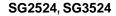


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# SGx524 Regulating Pulse-Width Modulators

Technical

Documents

#### 1 Features

- Complete Pulse-Width Modulation (PWM) Power-Control Circuitry
- Uncommitted Outputs for Single-Ended or Push-Pull Applications
- 8 mA (TYP) Standby Current

# 2 Applications

- Transformer-coupled DC/DC convertors
- Switching-regulators of any polarity

# 3 Description

Tools &

Software

The SG2524 and SG3524 devices incorporate all the functions required in the construction of a regulating power supply, inverter, or switching regulator on a single chip. They also can be used as the control element for high-power-output applications. The SG2524 and SG3524 were designed for switching regulators of either polarity, transformer-coupled dcto-dc converters, transformerless voltage doublers, and polarity-converter applications employing fixedmodulation frequency, pulse-width (PWM) techniques. The complementary output allows either single-ended or push-pull application. Each device includes an on-chip regulator, error amplifier, programmable oscillator, pulse-steering flip-flop, two uncommitted pass transistors, а high-gain comparator, and current-limiting and shutdown circuitry.

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#### Device Information<sup>(1)</sup>

PART NUMBER	PACKAGE (PIN)	BODY SIZE (NOM)				
	SOIC (16)	9.90 mm × 3.91 mm				
SGx524	PDIP (16)	9.90 mm × 6.35 mm				
	NS (16)	10.30 mm × 5.30 mm				
	NS (16)	10.30 mm × 5.30 mm				

(1) For all available packages, see the orderable addendum at the end of the datasheet.

# 4 Pinout Drawing

SG2524 . SG3524	D, I		
N-	1	16	REF OUT
N+	2	15	V <sub>CC</sub>
OSC OUT	3	14	EMIT 2
CURR LIM+	4	13	COL 2
CURR LIM-	5	12	COL 1
RT	6	11	EMIT 1
CT	7	10	SHUTDOWN
GND	8	9	COMP

Product Folder Links: SG2524 SG3524

# **Table of Contents**

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#### **Revision History** 5

Ch	anges from Revision I (February 2003) to Revision J	Page	
•	Added Applications, Device Information table, Pin Functions table, ESD Ratings table, Thermal Information table, Typical Characteristics, Feature Description section, Device Functional Modes, Application and Implementation section, Power Supply Recommendations section, Layout section, Device and Documentation Support section, and		
	Mechanical, Packaging, and Orderable Information section.		
•	Deleted Ordering Information table.	1	

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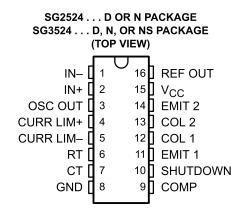
Mechanical, Packaging, and Orderable

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# 6 Pin Configurations and Functions



#### **Pin Functions**

PI	N	TYPE	DESCRIPTION
NAME	NO.	ITPE	DESCRIPTION
COL 1	12	0	Collector terminal of BJT output 1
COL 2	13	0	Collector terminal of BJT output 2
COMP	9	I/O	Error amplifier compensation pin
СТ	7	—	Capacitor terminal used to set oscillator frequency
CURR LIM+	4	I	Positive current limiting amplifier input
CURR LIM-	5	I	Negative current limiting amplifier input
EMIT 1	11	0	Emitter terminal of BJT output 1
EMIT 2 14 O Emitter terminal of BJT output 2			
GND	8	—	Ground
IN+	2	I	Positive error amplifier input
IN-	1	I	Positive error amplifier input
OSC OUT	3	0	Oscillator Output
REF OUT	16	0	Reference regulator output
RT	6	_	Resistor terminal used to set oscillator frequency
SHUTDOWN	10	I	Device shutdown
V <sub>CC</sub>	15	—	Positive supply

# 7 Specifications

#### 7.1 Absolute Maximum Ratings

over operating free-air temperature range (unless otherwise noted)<sup>(1)</sup>

		MIN	MAX	UNIT
$V_{CC}$	Supply voltage <sup>(2)(3)</sup>		40	V
I <sub>CC</sub>	Collector output current		100	mA
I <sub>O(ref)</sub>	Reference output current		50	mA
	Current through CT terminal	-5		mA
TJ	Maximum junction temperature		150	°C
	Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds		260	°C
T <sub>stg</sub>	Storage temperature range	-65	150	°C

(1) Stresses beyond those listed under Absolute Maximum Ratings table may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under Recommended Operating Conditions table are not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to network ground terminal.

(3) The reference regulator may be bypassed for operation from a fixed 5-V supply by connecting the VCC and reference output (REF OUT) pin both to the supply voltage. In this configuration, the maximum supply voltage is 6 V.

# 7.2 ESD Ratings

			VALUE	UNIT
M	Electrostatic discharge	Human body model (HBM), per ANSI/ESDA/JEDEC JS-001, all $pins^{(1)}$	1000	N
V <sub>(ESD)</sub>	Electrostatic discharge	Charged device model (CDM), per JEDEC specification JESD22-C101, all $pins^{(2)}$	1000	v

(1) JEDEC document JEP155 states that 500-V HBM allows safe manufacturing with a standard ESD control process.

