

Power Factor Correction Discontinuous Conduction Mode Controller

Features and Benefits

- Interleaved Discontinuous Conduction Mode (DCM) operation: low peak current, low ripple current, and low noise; for medium- to high-power applications
- Constant Voltage Mode control: no auxiliary windings required on inductors because of the built-in arithmetic circuit; achieves a simple PFC system
- Maximum on-time: 15 µs (typ)
- Built-in Soft Start function: reduces stress on power devices at startup
- Built-in High Speed Response (HSR): suppression of output voltage changes during dynamic load transients
- Error Amplifier reference voltage: 3.5 V (typ)

Continued on the next page ...

Description

The SSC2101S is a controller IC intended to implement a Discontinuous Conduction Mode (DCM) interleaved Power Factor Correction (PFC) circuit. Using the two-phase interleaved control incorporated in this IC, it is possible to achieve a low cost, high performance PFC system with low input/output ripple currents, low noise, and few external components.

Package: SOP8



Functional Block Diagram



Power Factor Correction Discontinuous Conduction Mode Controller

Features and Benefits (continued)

- Protection Functions
- Soft Overvoltage Protection (SOVP): output voltage reduction
- Output Overvoltage Protection (OVP): gate drive on/off on a pulse-by-pulse basis, with auto-restart
- Overcurrent Protection (OCP): dual-level OCP, with auto-restart
- Output Open Loop Detection (OLD): switching operation stop and transition to standby mode
- Open Terminal Protection (OTP): switching operation stop or output voltage reduction, during open condition on VFB, VIN, or IS terminals
- Thermal Shutdown (TSD): auto-restart with hysteresis

Selection Guide

Part Number	
SSC2101S	

Absolute Maximum Ratings* T_A = 25°C unless otherwise specified

Characteristics	Symbol	Notes	Terminals	Rating	Unit
VCC Terminal Voltage	V _{CC}		4 – 6	-0.3 to 30	А
COMP Terminal Voltage	V _{COMP}		1 – 6	-0.3 to 5.5	А
VFB Terminal Voltage	V _{FB}		3 – 6	-0.3 to 5.5	V
VFB Terminal Current	I _{FB}		3 – 6	-1 to 1	mA
VIN Terminal Voltage	V _{IN}		2 – 6	-0.3 to 5.5	V
VIN Terminal Current	l _{IN}		2 – 6	-1 to 1	mA
IS Terminal Voltage	V _{IS}		8 – 6	-16.0 to 5.5	V
IS Terminal Current	I _{IS}		8 – 6	−1.75 to 1	mA
OUT2 Terminal Voltage	V _{OUT2}		5 – 6	-0.3 to 30	V
OUT1 Terminal Voltage	V _{OUT1}		7 – 6	-0.3 to 30	V
Operating Frame Temperature	T _{FOP}		-	-40 to 85	°C
Storage Temperature	T _{stg}		_	-40 to 125	°C
Junction Temperature	Tj		_	-40 to 125	°C

*Current polarity is defined relative to the IC: sink as positive, source as negative.

Terminal List Table

Pin-out Diagram



		•
Name	Number	Function
1	COMP	Error Amplifier output and phase compensation terminal
2	VIN	AC mains rectified voltage monitoring input terminal
3	VFB	Feedback control terminal, input for: Constant Voltage Mode control signal, Overvoltage Protection signal, and Open Loop Detection signal
4	VCC	IC power supply input terminal
5	OUT2	Gate drive 2 output terminal
6	GND	IC ground terminal
7	OUT1	Gate drive 1 output terminal
8	IS	Peak current detection signal input terminal

