_{PP}$			500		MHz
LSBW	-3 dB Bandwidth	V _{OUT} = 2 V _{PP}			400		MHz
.1 dBBW	0. 1 dB Bandwidth	$V_{OUT} = 0.25 V_{PP}$			150		MHz
DG	Differential Gain	$R_L = 150 \Omega$, $f = 4.43 MHz$			0.02%		
DP	Differential Phase	$R_L = 150 \Omega$, $f = 4.43 MHz$			0.05		deg
XTLK	Channel to Channel Crosstalk	All Hostile, 5 MHz			-85		dB
TIME DO	MAIN RESPONSE						
TRS	Channel to Channel Switching Time	Logic Transition to 90% Ou	utput		8		ns
	Enable and Disable Times	Logic Transition to 90% or	10% Output		10		ns
TRL	Rise and Fall Time	4-V Step			2.4		ns
TSS	Settling Time to 0.05%	2-V Step 17			ns		
os	Overshoot	2-V Step			5%		
SR	Slew Rate	4-V Step 2200		V/μs			
DISTORT	ION						
HD2	2 nd Harmonic Distortion	2 V _{PP} , 5 MHz			-68		dBc
HD3	3 rd Harmonic Distortion	2 V _{PP} , 5 MHz		-84			dBc
IMD	3 rd Order Intermodulation Products	10 MHz, Two Tones 2 V _{PP}	at Output		-80		dBc
EQUIVAL	ENT INPUT NOISE						
VN	Voltage	>1 MHz, Input Referred			5		nV√ Hz
ICN	Current	>1 MHz, Input Referred			5		pA/√ Hz
STATIC, I	OC PERFORMANCE			!		*	
011014	Channel to Channel	DC, Difference in Gain		±(0.005%	±0.032%	
CHGM	Gain Difference	Between Channels	-40°C ≤ T _J ≤ 85°C			±0.035%	
	1 (2)		-		1	±20	.,
VIO	Input Offset Voltage (2)	$V_{IN} = 0 V$	-40°C ≤ T _J ≤ 85°C			±25	mV
DVIO	Offset Voltage Drift				30		μV/°C
IDNI	Input Bias Current (2)(3)	V 0.V			-3	±5.2	
IBN	input Bias Current (27(8)	$V_{IN} = 0 V$	-40°C ≤ T _J ≤ 85°C			±5.8	μA
DIBN	Bias Current Drift				11		nA/°C
	Inverting Input Bias	Pin 12, Feedback Point,			-7	±10	
	Current	$V_{IN} = 0 V$	-40°C ≤ T _J ≤ 85°C			±13	
DCDD	Power Supply Rejection	DC Innut Deferred		43	54		۲D
PSRR	Ratio ⁽²⁾	DC, Input Referred	-40°C ≤ T _J ≤ 85°C	41			dB

⁽¹⁾ Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T_J = T_A. No ensure of parametric performance is indicated in the electrical tables under conditions of internal self heating where T_J > T_A. See *Application and Implementation* for information on temperature de-rating of this device. Min/Max ratings are based on product testing, characterization and simulation. Individual parameters are tested as noted.

⁽²⁾ Parameters guaranteed by electrical testing at 25°C.

⁽³⁾ Positive Value is current into device.



Electrical Characteristics ±5 V (continued)

 V_S = ±5 V, R_L = 100 Ω , A_V = 2 V/V, R_F = 575 Ω , T_J = 25 °C, unless otherwise specified.