(2) JEDEC document JEP157 states that 250-V CDM allows safe manufacturing with a standard ESD control process.

# 7.3 Recommended Operating Conditions

over operating free-air temperature range (unless otherwise noted)

			MIN	MAX	UNIT
V <sub>CC</sub>	Supply Voltage		8	40	V
	Reference output current		0	50	mA
	Current through CT terminal		-0.03	-2	mA
R <sub>T</sub>	Timing resistor		1.8	100	kΩ
CT	Timing capacitor		0.001	0.1	μF
-		SG2524	-25	85	
IA	Operating free-air temperature	SG3524	0	70	°C

#### 7.4 Thermal Information

			SGx524		
	THERMAL METRIC <sup>(1)</sup>	D	N	NS	UNIT
			16 PINS		
$R_{\theta JA}$	Junction-to-ambient thermal resistance <sup>(2)(3)</sup>	73	67	64	°C/W

(1) For more information about traditional and new thermal metrics, see the *IC Package Thermal Metrics* application report, SPRA953.

(2) Maximum power dissipation is a function of  $T_J(max)$ ,  $\theta JA$ , and  $T_A$ . The maximum allowable power dissipation at any allowable ambient temperature is PD =  $(TJ(max) - TA)/\theta JA$ . Operation at the absolute maximum TJ of 150°C can impact reliability.

(3) The package thermal impedance is calculated in accordance with JESD 51-7.

#### 7.5 Electrical Characteristics

over operating free-air temperature range, V<sub>CC</sub> = 20 V, f = 20 kHz (unless otherwise noted)

	DADAMETER	TEST CONDITIONS <sup>(1)</sup>	SG2524			SG3524			
	PARAMETER	TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	MIN	TYP <sup>(2)</sup>	MAX	UNIT
Referen	ce section								
	Output voltage		4.8	5	5.2	4.6	5	5.4	V
	Input Regulation	$V_{CC} = 8 V$ to 40 V		10	20		10	30	mV
	Ripple rejection	f = 120 Hz		66			66		dB
	Output regulation	$I_0 = 0 \text{ mA to } 20 \text{ mA}$		20	50		20	50	mV
	Output voltage change with temperature	$T_A = MIN$ to MAX		0.3%	1%		0.3%	1%	
	Short-circuit output current <sup>(3)</sup>	V <sub>ref</sub> = 0		100			100		mA
Error Ar	nplifier section								
V <sub>IO</sub>	Input offset voltage	V <sub>IC</sub> = 2.5 V		0.5	5		2	10	mV
I <sub>IB</sub>	Input bias current	V <sub>IC</sub> = 2.5 V		2	10		2	10	μA
	Open-loop voltage amplification		72	80		60	80		dB
V <sub>ICR</sub>	Common-monde input voltage range	$T_A = 25^{\circ}C$	1.8 to 3.4			1.8 to 3.4			V
CMMR	Common-mode rejection ratio			70			70		dB
B <sub>1</sub>	Unity-gain bandwidth			3			3		MHz
	Output swing	T <sub>A</sub> = 25°C	0.5		3.8	0.5		3.8	V

For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions. All typical values, except for temperature coefficients, are at  $T_A = 25^{\circ}C$ . Stand<u>ard deviation is a</u> measure of the statistical distribution about the mean, as derived from the formula: (1)

(2) (3)

$$\sigma = \sqrt{\frac{\sum_{n=1}^{N} \left(x_n - \bar{x}\right)^2}{N - 1}}$$

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# 7.6 Electrical Characteristics — Continued, Both Parts

### over operating free-air temperature range, $V_{CC} = 20$ V, f = 20 kHz (unless otherwise noted)

	PARAMETER	TEST CONDITIONS <sup>(1)</sup>	MIN	TYP <sup>(2)</sup>	MAX	UNIT
Oscillator	section	· · · ·				
f <sub>OSC</sub>	Oscillator frequency	$C_{T} = 0.001 \ \mu F, R_{T} = 2 \ k\Omega$		450		kHz
	Standard deviation of frequency <sup>(3)</sup>	All values of voltage, temperature, resistance, and capacitance constant		5		_
	Frequency chance with voltage	$V_{CC} = 8 \text{ V to } 40 \text{ V}, \text{ T}_{A} = 25^{\circ}\text{C}$			1%	
∆f <sub>OSC</sub>	Frequency change with temperature	T <sub>A</sub> = MIN to MAX			2%	_
	Output amplitude at OSC OUT	T <sub>A</sub> = 25°C		3.5		V
t <sub>W</sub>	Output pulse duration (width) at OSC OUT	C <sub>T</sub> = 0.01 μF, TA = 25°C		0.5		μs
Output se	ection					
V <sub>(BR)CE</sub>	Collector-emitter breakdown voltage		40			V
	Collector off-state current	V <sub>CE</sub> = 40 V		0.01	50	μA
V <sub>sat</sub>	Collector-emitter saturation voltage	I <sub>C</sub> = 50 mA		1	2	V
Vo	Emitter output voltage	$V_{C} = 20 \text{ V}, \text{ I}_{E} = -250 \mu\text{A}$	17	18		V
t <sub>r</sub>	Turn-off voltage rise time	$R_{\rm C} = 2 \ \rm k\Omega$		0.2		μs
t <sub>f</sub>	Turn-on voltage fall time	$R_{C} = 2 k\Omega$		0.1		μs
Comparat	or section					
	Maximum duty cycle, each output		45%			
N/	han the shall with me at COMP	Zero duty cycle		1		V
V <sub>IT</sub>	Input threshold voltage at COMP	Maximum duty cycle		3.5		V
I <sub>IB</sub>	Input bias current			-1		μA
Current li	miting section					
VI	Input voltage range		-1		1	V
V <sub>(SENSE)</sub>	Sense voltage at $T_A = 25^{\circ}C$	V V > 50 mV/V − 0.V	175	200	225	mV
	Temperature coefficient of sense voltage	$V_{(IN+)}-V_{(IN-)} \ge 50 \text{ mV } V_{(COMP)} \ge V$		0.2		mV/°C
Total Dev	ice	· · · ·				
I <sub>st</sub>	Standby current	$V_{CC}$ = 40 V, IN–, CURR LIM+, C <sub>T</sub> , GND, COMP, EMIT 1, EMIT 2 grounded, IN+ at 2 V, All other inputs and outputs open		8	10	mA