Characteristics Symbol **Test Conditions** Terminals Min. Тур. Max. Unit **Power Supply Start-up Operation** VCC Operation Start Voltage V_{CC(ON)} 4 - 610.8 11.6 12.4 V VCC Operation Stop Voltage V_{CC(OFF)} 4 - 69.8 10.6 11.4 V VCC Undervoltage Lockout Hysteresis 4 - 60.8 1.0 1.2 V V_{CC(HYS)} VCC Circuit Current in Pre-operation 4 - 6_ 40 100 μΑ I_{CC(OFF)} VCC Circuit Current in Operation 4 - 611.0 15.0 mΑ I_{CC(ON)} _ VCC Circuit Current During OVP 4 - 68.0 10.0 mΑ I_{CC(OVP)} VCC Circuit Current During Standby 4 - 6100 200 μA I_{CC(Standby)} **Oscillator Operation** Maximum On-Time 7 - 6**t**ONMAX 14 15 16 us 5 - 65 OUT1 to OUT2 On-Time Matching **t**_{RATIO} -5 0 % 7 - 65 – 6 OUT1 to OUT2 Phase Difference 170 180 190 Δ_{PHASE} deg. 7 – 6 **Protection Operation** VFB Output Open Loop Stop Voltage 3 - 60.46 0.50 0.54 V V_{FB(OLDL)} V VFB Output Open Loop Start Voltage $V_{\text{FB(OLDH)}}$ 3 - 60.64 0.70 0.76 VFB Output Overvoltage Protection 3.64 3.72 3.80 V 3 - 6V_{FB(OVP)} Voltage VFB Output Soft Overvoltage 3.60 V 3 - 63.68 3.76 V_{FB(SOVP)} Protection Voltage IS Lower Overcurrent Protection 8 – 6 -0.48 -0.42 -0.36 V VIS(OCPL) Voltage IS Upper Overcurrent Protection 8 - 6-0.62 -0.55 -0.48 V VIS(OCPH) Voltage COMP Sink Current During 1 - 680 100 120 μA ICOMP(SK) Protection Mode Upper Thermal Shutdown Protection °C T_{JTSDH} Not tested, guaranteed by design _ 150 _ _ Threshold Temperature Lower Thermal Shutdown Protection 140 °C T_{JTSDL} Not tested, guaranteed by design Threshold Temperature Thermal Shutdown Protection °C Not tested, guaranteed by design 10 TJTSDHYS _ _ _ Hysteresis **Error Amplifier Operation** VFB Error Amplifier Reference V V_{FB(REF)} 3 - 63.4 3.5 3.6 Voltage VFB Error Amplifier Transconductance 80 100 120 μS **g**_{mEA} _ Gain COMP Error Amplifier Maximum 1 – 6 -36 -30 -24 μA I_{COMP(SO)} Source Current COMP Error Amplifier Maximum V_{COMP(MAX)} 1 - 64.00 4.12 4.25 V **Output Voltage** VFB High Speed Response VFB(HSR)enable Not tested, guaranteed by design 3 - 63.3 3.4 3.5 V Enable Voltage

ELECTRICAL CHARACTERISTICS Valid at T_A = 25°C, unless otherwise specified

Continued on the next page ...

Characteristics	Symbol	Test Conditions	Terminals	Min.	Тур.	Max.	Unit
VFB High Speed Response Active Voltage	V _{FB(HSR)} active		3 – 6	3.1	3.2	3.3	V
COMP High Speed Response Source Current	I _{COMP(SOHSR)}		1 – 6	-120	-100	-80	μA
VFB Input Bias Current	I _{FB(bias)}		3 – 6	_	_	1.5	μA
COMP Voltage During Output Open Loop Detection	V _{COMP(OLD)}		1 – 6	0.7	0.9	1.1	V
Drive Circuit						·	
OUTx Gate Voltage (Low)	V _{OUT(L)}		5 – 6 7 – 6	-	-	0.3	V
OUTx Gate Voltage (High)	V _{OUT(H)}		5 – 6 7 – 6	_	10.2	_	V
OUTx Rise Time	tr		5 – 6 7 – 6	-	70	_	ns
OUTx Fall Time	t _f		5 – 6 7 – 6	-	35	_	ns
OUTx Peak Source Current	I _{OUT(SO)}	Not tested, guaranteed by design	5-6 7-6	_	-0.5	_	А
OUTx Peak Sink Current	I _{OUT(SK)}	Not tested, guaranteed by design	5 – 6 7 – 6	_	0.5	_	A

ELECTRICAL CHARACTERISTICS (continued) Valid at T_A = 25°C, unless otherwise specified

*Current polarity is defined relative to the IC: sink as positive, source as negative.