	PARAMETER	TEST CON	IDITIONS ⁽¹⁾	MIN	TYP	MAX	UNIT
100	0	No. Local			13	16	A
ICC	Supply Current ⁽²⁾	No Load	-40°C ≤ T _J ≤ 85°C			18	mA
	Supply Current	ENABLE > 2 V			4.7	6.2	mA
	Disabled ⁽²⁾	ENABLE > 2 V	-40°C ≤ T _J ≤ 85°C			6.3	ША
	Supply Current	SHUTDOWN > 2 V			1.8	2.5	mA
	Shutdown	SHOTDOWN > 2 V	-40°C ≤ T _J ≤ 85°C			2.6	ША
VIH	Logic High Threshold (2)	Select & Enable Pins (SD &	EN)	2.0			V
VIL	Logic Low Threshold (2)	Select & Enable Pins (SD &	EN)			8.0	V
liL	Logic Pin Input Current	Logic Input = 0 V Select &		-3.3	-1		μΑ
IIL	Low ⁽³⁾	Enable Pins (SD & EN)	-40°C ≤ T _J ≤ 85°C	-9			μΑ
liH	Logic Pin Input Current	Logic Input = 2.0 V, Select			47	68	μA
111 1	High ⁽³⁾	& Enable Pins (SD & EN)	-40°C ≤ T _J ≤ 85°C			72.5	μΑ
MISCEL	LANEOUS PERFORMANC	E					
RIN+	Input Resistance				5		kΩ
CIN	Input Capacitance				0.8		pF
ROUT	Output Resistance	Output Active, (EN and SD	< 0.8 V)		0.04		Ω
ROUT	Output Resistance	Output Disabled, (EN or SD	> 2 V)		3000		Ω
COUT	Output Capacitance	Output Disabled, (EN or SD	> 2 V)		3.1		pF
VO		No Load		±3.54	±3.7		V
VO	Output Voltage Range	NO LOAU	-40°C ≤ T _J ≤ 85 °C	±3.53			V
VOL	Output Voltage Range	R _L = 100 Ω		±3.18	±3.5		V
VOL		KL = 100 12	-40°C ≤ T _J ≤ 85°C	±3.17			V
CMIR	Input Voltage Range			±2.5	±2.6		V
				+60			
10	Linear Output Current ⁽²⁾⁽³⁾	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\		-70	.00		mA
Ю	Current ⁽²⁾⁽³⁾	$V_{IN} = 0 V$	-40°C ≤ T _J ≤ 85°C	+50	±80		
			-40°C ≤ T _J ≤ 85°C	-60			
ISC	Short Circuit Current (4)	V _{IN} = ±2 V, Output Shorted	to Ground		±230		mA

⁽⁴⁾ The maximum output current (I_{OUT}) is determined by the device power dissipation limitations (The junction temperature cannot be allowed to exceed 150°C). See the *Power Dissipation* for more details. A short circuit condition should be limited to 5 seconds or less.



6.6 Electrical Characteristics ±3.3 V

 $V_S = \pm 3.3 \text{ V}$, $R_L = 100 \Omega$, $A_V = 2 \text{ V/V}$, $R_F = 575 \Omega$; unless otherwise specified.

	PARAMETER	TEST CONDITIONS ⁽¹⁾	MIN TYP	MAX	UNIT
FREQUEN	CY DOMAIN PERFORMANCE			1	
SSBW	-3 dB Bandwidth	$V_{OUT} = 0.5 V_{PP}$	475		MHz
LSBW	-3 dB Bandwidth	$V_{OUT} = 2.0 V_{PP}$	375		MHz
0.1 dBBW	0.1 dB Bandwidth	$V_{OUT} = 0.5 V_{PP}$	100		MHz
GFP	Peaking	DC to 200 MHz	0.4		dB
XTLK	Channel to Channel Crosstalk	All Hostile, f = 5 MHz	-85		dBc
TIME DOM	AIN RESPONSE				
TRL	Rise and Fall Time	2-V Step	2		ns
TSS	Settling Time to 0.05%	2-V Step	20		ns
OS	Overshoot	2-V Step	5%		
SR	Slew Rate	2-V Step	1400		V/μs
DISTORTIO	ON				
HD2	2 nd Harmonic Distortion	2 V _{PP} , 10 MHz	-67		dBc
HD3	3 rd Harmonic Distortion	2 V _{PP} , 10 MHz	-87		dBc
STATIC, D	C PERFORMANCE				
VIO	Input Offset Voltage	V _{IN} = 0 V	-5		mV
IBN	Input Bias Current ⁽²⁾	$V_{IN} = 0 V$	-3		μΑ
PSRR	Power Supply Rejection Ratio	DC, Input Referred	49		dB
ICC	Supply Current	No Load	12		mA
VIH	Logic High Threshold	Select & Enable Pins (SD & EN)	1.3		V
VIL	Logic Low Threshold	Select & Enable Pins (SD & EN)		0.4	V
MISCELLA	NEOUS PERFORMANCE			·	
RIN+	Input Resistance		5		kΩ
CIN	Input Capacitance		0.8		рF
ROUT	Output Resistance		0.06		Ω
VO	- Output Voltage Range	No Load	±2		V
VOL	Output voitage Range	$R_L = 100 \Omega$	±1.8		V
CMIR	Input Voltage Range		±1.2		V
Ю	Linear Output Current	V _{IN} = 0 V	±60		mA
ISC	Short Circuit Current	V _{IN} = ±1 V, Output Shorted to Ground	±150		mA