For conditions shown as MIN or MAX, use the appropriate value specified under recommended operating conditions. (1)

(2) (3)

All typical values, except for temperature coefficients, are at  $T_A = 25^{\circ}C$ . Standard deviation is a measure of the statistical distribution about the mean, as derived from the formula:

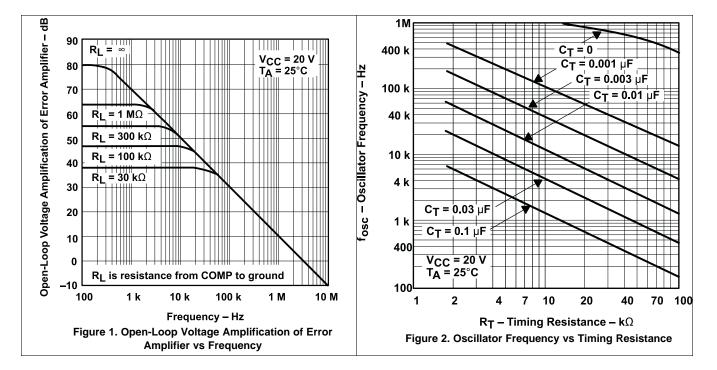
 $\sigma = \sqrt{\frac{\sum_{n=1}^{N} (x_n - \bar{x})^2}{\sum_{n=1}^{N} (x_n - \bar{x})^2}}$ 

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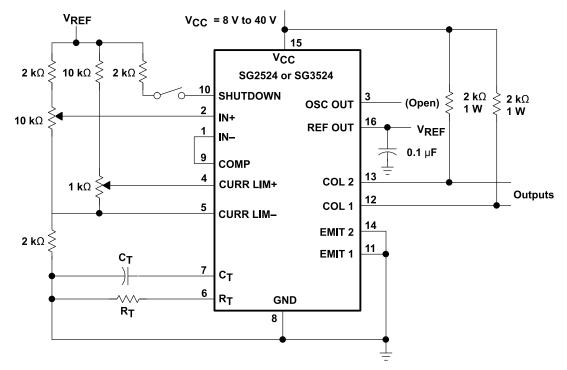
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# 7.7 Typical Characteristics



# 8 Parameter Measurement Information





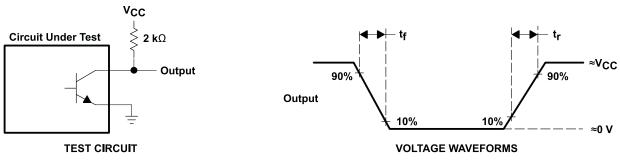


Figure 4. Switching Times

8



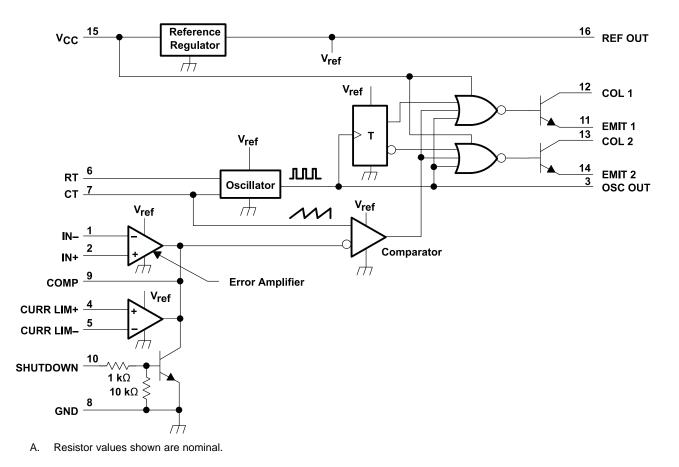
# 9 Detailed Description

SGx524 is a fixed-frequency pulse-width-modulation (PWM) voltage-regulator control circuit. The regulator operates at a fixed frequency that is programmed by one timing resistor,  $R_T$ , and one timing capacitor,  $C_T$ .  $R_T$  establishes a constant charging current for  $C_T$ . This results in a linear voltage ramp at  $C_T$ , which is fed to the comparator, providing linear control of the output pulse duration (width) by the error amplifier.