Thermal Characteristics Valid at T_A = 25°C

Characteristics	Symbol	Test Conditions	Terminals	Min.	Тур.	Max.	Unit
Package Thermal Resistance (Junction to Internal Leadframe)	$R_{\theta JF}$	Internal leadframe temperature (T_F) is measured at the root of pin 6, the GND terminal.	-	-	65	85	°C/W

Power Factor Correction Discontinuous Conduction Mode Controller

Functional Description

Interleaved Discontinuous Conduction Mode (DCM)

The well-known single-phase Discontinuous Conduction Mode (DCM) technique achieves low switching noise because the drain current increase starts at zero when a power MOSFET turns on, and the rate of drain current increase is not steep, as shown by the waveforms in Figure 1. However, the usable power level of single-phase DCM is limited by the very high input/output ripple currents that are generated.

The SSC2100 series provides two-phase interleaved DCM (see

Figure 2). This advanced technique incorporates two boost converters working together to cancel input ripple currents and to reduce output ripple currents. This result is based on a phase difference of 180° between the two converters.

Interleaved DCM also achieves a PFC system with lower switching noise and smaller input filter footprint in comparison to single-phase DCM. This is because reducing input/output ripple currents increases the filtering effectiveness of the EMI filter and also reduces switching noise.



Figure 1. External circuit and current waveforms for single-phase DCM



Figure 2. External circuit and current waveforms for two-phase interleaved DCM

Power Factor Correction Discontinuous Conduction Mode Controller

Startup Operation

VCC is the external power supply input to the SSC2100 IC. The external circuit for the VCC terminal is shown in Figure 3.

When AC mains and VCC external voltage are applied, after the VFB terminal voltage increases to $V_{FB(OLDH)} = 0.7 V (typ)$ or more and the VCC terminal voltage increases to $V_{CC(ON)} = 11.6 V (typ)$ or more, the control circuit starts switching operation.

Note: One of the startup conditions is that the input voltage must reach 20% or more of the rated value for V_{OUT} . This value of V_{OUT} is equivalent to approximately $V_{FB(OLDH)} = 0.7 V$ (typ).

When the VCC terminal voltage subsequently decreases to $V_{CC(OFF)} = 10.6 \text{ V} (typ)$ or less, the control circuit stops switching operation. It does so by enabling the UVLO (undervoltage lockout) circuit, and then reverting to the standby mode that is the state of the IC before startup.

When the VFB terminal voltage subsequently decreases to $V_{FB(OLDL)} = 0.5 V (typ)$ or less, the control circuit stops switching operation and reverts to pre-startup standby mode, even if VCC terminal voltage has increased to $V_{CC(ON)}$ or more.

Because the regulation range of the VCC internal circuit is very wide, between $V_{CC(OFF)} = 11.4 \text{ V} (\text{max})$ and the V_{CC} absolute maximum rating of 30 V (max), a wide input voltage range from the external power supply can be applied. The behaviors of ICC during startup and when switching is stopped are shown in Figure 4.



Figure 3. External circuit of VCC terminal





Soft Start Function

Soft start is adjusted by the external circuits on the VFB and COMP terminals, as shown in Figure 5. At startup, when the input voltage increases to approximately 20% of the rated output voltage, V_{OUT} , and the VCC terminal voltage increases to $V_{CC(ON)} = 11.6 \text{ V}$ (typ), soft start operation begins.

As shown in Figure 6, during the soft start period, the COMP terminal is charged by $I_{COMP(SO)} = -30 \mu A$. In this way, the output power increases gradually, reducing stress on the power devices.



Figure 5. External circuits of VFB and COMP terminals





Power Factor Correction Discontinuous Conduction Mode Controller

Voltage Control Operation

A generic PFC circuit for implementing single-phase DCM is shown in Figure 7. The circuit is composed of a boost inductor (L1), a switching device (Q1), a rectifier diode (D2), and an output capacitor (C2). A control circuit would monitor the C2 voltage and generate an error amplifier output signal to operate Q1. When the control circuit detects an off-time at the L1 Zero Current Detection (ZCD) winding, it turns on Q1 for a period of time. When Q1 is later turned off, the energy stored in L1 is transferred through D2 to C2. After all of the energy stored in L1 is transferred to C2, the control circuit would again turn on Q1, repeating the process.