⁽¹⁾ Electrical Table values apply only for factory testing conditions at the temperature indicated. Factory testing conditions result in very limited self-heating of the device such that T_J = T_A. No ensure of parametric performance is indicated in the electrical tables under conditions of internal self heating where T_J > T_A. See *Application and Implementation* for information on temperature de-rating of this device. Min/Max ratings are based on product testing, characterization and simulation. Individual parameters are tested as noted.

Product Folder Links: LMH6574

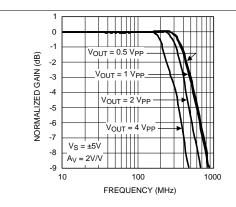
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⁽²⁾ Positive Value is current into device.

TEXAS INSTRUMENTS

6.7 Typical Characteristics

 V_S = ±5 V, R_L = 100 Ω , A_V = 2, R_F = R_G = 575 Ω , unless otherwise specified.



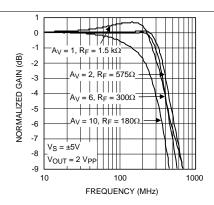


Figure 1. Frequency Response vs V_{OUT}

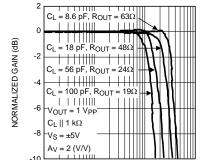


Figure 2. Frequency Response vs Gain

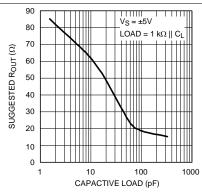


Figure 3. Frequency Response vs Capacitive Load

FREQUENCY (MHz)

100

1000

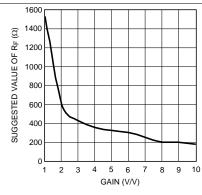


Figure 4. Suggested R_{OUT} vs Capacitive Load

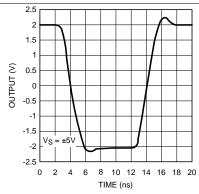


Figure 5. Suggested Value of R_F vs Gain

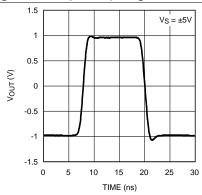
Figure 6. Pulse Response 4VPP

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Typical Characteristics (continued)

 V_S = ±5 V, R_L = 100 Ω , A_V = 2, R_F = R_G = 575 Ω , unless otherwise specified.



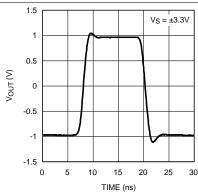


Figure 7. Pulse Response 2V_{PP}

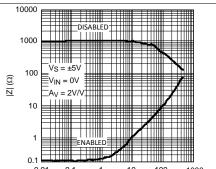


Figure 8. Pulse Response 2V_{PP}

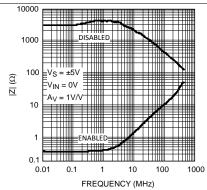


Figure 9. Closed Loop Output Impedance

FREQUENCY (MHz)

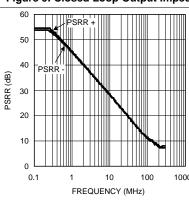


Figure 10. Closed Loop Output Impedance

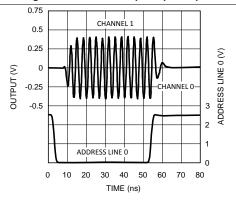


Figure 11. PSRR vs Frequency

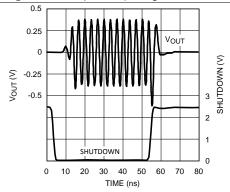
Figure 12. Channel Switching

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TEXAS INSTRUMENTS

Typical Characteristics (continued)

 V_S = ±5 V, R_L = 100 Ω , A_V = 2, R_F = R_G = 575 Ω , unless otherwise specified.