The SGx524 contains an onboard 5-V regulator that serves as a reference, as well as supplying the SGx524 internal regulator control circuitry. The internal reference voltage is divided externally by a resistor ladder network to provide a reference within the common-mode range of the error amplifier as shown in Figure 11, or an external reference can be used.

The output is sensed by a second resistor divider network and the error signal is amplified. This voltage is then compared to the linear voltage ramp at  $C_T$ . The resulting modulated pulse out of the high-gain comparator then is steered to the appropriate output pass transistor (Q1 or Q2) by the pulse-steering flip-flop, which is synchronously toggled by the oscillator output. The oscillator output pulse also serves as a blanking pulse to ensure both outputs are never on simultaneously during the transition times. The duration of the blanking pulse is controlled by the value of  $C_T$ .

The outputs may be applied in a push-pull configuration in which their frequency is one-half that of the base oscillator, or paralleled for single-ended applications in which the frequency is equal to that of the oscillator. The output of the error amplifier shares a common input to the comparator with the current-limiting and shut-down circuitry and can be overridden by signals from either of these inputs. This common point is pinned out externally via the COMP pin, which can be employed to either control the gain of the error amplifier or to compensate it. In addition, the COMP pin can be used to provide additional control to the regulator.



# 9.2 Functional Block Diagram



#### 9.3 Feature Description

#### 9.3.1 Blanking

The output pulse of the oscillator is used as a blanking pulse at the output. This pulse duration is controlled by the value of  $C_T$  as shown in Figure 2. If small values of  $C_T$  are required, the oscillator output pulse duration can be maintained by applying a shunt capacitance from OSC OUT to ground.

#### 9.3.2 Error Amplifier

The error amplifier is a differential-input transconductance amplifier. The output is available for DC gain control or AC phase compensation. The compensation node (COMP) is a high-impedance node ( $R_L = 5 \text{ M}\Omega$ ). The gain of the amplifier is AV = (0.002  $\Omega$ -1) $R_L$  and easily can be reduced from a nominal 10,000 by an external shunt resistance from COMP to ground. Refer to Figure 1 for data.

#### 9.3.3 Compensation

COMP, as previously discussed, is made available for compensation. Since most output filters introduce one or more additional poles at frequencies below 200 Hz, which is the pole of the uncompensated amplifier, introduction of a zero to cancel one of the output filter poles is desirable. This can be accomplished best with a series RC circuit from COMP to ground in the range of 50 k $\Omega$  and 0.001  $\mu$ F. Other frequencies can be canceled by use of the formula f  $\approx$  1/RC.

#### 9.3.4 Output Circuitry

SGx524 contains two identical npn transistors, the collectors and emitters of which are uncommitted. Each transistor has antisaturation circuitry that limits the current through that transistor to a maximum of 100 mA for fast response.

#### 9.3.5 Current Limiting

A current-limiting sense amplifier is provided in the SGx524 device. The current-limiting sense amplifier exhibits a threshold of 200 mV  $\pm$ 25 mV and must be applied in the ground line since the voltage range of the inputs is limited to 1 V to -1 V. Caution should be taken to ensure the -1-V limit is not exceeded by either input, otherwise, damage to the device may result.

Foldback current limiting can be provided with the network shown in Figure 5. The current-limit schematic is shown in Figure 6.

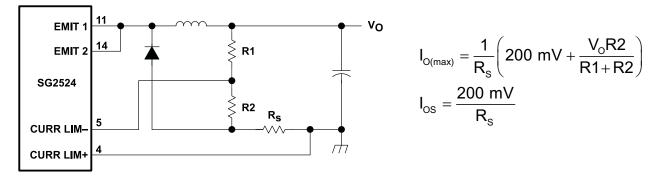


Figure 5. Foldback Current Limiting for Shorted Output Conditions



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#### Feature Description (continued)

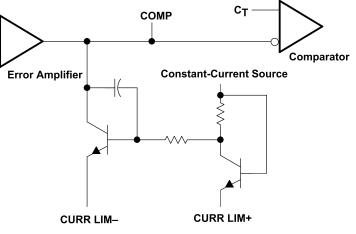


Figure 6. Current-Limit Schematic

#### 9.4 Device Functional Modes

#### 9.4.1 Synchronous Operation

When an external clock is desired, a clock pulse of approximately 3 V can be applied directly to the oscillator output terminal. The impedance to ground at this point is approximately 2 k $\Omega$ . In this configuration, R<sub>T</sub>C<sub>T</sub> must be selected for a clock period slightly greater than that of the external clock.