The SSC2100 series two-phase interleaved DCM uses the VIN terminal to monitor the AC mains rectified input voltage, the VFB terminal to monitor output voltage, and the COMP terminal to monitor phase compensation. This IC internally generates the on-time, t_{ON} , and off-time, t_{OFF} , and it controls output voltage



Figure 7. PFC circuit with generic single-phase DCM

using the voltage-mode control method. Thus, a PFC system used with this IC has no requirement for an auxiliary winding to detect zero crossings of the inductor current. This allows simple circuits with few external components.

In the boost PFC converter, t_{ON} is a function of load power and t_{OFF} is a function of both the input voltage, E_{IN} , and the rated output voltage, V_{OUT} . The relationship between t_{ON} and t_{OFF} is given by the following:

$$t_{\rm OFF} > \frac{E_{\rm IN}}{V_{\rm OUT} - E_{\rm IN}} \times t_{\rm ON}$$
(1)

The VIN terminal voltage is monitored internally and used to calculate the internal t_{OFF} . The typical relationship between t_{ON} and the VIN terminal voltage, V_{IN} , is shown in Figure 8. The maximum t_{ON} occurs at $V_{IN} = 0$ V. The values shown assume $V_{COMP} = 4$ V, where V_{COMP} is the COMP terminal voltage.

As shown in Figure 9, the rectified input voltage is divided by R1 and R2, and input to the VIN terminal. The output voltage is divided by R3 and R4, and input to the VFB terminal. Because of the way in which the VIN terminal voltage and the VFB terminal voltage are used for internal calculations, the two dividers should be well matched. Thus, the R1, R2, and C7 values of the input portion should be equal to the R3, R4, and C8 values of the output portion.

R1 is recommended to be a high-value resistor, in the range from several hundred k Ω to several M Ω , ±1% tolerance, and of an anti-electromigration type, such as metal oxide film.

C8, if necessary to reduce high frequency noise, is recommended to have a capacitance of in the range of 0.1 to 10 nF.



Figure 8. Typical relationship between V_{IN} and t_{ON}

Power Factor Correction Discontinuous Conduction Mode Controller

High Speed Response Function (HSR)

The boost PFC converter is supplied by an AC sinusoidal waveform at the local commercial mains input voltage and frequency. However, the IC voltage control circuit, described above, characteristically responds at a relatively slow rate. As a result, the dynamic load response of the IC would be slow, and could cause the output voltage to drop too quickly.

The innovative built-in High Speed Response (HSR) function reduces variation of the output voltage under dynamic load change conditions. As shown in Figure 10, when the VFB terminal voltage increases to $V_{FB(HSR)enable} = 3.4 \text{ V} (typ)$ or more, the control circuit enables the HSR operation. If the VFB terminal voltage subsequently decreases to $V_{FB(HSR)active} = 3.2 \text{ V} (typ)$ or less, whether due to dynamic load change or other conditions, the control circuit activates the HSR operation.

When HSR is in active operation, the COMP terminal charges by $I_{COMP(SOHSR)} = -100 \ \mu A (typ)$ and the output power increases until the COMP terminal voltage increases to 3.2 V (typ). $V_{FB(HSR)active} = 3.2 V (typ)$ is equivalent to approximately 91.4% of the rated output voltage, V_{OUT} .

Soft start period

LC : Dynamic load change period HSR: High speed response operation period

OV: Overvoltage operation period

CV :

Constant voltage operation period



Figure 9. External circuits for VIN and VFB terminals



Figure 10. VFB terminal voltage waveforms

SSC2101S-DS, Rev. 1

Gate Drive

The OUT1 and OUT2 terminals each directly drive an external power MOSFET. Currents and voltages are set as follows:

Peak C	Current	Gate Voltage			
Source	Sink	Low	High		
–0.5 A (typ)	0.5 A (typ)	0.3 V (max)	10.2 V (typ)		

Resistors R7, R8, R9, and R10 in Figure 11 should be selected for performance in the actual application, because these values relate to the individual board layout patterns and power MOSFET capacities. The gate resistors, R7 and R8, are recommended to be in the range of several ohms to several tens of ohms, and should be selected to reduce gate voltage ringing and EMI noise. R9 and R10 help to prevent malfunctions caused by steep dV/dt during power MOSFET turn-off. The recommended values are in the 10 to 100 k Ω range. These components should be placed close to the gate and source terminals of the corresponding power MOSFET.