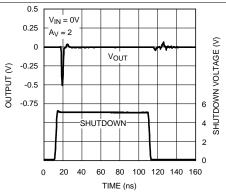
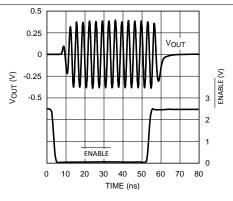


Figure 13. SHUTDOWN Switching

Figure 14. Shutdown Glitch



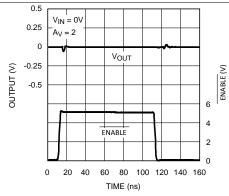
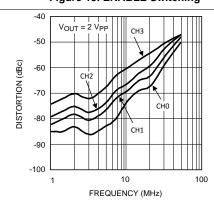


Figure 15. ENABLE Switching

Figure 16. Disable Glitch



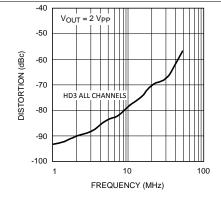


Figure 17. HD2 vs Frequency

Figure 18. HD3 vs Frequency

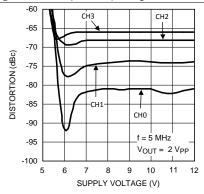
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Typical Characteristics (continued)

 V_S = ±5 V, R_L = 100 Ω , A_V = 2, R_F = R_G = 575 Ω , unless otherwise specified.



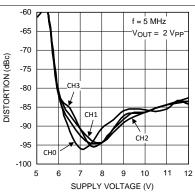


Figure 19. HD2 vs V_S

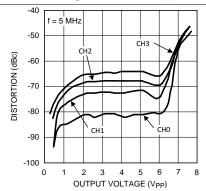


Figure 20. HD3 vs $V_{\rm S}$

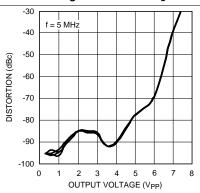


Figure 21. HD2 vs $V_{\rm OUT}$

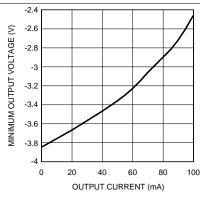
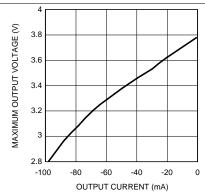


Figure 22. HD3 vs $V_{\rm OUT}$



Positive Value is current into device

Figure 23. Minimum V_{OUT} vs I_{OUT}

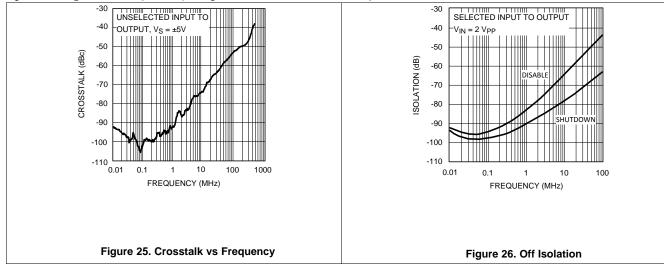
Positive Value is current into device

Figure 24. Maximum V_{OUT} vs I_{OUT}



Typical Characteristics (continued)

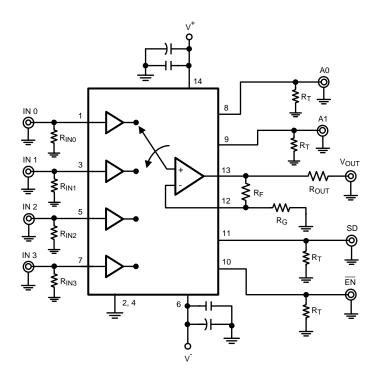
 V_S = ±5 V, R_L = 100 Ω , A_V = 2, R_F = R_G = 575 Ω , unless otherwise specified.