If two or more SGx524 regulators are operated synchronously, all oscillator output terminals must be tied together. The oscillator programmed for the minimum clock period is the master from which all the other SGx524s operate. In this application, the  $C_TR_T$  values of the slaved regulators must be set for a period approximately 10% longer than that of the master regulator. In addition, CT (master) = 2 C<sub>T</sub> (slave) to ensure that the master output pulse, which occurs first, has a longer pulse duration and, subsequently, resets the slave regulators.

#### 9.4.2 Shutdown Circuitry

COMP also can be employed to introduce external control of the SGx524. Any circuit that can sink 200 µA can pull the compensation terminal to ground and, thus, disable the SGx524.

In addition to constant-current limiting, CURR LIM+ and CURR LIM– also can be used in transformer-coupled circuits to sense primary current and shorten an output pulse should transformer saturation occur. CURR LIM– also can be grounded to convert CURR LIM+ into an additional shutdown terminal.

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#### **10** Application and Implementation

#### NOTE

Information in the following applications sections is not part of the TI component specification, and TI does not warrant its accuracy or completeness. TI's customers are responsible for determining suitability of components for their purposes. Customers should validate and test their design implementation to confirm system functionality.

#### **10.1** Application Information

There are a wide variety of output configurations possible when considering the application of the SG2524 as a voltage-regulator control circuit. They can be segregated into three basic categories:

- Capacitor-diode-coupled voltage multipliers
- Inductor-capacitor-implemented single-ended circuits
- Transformer-coupled circuits

Examples of these categories are shown in Figure 7, Figure 8, and Figure 9, respectively. *Typical Application* demonstrates how to set up the SG2524 for a capacitor-diode output design. The same techniques for setting up the internal circuitry of the IC may also be used for the other two output stage examples shown *Examples of Other Output Stages*.

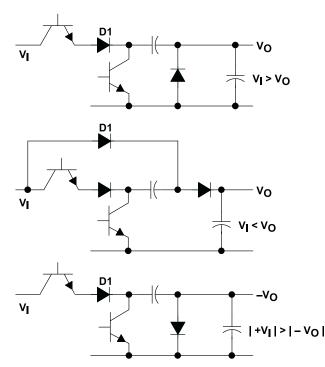


Figure 7. Capacitor-Diode-Coupled Voltage-Multiplier Output Stages



# **Application Information (continued)**

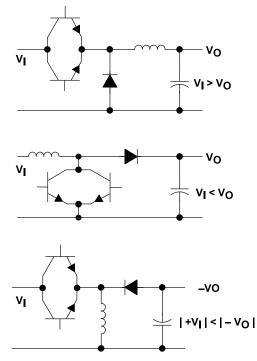


Figure 8. Single-Ended Inductor Circuit

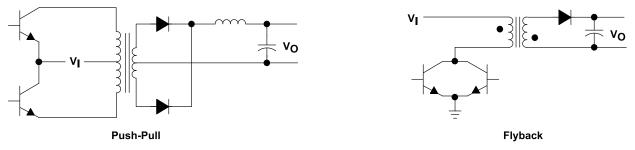


Figure 9. Transformer-Coupled Outputs

SG2524, SG3524

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#### **10.2 Typical Application**

### 10.2.1 Capacitor-Diode Output

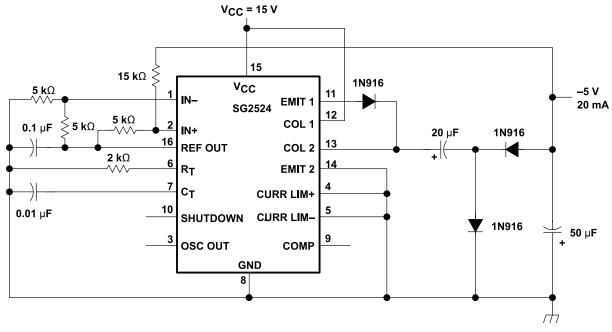


Figure 10. Capacitor-Diode Output Circuit Schematic

#### 10.2.1.1 Design Requirements

- 15-V supply voltage
- –5-V output voltage

# 10.2.1.2 Detailed Design Procedure

#### 10.2.1.2.1 Oscillator

The oscillator controls the frequency of the SG2524 and is programmed by RT and CT as shown in Figure 12.  $f \approx \frac{1.30}{1.30}$ 

<sup>'∼</sup> <del>R</del><sub>⊤</sub>R<sub>c</sub> where

- R<sub>T</sub> is in kΩ
- C<sub>T</sub> is in μF
- fis in kHz

(1)

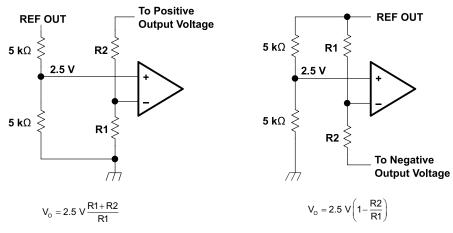
Practical values of CT fall between 0.001  $\mu F$  and 0.1  $\mu F$ . Practical values of RT fall between 1.8 k $\Omega$  and 100 k $\Omega$ . This results in a frequency range typically from 130 Hz to 722 kHz.