Error Amplifier Phase Compensation

The phase compensation circuit is connected between the COMP and GND terminals, as shown in Figure 12. The COMP terminal

D2

D3

Q1

R9

Q2

VOUT

C2

L1

L2

R8

R10

Ж

R7



The phase compensation components, C4, C5, and R11 (see Figure 12), have typical recommended values shown below, but should be selected for performance in the application: to reduce ripple, or to enhance transient load response at the rated output voltage.

- C4: 0.047 to 0.47 μF
- C5: 0.47 to 10 μF
- R11: 10 to 100 k Ω

Thermal Shutdown Protection (TSD)

When the temperature of the IC increases to T_{JTSDH} = 150°C (min) or more, the control circuit stops switching operation. Conversely, when temperature decreases to T_{JTSDL} = 140°C or less, the control circuit restarts switching operation. The hysteresis of the detection temperature, $T_{JTSDHYS}$, is 10°C (typ).



Figure 11. External circuits for OUTx terminals

Figure 12. Phase compensation circuit (external COMP terminal circuit)

SSC2100

IS 8

OUT1 7

GND 6

0UT2 5

1 COMP

2 VIN

3 VFB

4 VCC

Power Factor Correction Discontinuous Conduction Mode Controller

Overcurrent Protection (OCP)

The inductor current of both inductors is monitored by the detection resistor, R5, and is input to the IS terminal, as shown in Figure 13.

The overcurrent protection function has two stages, IS Lower OCP, and IS Upper OCP, described below.

IS Lower Overcurrent Protection, $V_{IS(OCPL)}$ When the inductor current is increasing and if the IS terminal voltage decreases to $V_{IS(OCPL)} = -0.42$ V (typ), the control circuit limits the output power by turning off either one or both power MOSFETs, according to the output states of both OUT1 and OUT2, as follows:

• If either one of OUT1 or OUT2 is high when the fault occurs, that output is now set low (so both outputs are off). Figure 14 is



Figure 13. External circuits for IS and OUTx terminals



Figure 14. $V_{\rm IS(OCPL)}$ operation waveform after OUT1 is set to high and OUT2 is set to low

an example. Where the IS terminal voltage falls to $V_{\rm IS(OCPL)}$ or lower while OUT1 is high (Q1 is ON) and OUT2 is low, under this condition, OUT1 is set to low.

• If both OUT1 and OUT2 are high when the fault occurs, the output that went high earlier than the other output (considering the current pulses only) is now set low (the other output remains high). Figure 15 is an example where both OUT1 and OUT2 are high (Q1 and Q2 are on), and the IS terminal detects $V_{IS(OCPL)}$ or lower. Under this condition, because OUT1 was set high before OUT2 was, OUT1 is now set low (and OUT2 remains high).

R5 (see Figure 13) should be selected for performance in the actual application, such that IS terminal voltage reaches $V_{\rm IS(OCPL)}$ or lower under the conditions of minimum input voltage and peak load.



Figure 15. $V_{\text{IS}(\text{OCPL})}$ operation waveform after both OUT1 and OUT2 are set to high



Figure 16. Phase compensation circuit (external COMP terminal circuit)

Power Factor Correction Discontinuous Conduction Mode Controller

R6 is a damping resistor, which buffers IS terminal current against surge currents, such as inrush currents. It is recommended to have a value of 100 Ω .

C3, if necessary to reduce high frequency noise, is recommended to have a capacitance of in the range of 0.1 to 10 nF.

IS Upper Overcurrent Protection, $V_{IS(OCPH)}$ If the IS terminal voltage decreases to $V_{IS(OCPH)} = -0.55$ V (typ) or lower, the control circuit limits the output power on a pulse-by-pulse basis by setting both OUT1 and OUT2 low, which turns off both power MOSFETs. This is shown in Figure 16. This protection function operates under abnormal conditions such as when an inductor is shorted or is saturated.