7 Detailed Description

7.1 Functional Block Diagram



7.2 Feature Description

7.2.1 Video Performance

The LMH6574 has been designed to provide excellent performance with production quality video signals in a wide variety of formats such as HDTV and High Resolution VGA. Best performance will be obtained with back-terminated loads. The back termination reduces reflections from the transmission line and effectively masks transmission line and other parasitic capacitances from the amplifier output stage. The *Functional Block Diagram* shows a typical configuration for driving a 75 Ω cable. The output buffer is configured for a gain of 2, so using back terminated loads will give a net gain of 1.

7.2.2 Feedback Resistor Selection

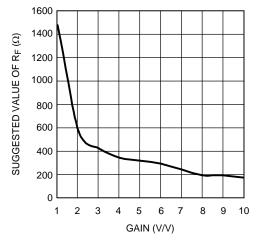


Figure 27. Suggested R_F vs Gain



Feature Description (continued)

The LMH6574 has a current feedback output buffer with gain determined by external feedback (R_F) and gain set (R_G) resistors. With current feedback amplifiers, the closed loop frequency response is a function of R_F . For a gain of 2 V/V, the recommended value of R_F is 575 Ω . For other gains see Figure 27. Generally, lowering R_F from the recommended value will peak the frequency response and extend the bandwidth while increasing the value of R_F will cause the frequency response to roll off faster. Reducing the value of R_F too far below the recommended value will cause overshoot, ringing and, eventually, oscillation.

Since all applications are slightly different it is worth some experimentation to find the optimal R_F for a given circuit. For more information see *Current Feedback Loop Gain Analysis and Performance Enhancement*, Application Note OA-13 (SNOA366), which describes the relationship between R_F and closed-loop frequency response for current feedback operational amplifiers. The impedance looking into pin 12 is approximately 20Ω . This allows for good bandwidth at gains up to 10 V/V. When used with gains over 10 V/V, the LMH6574 will exhibit a "gain bandwidth product" similar to a typical voltage feedback amplifier. For gains of over 10 V/V consider selecting a high performance video amplifier like the LMH6720 (SNOSA39) to provide additional gain.

7.2.3 Other Applications

The LMH6574 could support a multi antenna receiver with up to four separate antennas. Monitoring the signal strength of all 4 antennas and connecting the strongest signal to the final IF stage would provide effective spacial diversity.

For direction finding, the LMH6574 could be used to provide high speed sampling of four separate antennas to a single DSP which would use the information to calculate the direction of the received signal.



Feature Description (continued)

7.2.4 Driving Capacitive Loads

Capacitive output loading applications will benefit from the use of a series output resistor R_{OUT} . Figure 28 shows the use of a series output resistor, R_{OUT} , to stabilize the amplifier output under capacitive loading. Capacitive loads of 5 to 120 pF are the most critical, causing ringing, frequency response peaking and possible oscillation. Figure 29 provides a recommended value for selecting a series output resistor for mitigating capacitive loads. The values suggested in the charts are selected for 0.5 dB or less of peaking in the frequency response. This gives a good compromise between settling time and bandwidth. For applications where maximum frequency response is needed and some peaking is tolerable, the value of R_{OUT} can be reduced slightly from the recommended values.

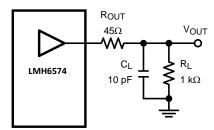
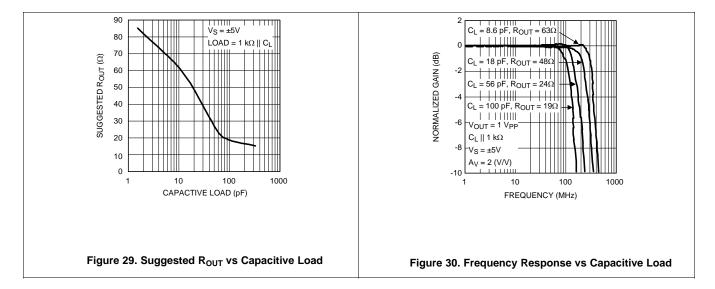