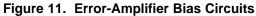
#### 10.2.1.2.2 Voltage Reference

The 5-V internal reference can be employed by use of an external resistor divider network to establish a reference common-mode voltage range (1.8 V to 3.4 V) within the error amplifiers (see Figure 11), or an external reference can be applied directly to the error amplifier. For operation from a fixed 5-V supply, the internal reference can be bypassed by applying the input voltage to both the V<sub>CC</sub> and V<sub>REF</sub> terminals. In this configuration, however, the input voltage is limited to a maximum of 6 V.

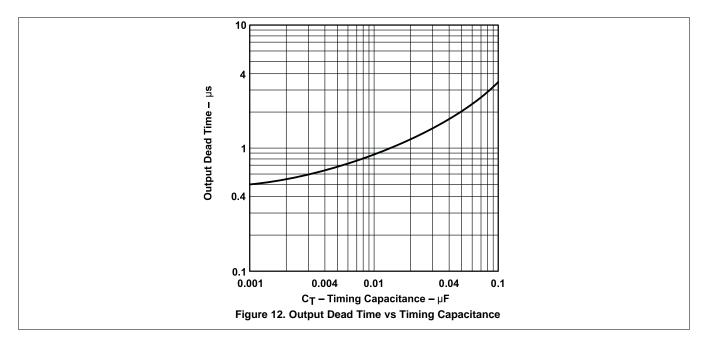


#### **Typical Application (continued)**





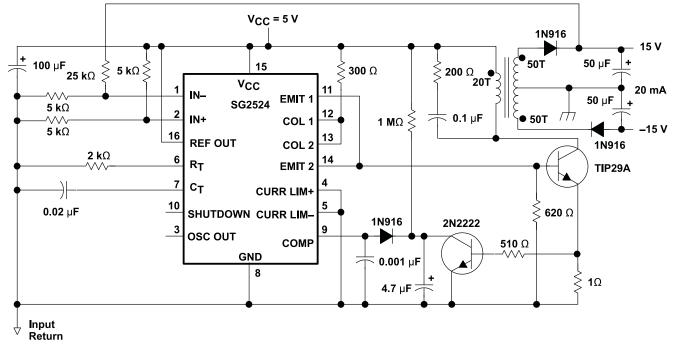
#### 10.2.1.3 Application Curves



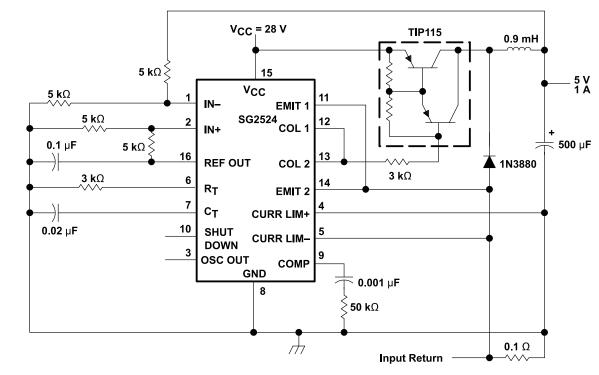


# 10.3 Examples of Other Output Stages

### 10.3.1 Flyback Converter







# 10.3.2 Single-Ended LC





# **Examples of Other Output Stages (continued)**



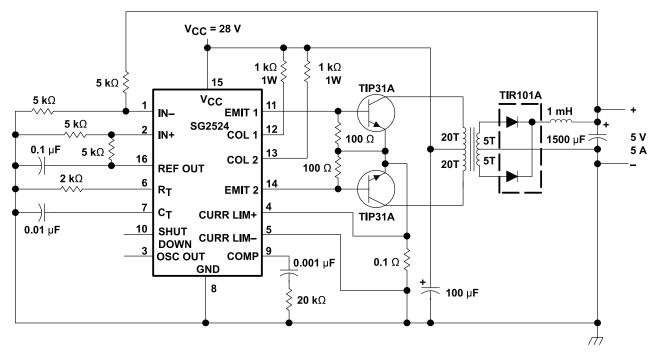


Figure 15. Push-Pull Transformer-Coupled Circuit Schematic



#### **11** Power Supply Recommendations

SGx524 is designed to operate from an input voltage supply range between 8 V and 40 V. This input supply should be well regulated. If the input supply is located more than a few inches from the device, additional bulk capacitance may be required in addition to the ceramic bypass capacitors. A tantalum capacitor with a value of  $47 \ \mu\text{F}$  is a typical choice, however this may vary depending upon the output power being delivered.

# 12 Layout

#### 12.1 Layout Guidelines

Always try to use a low EMI inductor with a ferrite type closed core. Some examples would be toroid and encased E core inductors. Open core can be used if they have low EMI characteristics and are located a bit more away from the low power traces and components. Make the poles perpendicular to the PCB as well if using an open core. Stick cores usually emit the most unwanted noise.

#### 12.1.1 Feedback Traces

Try to run the feedback trace as far from the inductor and noisy power traces as possible. You would also like the feedback trace to be as direct as possible and somewhat thick. These two sometimes involve a trade-off, but keeping it away from inductor EMI and other noise sources is the more critical of the two. Run the feedback trace on the side of the PCB opposite of the inductor with a ground plane separating the two.