Overvoltage Protection (OVP)

The overvoltage protection function has two stages, Soft OVP, and OVP, illustrated in Figure 17 and described below.

VFB Output Soft Overvoltage Protection, $V_{FB(SOVP)}$ When VFB terminal voltage increases to $V_{FB(SOVP)} = 3.68 \text{ V}$ (typ), Soft Overvoltage Protection is activated. This discharges the COMP terminal by $I_{COMP(SK)} = 100 \mu A$ (typ) and the output voltage is decreased. $V_{FB(SOVP)} = 3.68 \text{ V}$ (typ) is equivalent to about 105% of the rated output voltage, V_{OUT} .

The output voltage threshold that initiates Soft Overvoltage Protection, is calculated approximately as follows:

$$V_{\text{OUT(SOVP)}} \approx \frac{V_{\text{OUT(norm)}}}{V_{\text{FB(REF)}}} \times V_{\text{FB(SOVP)}}$$
 (2)

where $V_{OUT(norm)}$ is V_{OUT} under normal operating conditions, and $V_{FB(REF)}$ is the Error Amplifier reference voltage, 3.5V (typ).

VFB Output Overvoltage Protection, $V_{FB(OVP)}$ When the VFB terminal voltage increases to $V_{FB(OVP)} = 3.72$ V (typ), both OUT1 and OUT2 are set low on a pulse-by-pulse basis, which stops the output supply by turning off the power MOSFETS. When VFB terminal voltage decreases to $V_{FB(SOVP)}$, the control circuit stops discharging from the COMP terminal and restores switching operation.

The output voltage threshold that initiates Overvoltage Protection, is calculated approximately as follows:

$$V_{\text{OUT(OVP)}} \approx \frac{V_{\text{OUT(norm)}}}{V_{\text{FB(REF)}}} \times V_{\text{FB(OVP)}}$$
 (3)

where $V_{OUT(norm)}$ is V_{OUT} under normal operating conditions, and $V_{FB(REF)}$ is the Error Amplifier reference voltage, 3.5V (typ).

R3 is recommended to be a high-value resistor, in the range from several hundred k Ω to several M Ω , ±1% tolerance, and of an anti-electromigration type, such as metal oxide film.

C8 is recommended if necessary to reduce high frequency noise, and should have a rating of 0.1 to 10 nF.

Open Loop Detection (OLD)

In the event that the output voltage detection resistor, R3 (see Figure 18), opens and VFB terminal voltage decreases to $V_{FB(OLDL)} = 0.5 V (typ)$ or less, the control circuit stops the switching operation and enters standby mode. $V_{FB(OLDL)} = 0.5 V (typ)$ is equivalent to about 14.3% of the rated output voltage, V_{OUT} .

When the VFB terminal voltage subsequently increases to $V_{FB(OLDH)} = 0.7 V$ (typ) or more, the control circuit restores switching operation. $V_{FB(OLDH)} = 0.7 V$ (typ) is equivalent to about 20% of the rated output voltage, V_{OUT} .



Open Terminal Protection (OTP)

The VFB, IS, and VIN terminals each have dedicated internal Open Terminal Protection functions.

VFB Open Protection The VFB terminal is internally connected with a pull-up current source. In the event that the VFB terminal is open, VFB terminal voltage is pulled-up to the internal supply voltage, the IC overvoltage protection is activated, and both OUT1 and OUT2 are set low, decreasing the output voltage. **IS Open Protection** The IS terminal is internally connected with a pull-up current source. In the event that the IS terminal is open, the IS terminal voltage is pulled-up to the internal supply voltage, the IC overcurrent protection is activated, and both OUT1 and OUT2 are set low, decreasing the output voltage.

VIN Open Protection The VIN terminal is internally connected with a pull-up current source. In the event that the VIN terminal is open, the VIN terminal voltage is pulled-up to the internal supply voltage, and the control circuit limits IC operation or stops it.