Figure 28. Decoupling Capacitive Loads



7.2.5 ESD Protection

The LMH6574 is protected against electrostatic discharge (ESD) on all pins. The LMH6574 will survive 2000-V Human Body model and 200-V Machine model events. Under normal operation the ESD diodes have no effect on circuit performance. There are occasions, however, when the ESD diodes will be evident. If the LMH6574 is driven by a large signal while the device is powered down the ESD diodes will conduct. The current that flows through the ESD diodes will either exit the chip through the supply pins or will flow through the device, hence it is possible to power up a chip with a large signal applied to the input pins. Using the shutdown mode is one way to conserve power and still prevent unexpected operation.



7.3 Device Functional Modes

7.3.1 SD vs EN

The LMH6574 has both shutdown and disable capability. The shutdown feature affects the entire chip, whereas the disable function only affects the output buffer. When in shutdown mode, minimal power is consumed. The shutdown function is very fast, but causes a very brief spike of about 400 mV to appear on the output. When in shutdown mode the LMH6574 consumes only 1.8 mA of supply current. For maximum input to output isolation use the shutdown function.

The $\overline{\text{EN}}$ pin only disables the output buffer which results in a substantially reduced output glitch of only 50 mV. While disabled the chip consumes 4.7 mA, considerably more than when shutdown. This is because the input buffers are still active. For minimal output glitch use the $\overline{\text{EN}}$ pin. Also, care should be taken to ensure that, while in the disabled state, the voltage differential between the active input buffer (the one selected by pins A0 and A1) and the output pin stays less than 2V. As the voltage differential increases, input to output isolation decreases. Normally this is not an issue. See *Multiplexer Expansion* for further details.

To reduce the output glitch when using the SD pin, switch the $\overline{\text{EN}}$ pin at least 10 ns before switching the SD pin. This can be accomplished by using an RC delay circuit between the two pins if only one control signal is available.

Logic inputs "SD" and " \overline{EN} " will revert to the "High", while " A_0 " and " A_1 " will revert to the "Low" state when left floating.



8 Application and Implementation

NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

8.1 Application Information

The LMH6574 is a high-speed 4:1 analog multiplexer, optimized for very high speed and low distortion. With selectable gain and excellent AC performance, the LMH6574 is ideally suited for switching high resolution, presentation grade video signals. The LMH6574 has no internal ground reference. Single or split supply configurations are both possible. The LMH6574 features very high speed channel switching and disable times. When disabled the LMH6574 output is high impedance making MUX expansion possible by combining multiple devices. See *Multiplexer Expansion*.

8.1.1 Multiplexer Expansion

It is possible to use multiple LMH6574 devices to expand the number of inputs that can be selected for output. Figure 31 shows an 8:1 MUX using two LMH6574 devices.

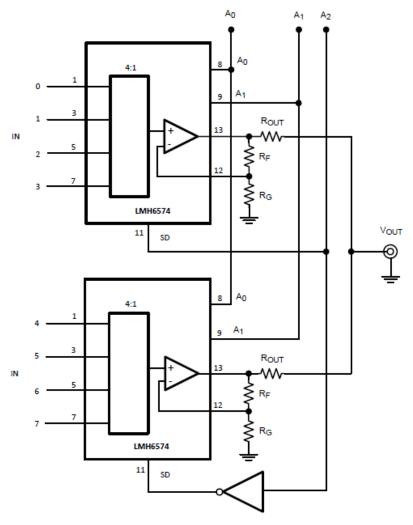


Figure 31. 8:1 MUX Using Two LMH6574 Devices



Application Information (continued)

In such an application, the output settling may be longer than the LMH6574 switching specifications (~20ns), while switching between two separate LMH6574 devices. The switching time limiting factor occurs when one LMH6574 is turned off and another one is turned on, using the SD (shutdown) pin. The output settling time consists of the time needed for the first LMH6574 to enter high impedance state plus the time required for the second LMH6574 output to dissipate the left-over output charge of the first device (limited by the output current capability of the second device) and the time needed to settle to the final voltage value.