#### 12.1.2 Input/Output Capacitors

When using a low value ceramic input filter capacitor, it should be located as close to the VIN pin of the IC as possible. This will eliminate as much trace inductance effects as possible and give the internal IC rail a cleaner voltage supply. Some designs require the use of a feed-forward capacitor connected from the output to the feedback pin as well, usually for stability reasons. In this case it should also be positioned as close to the IC as possible. Using surface mount capacitors also reduces lead length and lessens the chance of noise coupling into the effective antenna created by through-hole components.

#### 12.1.3 Compensation Components

External compensation components for stability should also be placed close to the IC. Surface mount components are recommended here as well for the same reasons discussed for the filter capacitors. These should not be located very close to the inductor either.

#### 12.1.4 Traces and Ground Planes

Make all of the power (high-current) traces as short, direct, and thick as possible. It is good practice on a standard PCB board to make the traces an absolute minimum of 15 mils (0.381 mm) per ampere. The inductor, output capacitors, and output diode should be as close to each other possible. This helps reduce the EMI radiated by the power traces due to the high switching currents through them. This will also reduce lead inductance and resistance as well, which in turn reduces noise spikes, ringing, and resistive losses that produce voltage errors.

The grounds of the IC, input capacitors, output capacitors, and output diode (if applicable) should be connected close together directly to a ground plane. It would also be a good idea to have a ground plane on both sides of the PCB. This will reduce noise as well by reducing ground loop errors as well as by absorbing more of the EMI radiated by the inductor. For multi-layer boards with more than two layers, a ground plane can be used to separate the power plane (where the power traces and components are) and the signal plane (where the feedback and compensation and components are) for improved performance. On multi-layer boards the use of vias will be required to connect traces and different planes. It is good practice to use one standard via per 200 mA of current if the trace will need to conduct a significant amount of current from one plane to the other.

Arrange the components so that the switching current loops curl in the same direction. Due to the way switching regulators operate, there are two power states. One state when the switch is on and one when the switch is off. During each state there will be a current loop made by the power components that are currently conducting. Place the power components so that during each of the two states the current loop is conducting in the same direction. This prevents magnetic field reversal caused by the traces between the two half-cycles and reduces radiated EMI.



# 12.2 Layout Example

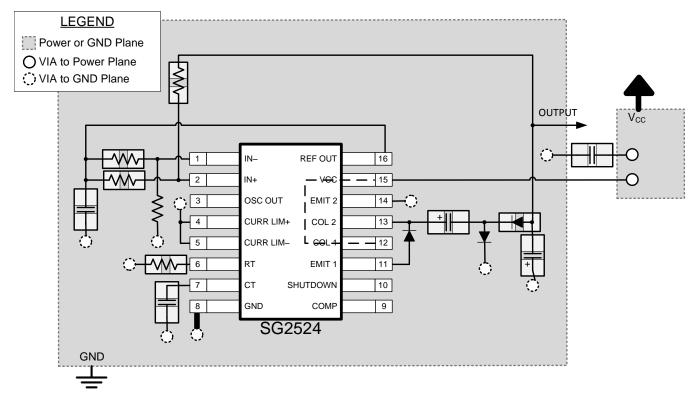


Figure 16. Layout Example for SG2524

# **13 Device and Documentation Support**

# 13.1 Related Links

The table below lists quick access links. Categories include technical documents, support and community resources, tools and software, and quick access to sample or buy.

PARTS	PRODUCT FOLDER	SAMPLE & BUY	TECHNICAL DOCUMENTS	TOOLS & SOFTWARE	SUPPORT & COMMUNITY
SG2524	Click here	Click here	Click here	Click here	Click here
SG3524	Click here	Click here	Click here	Click here	Click here

#### Table 1. Related Links

#### 13.2 Trademarks

All trademarks are the property of their respective owners.

#### 13.3 Electrostatic Discharge Caution



These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# 13.4 Glossary

#### SLYZ022 — TI Glossary.

This glossary lists and explains terms, acronyms, and definitions.

# 14 Mechanical, Packaging, and Orderable Information

The following pages include mechanical, packaging, and orderable information. This information is the most current data available for the designated devices. This data is subject to change without notice and revision of this document. For browser-based versions of this data sheet, refer to the left-hand navigation.