Figure 18. External VFB terminal circuit



Figure 19. Typical application diagram

Package Outline Drawing



Power Factor Correction Discontinuous Conduction Mode Controller

Because reliability can be affected adversely by improper storage environments and handling methods, please observe the following cautions.

Cautions for Storage

- Ensure that storage conditions comply with the standard temperature (5°C to 35°C) and the standard relative humidity (around 40% to 75%); avoid storage locations that experience extreme changes in temperature or humidity.
- Avoid locations where dust or harmful gases are present and avoid direct sunlight.
- Reinspect for rust on leads and solderability of the products that have been stored for a long time.

Cautions for Testing and Handling

When tests are carried out during inspection testing and other standard test periods, protect the products from power surges from the testing device, shorts between the product pins, and wrong connections. Ensure all test parameters are within the ratings specified by Sanken for the products.

Soldering

 When soldering the products, please be sure to minimize the working time, within the following limits:
SOP8

, 2015

Reflow soldering: 180°C 90±30 s for preheating 250°C 10±1 s (260°C peak, 2 times) for solder heating

Soldering iron:

380±10°C 3.5±0.5 s (1 time) Note: Flow soldering must not be used.

Electrostatic Discharge

- When handling the products, the operator must be grounded. Grounded wrist straps worn should have at least 1 M Ω of resistance from the operator to ground to prevent shock hazard, and it should be placed near the operator.
- Workbenches where the products are handled should be grounded and be provided with conductive table and floor mats.
- When using measuring equipment such as a curve tracer, the equipment should be grounded.
- When soldering the products, the head of soldering irons or the solder bath must be grounded in order to prevent leak voltages generated by them from being applied to the products.
- The products should always be stored and transported in Sanken shipping containers or conductive containers, or be wrapped in aluminum foil.

- The contents in this document are subject to changes, for improvement and other purposes, without notice. Make sure that this is the latest revision of the document before use.
- Application and operation examples described in this document are quoted for the sole purpose of reference for the use of the products herein and Sanken can assume no responsibility for any infringement of industrial property rights, intellectual property rights or any other rights of Sanken or any third party which may result from its use.
- Although Sanken undertakes to enhance the quality and reliability of its products, the occurrence of failure and defect of semiconductor products at a certain rate is inevitable. Users of Sanken products are requested to take, at their own risk, preventative measures including safety design of the equipment or systems against any possible injury, death, fires or damages to the society due to device failure or malfunction.
- Sanken products listed in this document are designed and intended for the use as components in general purpose electronic equipment or apparatus (home appliances, office equipment, telecommunication equipment, measuring equipment, etc.).

When considering the use of Sanken products in the applications where higher reliability is required (transportation equipment and its control systems, traffic signal control systems or equipment, fire/crime alarm systems, various safety devices, etc.), and whenever long life expectancy is required even in general purpose electronic equipment or apparatus, please contact your nearest Sanken sales representative to discuss, prior to the use of the products herein.

The use of Sanken products without the written consent of Sanken in the applications where extremely high reliability is required (aerospace equipment, nuclear power control systems, life support systems, etc.) is strictly prohibited.

• In the case that you use Sanken products or design your products by using Sanken products, the reliability largely depends on the degree of derating to be made to the rated values. Derating may be interpreted as a case that an operation range is set by derating the load from each rated value or surge voltage or noise is considered for derating in order to assure or improve the reliability. In general, derating factors include electric stresses such as electric voltage, electric current, electric power etc., environmental stresses such as ambient temperature, humidity etc. and thermal stress caused due to self-heating of semiconductor products. For these stresses, instantaneous values, maximum values and minimum values must be taken into consideration.

In addition, it should be noted that since power devices or IC's including power devices have large self-heating value, the degree of derating of junction temperature affects the reliability significantly.

- When using the products specified herein by either (i) combining other products or materials therewith or (ii) physically, chemically or otherwise processing or treating the products, please duly consider all possible risks that may result from all such uses in advance and proceed therewith at your own responsibility.
- Anti radioactive ray design is not considered for the products listed herein.
- Sanken assumes no responsibility for any troubles, such as dropping products caused during transportation out of Sanken's distribution network.
- The contents in this document must not be transcribed or copied without Sanken's written consent.