While Figure 31 MUX expansion benefits from more isolation, originating from the parasitic loading of the unselected channels on the selected channel, afforded by individual R_{OUT} on each multiplexer output, this configuration does not produce the fastest transition between individual LMH6574 devices. For the fastest transition, the configuration of Figure 32 can be used where the LMH6574 output pins are all shorted together.

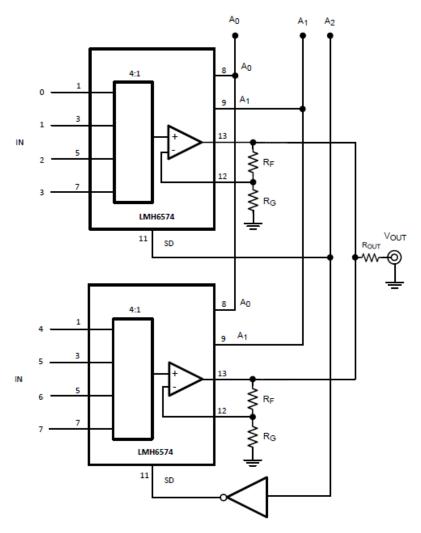


Figure 32. Alternate 8:1 MUX Expansion Schematic (for Faster SD Switching)



Application Information (continued)

Figure 33 shows typical transition waveforms and shows that SD pin switching settles in less than 145 ns.

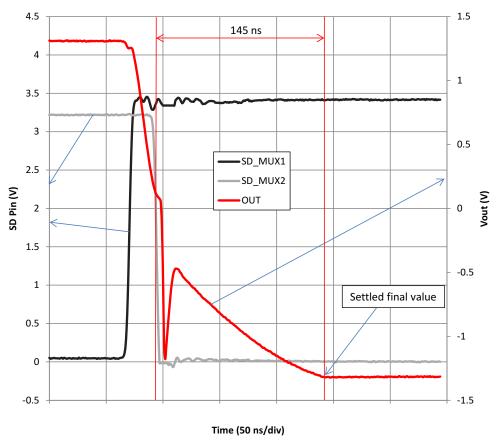


Figure 33. SD Pin Switching Waveform and Output Settling

If it is important in the end application to make sure that no two inputs are presented to the output at the same time, an optional delay block can be added, to drive the SHUTDOWN pin of each device. Figure 34 shows one possible approach to this delay circuit. The delay circuit shown will delay SHUTDOWN's H to L transitions (R1 and C1 decay) but will not delay its L to H transition. R2 should be kept small compared to R1 in order to not reduce the SHUTDOWN voltage and to produce little or no delay to SHUTDOWN.

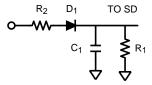


Figure 34. Delay Circuit Implementation



Application Information (continued)

With the SHUTDOWN pin putting the output stage into a high impedance state, several LMH6574's can be tied together to form a larger input MUX. However, there is a loading effect on the active output caused by the unselected devices. The circuit in Figure 35 shows how to compensate for this effect. For the 16:1 MUX function shown in Figure 35, the gain error would be about -0.8 dB, or about 9%. In the circuit in Figure 35, resistor ratios have been adjusted to compensate for this gain error. By adjusting the gain of each multiplexer circuit the error can be reduced to the tolerance of the resistors used (1% in this example).

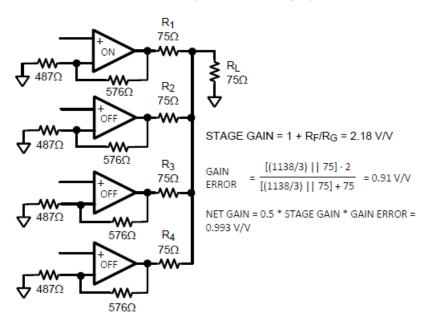


Figure 35. Multiplexer Gain Compensation

NOTE

Disabling of the LMH6574 using the EN pin is not recommended for use when doing multiplexer expansion. While disabled, If the voltage between the selected input and the chip output exceeds approximately 2V the device will begin to enter a soft breakdown state. This will show up as reduced input to output isolation. The signal on the non-inverting input of the output driver amplifier will leak through to the inverting input, and then to the output through the feedback resistor. The worst case is a gain of 1 configuration where the non inverting input follows the active input buffer and (through the feedback resistor) the inverting input follows the voltage driving the output stage. The solution for this is to use shutdown mode for multiplexer expansion.