24-Apr-2015

# **PACKAGING INFORMATION**

Orderable Device	Status	Package Type	Package Drawing	Pins	Package Qty	Eco Plan (2)	Lead/Ball Finish	MSL Peak Temp	Op Temp (°C)	Device Marking (4/5)	Samples
SG2524D	ACTIVE	SOIC	D	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-25 to 85	SG2524	Samples
SG2524DR	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-25 to 85	SG2524	Samples
SG2524DRE4	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-25 to 85	SG2524	Samples
SG2524DRG4	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	-25 to 85	SG2524	Samples
SG2524J	OBSOLETE	CDIP	J	16		TBD	Call TI	Call TI	-25 to 85		
SG2524N	ACTIVE	PDIP	N	16	25	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type	-25 to 85	SG2524N	Samples
SG3524D	ACTIVE	SOIC	D	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	Samples
SG3524DE4	ACTIVE	SOIC	D	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	Samples
SG3524DG4	ACTIVE	SOIC	D	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	Samples
SG3524DR	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	Samples
SG3524DRE4	ACTIVE	SOIC	D	16	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	Samples
SG3524J	OBSOLETE	CDIP	J	16		TBD	Call TI	Call TI	0 to 70		
SG3524N	ACTIVE	PDIP	Ν	16	25	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type	0 to 70	SG3524N	Samples
SG3524NE4	ACTIVE	PDIP	N	16	25	Pb-Free (RoHS)	CU NIPDAU	N / A for Pkg Type	0 to 70	SG3524N	Samples
SG3524NS	OBSOLETE	E SO	NS	16		Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	
SG3524NSR	ACTIVE	SO	NS	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM	0 to 70	SG3524	Samples

<sup>(1)</sup> The marketing status values are defined as follows: **ACTIVE:** Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.



24-Apr-2015

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available. **OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. - The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

<sup>(4)</sup> There may be additional marking, which relates to the logo, the lot trace code information, or the environmental category on the device.

<sup>(5)</sup> Multiple Device Markings will be inside parentheses. Only one Device Marking contained in parentheses and separated by a "~" will appear on a device. If a line is indented then it is a continuation of the previous line and the two combined represent the entire Device Marking for that device.

(6) Lead/Ball Finish - Orderable Devices may have multiple material finish options. Finish options are separated by a vertical ruled line. Lead/Ball Finish values may wrap to two lines if the finish value exceeds the maximum column width.

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# PACKAGE MATERIALS INFORMATION

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# TAPE AND REEL INFORMATION





# QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nominal												
Device	Package Type	Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
SG2524DR	SOIC	D	16	2500	330.0	16.4	6.5	10.3	2.1	8.0	16.0	Q1
SG2524DRG4	SOIC	D	16	2500	330.0	16.4	6.5	10.3	2.1	8.0	16.0	Q1
SG3524DR	SOIC	D	16	2500	330.0	16.4	6.5	10.3	2.1	8.0	16.0	Q1
SG3524NSR	SO	NS	16	2000	330.0	16.4	8.2	10.5	2.5	12.0	16.0	Q1

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# PACKAGE MATERIALS INFORMATION

7-Nov-2014



\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
SG2524DR	SOIC	D	16	2500	333.2	345.9	28.6
SG2524DRG4	SOIC	D	16	2500	333.2	345.9	28.6
SG3524DR	SOIC	D	16	2500	333.2	345.9	28.6
SG3524NSR	SO	NS	16	2000	367.0	367.0	38.0

J (R-GDIP-T\*\*) 14 LEADS SHOWN

CERAMIC DUAL IN-LINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- C. This package is hermetically sealed with a ceramic lid using glass frit.
- D. Index point is provided on cap for terminal identification only on press ceramic glass frit seal only.
- E. Falls within MIL STD 1835 GDIP1-T14, GDIP1-T16, GDIP1-T18 and GDIP1-T20.

# N (R-PDIP-T\*\*)

PLASTIC DUAL-IN-LINE PACKAGE

16 PINS SHOWN



NOTES:

- A. All linear dimensions are in inches (millimeters).B. This drawing is subject to change without notice.
- Falls within JEDEC MS-001, except 18 and 20 pin minimum body length (Dim A).
- $\triangle$  The 20 pin end lead shoulder width is a vendor option, either half or full width.



D (R-PDSO-G16)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters).

- B. This drawing is subject to change without notice.
- Body length does not include mold flash, protrusions, or gate burrs. Mold flash, protrusions, or gate burrs shall not exceed 0.006 (0,15) each side.
- Body width does not include interlead flash. Interlead flash shall not exceed 0.017 (0,43) each side.
- E. Reference JEDEC MS-012 variation AC.



4211283-4/E 08/12

# D (R-PDSO-G16) PLASTIC SMALL OUTLINE Stencil Openings (Note D) Example Board Layout (Note C) –16x0,55 -14x1,27 -14x1,27 16x1,50 5,40 5.40 Example Non Soldermask Defined Pad Example Pad Geometry (See Note C) 0,60 .55 Example 1. Solder Mask Opening (See Note E) -0,07 All Around

NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525 for other stencil recommendations.
  E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.



# MECHANICAL DATA

### PLASTIC SMALL-OUTLINE PACKAGE

#### 0,51 0,35 ⊕0,25⊛ 1,27 8 14 0,15 NOM 5,60 8,20 5,00 7,40 $\bigcirc$ Gage Plane ₽ 0,25 7 1 1,05 0,55 0-10 Δ 0,15 0,05 Seating Plane — 2,00 MAX 0,10PINS \*\* 14 16 20 24 DIM 10,50 10,50 12,90 15,30 A MAX A MIN 9,90 9,90 12,30 14,70 4040062/C 03/03

NOTES: A. All linear dimensions are in millimeters.

NS (R-PDSO-G\*\*)

**14-PINS SHOWN** 

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion, not to exceed 0,15.



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