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9 Power Supply Recommendations

9.1 Power Dissipation

The LMH6574 is optimized for maximum speed and performance in the small form factor of the standard SOIC package. To ensure maximum output drive and highest performance, thermal shutdown is not provided. Therefore, it is of utmost importance to make sure that the T_{JMAX} is never exceeded due to the overall power dissipation.

Follow these steps to determine the Maximum power dissipation for the LMH6574:

1. Calculate the quiescent (no-load) power.

$$P_{AMP} = I_{CC}^* (V_S)$$

where

•
$$V_S = V^+ - V^-$$
 (1)

2. Calculate the RMS power dissipated in the output stage:

$$P_D$$
 (rms) = rms (($V_S - V_{OUT}$) * I_{OUT})

where

- V_{OUT} is the voltage across the external load
- I_{OUT} is the current through the external load

3. Calculate the total RMS power: $P_T = P_{AMP} + P_D$.

The maximum power that the LMH6574 package can dissipate at a given temperature can be derived with the following equation:

$$P_{MAX} = (150^{\circ} - T_{AMB})/R_{\theta JA}$$

where

- T_{AMB} = Ambient temperature (°C)
- R_{BJA} = Thermal resistance, from junction to ambient, for a given package (°C/W)

For the SOIC package R_{θ,JA} is 130 °C/W.

10 Layout

10.1 Layout Guidelines

Whenever questions about layout arise, use the evaluation board LMH730276 as a guide. To reduce parasitic capacitances, ground and power planes should be removed near the input and output pins. For long signal paths controlled impedance lines should be used, along with impedance matching elements at both ends. Bypass capacitors should be placed as close to the device as possible. Bypass capacitors from each rail to ground are applied in pairs. The larger electrolytic bypass capacitors can be located farther from the device, the smaller ceramic capacitors should be placed as close to the device as possible. In the *Functional Block Diagram*, the capacitor between V⁺ and V⁻ is optional, but is recommended for best second harmonic distortion. Another way to enhance performance is to use pairs of 0.01 μ F and 0.1 μ F ceramic capacitors for each supply bypass.

Product Folder Links: LMH6574

(3)



11 Device and Documentation Support

11.1 Documentation Support

11.1.1 Related Documentation

For additional information, see the following:

- Current Feedback Loop Gain Analysis and Performance Enhancement Application Note OA-13
- IC Package Thermal Metrics Application Report
- LMH730276 4:1 Multiplexer Evaluation Board

11.2 Receiving Notification of Documentation Updates

To receive notification of documentation updates, navigate to the device product folder on ti.com. In the upper right corner, click on *Alert me* to register and receive a weekly digest of any product information that has changed. For change details, review the revision history included in any revised document.

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11.5 Electrostatic Discharge Caution



This integrated circuit can be damaged by ESD. Texas Instruments recommends that all integrated circuits be handled with appropriate precautions. Failure to observe proper handling and installation procedures can cause damage.

ESD damage can range from subtle performance degradation to complete device failure. Precision integrated circuits may be more susceptible to damage because very small parametric changes could cause the device not to meet its published specifications.

11.6 Glossary

SLYZ022 — TI Glossarv.

This glossary lists and explains terms, acronyms, and definitions.

12 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.

PACKAGE MATERIALS INFORMATION

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TAPE AND REEL INFORMATION





	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
LMH6574MAX/NOPB	SOIC	D	14	2500	330.0	16.4	6.5	9.35	2.3	8.0	16.0	Q1

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*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)	
LMH6574MAX/NOPB	SOIC	D	14	2500	367.0	367.0	35.0	

D (R-PDSO-G14)

PLASTIC SMALL OUTLINE



NOTES:

- A. All linear dimensions are in inches (millimeters).
- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AB.



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